Two General Theorems in the Differential Calculus.

By WILLIAM BRASH.

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1.

Theorem I. Let $_{n}a_{p}$ denote

$$\frac{1}{p!} \Big\{ \delta^{n}(z^{p}) - pz \delta^{n}(z^{p-1}) + \frac{p(p-1)}{1 \cdot 2} z^{2} \delta^{n}(z^{p-2}) - \dots \pm p z^{p-1} \delta^{n}(z) \Big\},\$$

where $\delta \equiv \frac{d}{dx}$. Then for any change in the independent variable x,

say z = f(x), the coefficient of $\frac{d^p}{dz^p}$ in $\frac{d^n}{dx^n}$ is ${}_na_p$.

This theorem is true for all positive integral values of n and p. The expression under the brackets becomes symmetrical on adding the term $z^p \delta^n(z^\circ)$, which is zero, and is left out except in the particular case of n = 0, when it is z^p .

Example: $x = e^{z}$, or $z = \log x$.

By the above theorem

$$\begin{aligned} \frac{d^3}{dx^3} &= \left\{ \frac{d^3}{dx^3} (\log x) \right\} \frac{d}{dz} + \frac{1}{2!} \left\{ \frac{d^3}{dx^3} (\log x)^2 - 2z \frac{d^3}{dx^3} (\log x) \right\} \frac{d^2}{dz^2} + \frac{1}{x^3} \frac{d^3}{dz^3}, \\ &= e^{-3s} \left\{ 2 \frac{d}{dz} - 3 \frac{d^2}{dz^2} + \frac{d^3}{dz^3} \right\}, \\ &= e^{-3s} \left(\frac{d}{dz} - 2 \right) \left(\frac{d}{dz} - 1 \right) \frac{d}{dz}, \end{aligned}$$

agreeing with a result well known in the theory of differential equations.

Proof of Theorem I. by Induction.

We have

$$\delta(_{n}a_{p}) = \frac{1}{p!} \Big[\{ \delta^{n+1}(z^{p}) - pz\delta^{n+1}(z^{p-1}) + \dots \pm pz^{p-1}\delta^{n+1}(z) \} \\ - p\delta(z) \{ \delta^{n}(z^{p-1}) - (p-1)z\delta^{n}(z^{p-2}) + \dots \mp (p-1)z^{p-1}\delta^{n}(z) \} \Big] \\ = {}_{n+1}a_{p} - \delta(z) \cdot {}_{n}a_{p-1}.....(A)$$

Now if

$$\frac{d^{\mathbf{u}}u}{dx^{\mathbf{u}}} = {}_{\mathbf{s}}a_{1}\frac{du}{dz} + \ldots + {}_{\mathbf{s}}a_{p-1}\frac{d^{p-1}u}{dz^{p-1}} + {}_{\mathbf{s}}a_{p}\frac{d^{p}u}{dz^{p}} + \ldots,$$

then

$$\frac{d^{s+1}u}{dx^{s+1}} = \delta(a_1) \cdot \frac{du}{dz} + \dots + \{a_{p-1}, \delta(z) + \delta(a_p)\} \frac{d^p u}{dz^p} + \dots,$$
$$= a_{s+1}a_1\frac{du}{dz} + \dots + a_{s+1}a_p\frac{d^p u}{dz^p} + \dots, \text{ by } (A).$$

Thus if the theorem holds for all positive integral values of p when n = s, it also holds when n = s + 1.

Again, when n = 1, $a_1 = \delta(z)$

.

and

$$(p>1), \ _{1}a_{p} = \frac{1}{p!} \{\delta(z^{p}) - pz\delta(z^{p-1}) + \dots \pm pz^{p-1}\delta(z)\},$$

$$= \frac{z^{p-1}\delta(z)}{(p-1)!} \{1 - (p-1) + \frac{p(p-1)}{1 \cdot 2} - \dots \pm 1\}$$

$$= 0,$$

whence
$$\frac{du}{dx} = \delta(z)\frac{du}{dz}$$
.
So when $n = 2$, $_{2}a_{1} = \delta^{2}(z)$,
 $_{2}a_{2} = \{\delta(z)\}^{2}$,
 $(p > 2)$, $_{2}a_{p} = 0$,
whence $\frac{d^{2}u}{dx^{2}} = \delta^{2}(z) \cdot \frac{du}{dz} + \{\delta(z)\}^{2} \cdot \frac{d^{2}u}{dz^{2}}$

,

Hence the theorem holds for all values of p when n = 1, 2. It follows in the usual way that the theorem holds for all values of p and n.

Cor. When p > n, $a_p = 0$.

Note.—A more rigorous proof of this theorem can be based on a 'p' induction for all values of n. The above proof, however, has the advantage of much greater simplicity.

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In (A) let
$$n = p - 1$$
, then ${}_{n}a_{p} = 0$.
 $\therefore {}_{p}a_{p} = \delta(z) \cdot {}_{p-1}a_{p-1}$
 $= (\delta z)^{2}{}_{p-2}a_{p-2}$
etc.
 $\therefore {}_{p}a_{p} = \{\delta z\}^{p}$(B).

