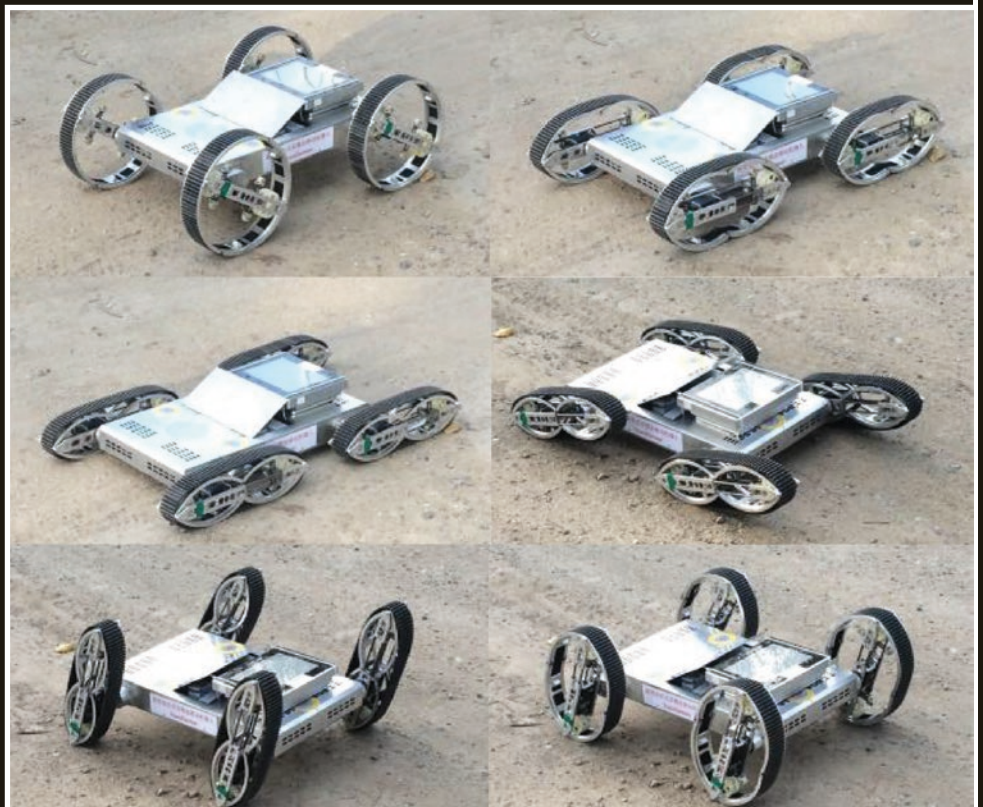


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Cover Image: Implementation of a Reconfigurable Robot to Achieve Multimodal Locomotion Based on Three Rules of Configuration by Faliang Zhou, Xiaojun Xu, Haijun Xu, Yukang Chang, Qi Wang and Jinzhou Chen. Figure 19 'Reconfigurable robot with multimodal locomotion.'