Again, from (A) we have, putting
$$n = p + 1$$
 and using (B),
 $_{p+1}a_p = \delta\{(\delta z)^p\} + \delta(z) \cdot {}_{p}a_{p-1},$
 $= p(\delta z)^{p-1}\delta^2(z) + \delta(z)\{(p-1)(\delta z)^{p-2}\delta^2 z\} + (dz)^{2}\{(p-2)(dz)^{p-3} \cdot \delta^2 z\}$
 $+ \dots + (\delta z)^{p-1}\{\delta^2 z\},$
 $\therefore {}_{p+1}a_p = (\delta z)^{p-1}\delta^2 z\{p + (p-1) + (p-2) + \dots + 1\}.$
 $= \frac{(p+1)p}{2} \cdot (\delta z)^{p-1}\delta^2 z.$

Or
$$_{p}a_{p-1} = \frac{p(p-1)}{2}(\delta z)^{p-2}\delta^{2}z....(C).$$

Similarly

where

$${}_{p}a_{p-2} = \frac{p(p-1)(p-2)(p-3)}{2.4} (\delta^{2}z)^{2} (\delta z)^{p-4} + \frac{p(p-1)(p-2)}{2.3} (\delta z)^{p-3} \delta^{3}(z) \dots \dots (D)$$

 $_{p}a_{p-3}$ is of the form $a(\delta^{2}z)^{3}(\delta z)^{p-6} + \beta(\delta^{2}z)(\delta^{3}z)(\delta z)^{p-5} + \gamma(\delta z)^{p-4}\delta^{4}z$, where a, β, γ involve p and not z.

And a_r is a sum of terms of the form

$$A(\delta z)^{a}(\delta^{s} z)^{\beta}(\delta^{s} z)^{\gamma} \dots , \qquad (E)$$

$$a + 2\beta + 3\gamma + \dots = p,$$

$$d \ r \ hut not z$$

and A involves p and r, but not z.

Now in the transformation of $\frac{d^p}{dx^p}$ by means of the substitution z = f(x), we are dealing with the coefficients ${}_{p}a_{r}$, [r = p, p - 1, ...1].

To find when all these coefficients will be constant multiples of one another. We must have from (B) and (C) the relation

> $(\delta z)^{p} = k(\delta z)^{p-2}\delta^{2}z,$ or $k\delta^{2}z = (\delta z)^{2}....(F).$ $\therefore \quad \delta z = \frac{1}{cx+d}.$ $\therefore \quad z = \log(cx+d).$

By (F) the terms in p^{n_r} all reduce to the form

$$\mathbf{A}(\delta z)^{a}(\delta z)^{2\beta}(\delta z)^{3\gamma}...,$$

i.e. to the form $A(\delta z)^p$,

and (F) therefore denotes a necessary and sufficient condition.

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Hence $z = \log(cx + d)$ alone transforms $\frac{d^p}{dx^p}$ into

$$\phi(x)\left\{a\frac{d^p}{dz^p}+b\frac{d^{p-1}}{dz^{p-1}}+\ldots+k\frac{d}{dz}\right\},$$

where a, b, ...k are constants. $\phi(x)$ has then the value $\frac{k}{(cx+d)^p}$ and we see that $z = \log(cx+d)$ transforms the differential equation $\Sigma(cx+d)^n \frac{d^n y}{dx^n} = 0$ into a linear equation with constant coefficients.

The conditions that z = f(x) transforms

$$\mathbf{X}_{p}\frac{d^{p}y}{dx^{p}} + \mathbf{X}_{p-1}\frac{d^{p-1}y}{dx^{p-1}} + \ldots + \mathbf{X}_{o}y = 0,$$

where $X_{p}...X_{0}$ are functions of x, into an equation with constant coefficients are

$$\begin{split} & X_{p \ p} a_{p} = a, \\ & X_{p \ p} a_{p-1} + X_{p-1 \ p-1} a_{p-1} = \beta, \\ & X_{p \ p} a_{p-2} + X_{p-1 \ p-1} a_{p-2} + X_{p-2 \ p-2} a_{p-2} = \gamma, \\ & \text{etc.} \end{split}$$

Thus if $X_p = x^p$, these conditions give $X_{p-1} = ax^{p-1}$, $X_{p-2} = bx^{p-2}$, etc. This is the case above discussed.

If
$$X_p = \frac{1}{\cos^2 x}$$
 and $a = 1$, $\therefore \quad z = \sin x$,
 $\therefore \quad X_{p-1} = \frac{a}{\cos x} + \frac{\sin x}{\cos^2 x}$

Thus the equations

$$y'' + (a\cos x + \tan x)y' + \cos^2 x \cdot y = 0,$$

 $y'' + \tan x \cdot y' + \cot^2 x \cdot y = 0,$

are both reducible by the substitution $z = \sin x$.

3.

Theorem II. For a general transformation of the form

 $z=f(x), y=u \cdot \phi(x),$

the coefficient of $\frac{d^n u}{dz^n}$ in $\frac{d^n y}{dx^n}$ is

$$\frac{1}{r!} \bigg[\delta^{n} \{ \phi(x).z^{r} \} - rz. \delta^{n} \{ \phi(x).z^{r-1} \} + \frac{r(r-1)}{1.2} z^{3} \delta^{n} \{ \phi(x).z^{r-2} \} - \dots z^{r} \delta^{n} \{ \phi(x) \}$$

In particular the coefficient of u in $\frac{d^n y}{dx^n}$ is $\delta^n \{\phi(x)\}$,

and the coefficient of
$$\frac{d^n u}{dz^n}$$
 in $\frac{d^n y}{dx^n}$ is $\phi(x) (\delta z)^n$.
Example: $x = e^z$, $y = ue^{2z} = ux^2$.

By the theorem, the coefficient of

$$\frac{d^2 u}{dz^2} \text{ in } \frac{d^3 y}{dx^3} = \frac{1}{2} \left[\delta^3 \left\{ x^2 (\log x)^2 \right\} - 2 \log x \delta^3 \left\{ x^2 \log x \right\} \right],$$
$$= \frac{1}{2} \left[\frac{6}{x} + 4 \frac{\log x}{x} - \frac{4 \log x}{x} \right],$$
$$= 3/x = 3e^{-x},$$

the coefficient of

$$\frac{d^3u}{dz^3} \quad \text{in} \quad \frac{d^3y}{dx^3} = x^2 \left(\frac{dz}{dx}\right)^3 = x^2 e^{-3z} = e^{-z},$$

and the coefficient of u in $\frac{d^3y}{dx^3} = 0$.

These results agree with the formula used in differential equations, viz.,

$$\begin{aligned} \frac{d^3y}{dx^3} &= e^{-s} \frac{d}{dz} \left(\frac{d}{dz} + 1 \right) \left(\frac{d}{dz} + 2 \right) u, \\ &= e^{-s} \left\{ \frac{d^3u}{dz^3} + 3 \frac{d^2u}{dz^3} + 2 \frac{du}{dz} \right\}. \end{aligned}$$

Theorem II. follows at once from Theorem I., and the Theorem of Leibniz, for if $y = u \cdot \phi(x)$,

$$\frac{d^n y}{dx^n} = \phi \cdot \frac{d^n u}{dx^n} + {}_n c_1 \delta \phi \cdot \frac{d^{n-1} u}{dx^{n-1}} + \ldots + u \delta^n \phi,$$

and the coefficient of $\frac{d^r u}{dz^r}$ on the right

$$= \phi_n a_r + {}_n c_1 \delta \phi \cdot {}_{n-1} a_r + \dots + \delta^n \phi \cdot {}_0 a_r,$$

$$= \frac{1}{r!} [\{ \phi \delta^n(z^r) + {}_n c_1 \delta \phi \cdot \delta^{n-1}(z^r) + \dots + \delta^n \phi \cdot z^r \} - \text{etc.}],$$

$$= \frac{1}{r!} [\delta^n \{ \phi \cdot z^r \} - rz \delta^n \{ \phi \cdot z^{r-1} \} + \frac{r(r-1)}{1 \cdot 2} z^2 \delta^n \{ \phi \cdot z^{r-2} \}$$

$$- \dots \mp rz^{r-1} \delta^n \{ \phi \cdot z \} \pm z^r \delta^n \phi].$$

Also, since ${}_{p}a_{p} = (\delta z)^{p}$, it follows that the coefficient of

$$\frac{d^n u}{dz^n} \text{ in } \frac{d^n y}{dx^n} \text{ is } \phi(x) \left(\frac{dz}{dx}\right)^n,$$

and the coefficient of u is clearly $\delta^n{\phi(x)}$. Hence Theorem II. is proved.

4.

Theorem: By the substitution z = (ax + b)/(cx + d), $y = u(cx + d)^{n-1}$ $\frac{d^n y}{dx^n}$ is transformed into $\frac{p^n}{(cx + d)^{n+1}} \frac{d^n u}{dz^n}$, where p = ad - bc.

This Theorem follows from Theorem II. Thus, using the substitution z = f(x), $y = u \cdot \phi(x)$,

$$\frac{d^n y}{dx^n} \operatorname{becomes} \sum_{r=0}^{r=n} \frac{1}{r!} \bigg[\delta^n \{ \phi(x) \cdot z^r \} - rz \delta^n \{ \phi(x) \cdot z^{r-1} \} + \ldots \pm z^r \delta^n \{ \phi(x) \} \bigg] \frac{d^r u}{dz^r},$$

The sufficient conditions that all the differential coefficients up to the $(n-1)^{\text{th}}$, as well as the term in u, may vanish, are

$$\delta^{n} \{ \phi(x) \} = 0 \dots (i),$$

$$\delta^{n} \{ \phi(x) \cdot z \} = 0 \dots (ii),$$

$$\delta^{n} \{ \phi(x) \cdot z^{2} \} = 0 \dots (iii),$$

$$\delta^{n} \{ \phi(x) \cdot z^{n-1} \} = 0 \dots (n).$$

(i) gives $\phi(x) = a_{0} + a_{1}x + \dots + a_{n-1}x^{n-1}.$
(n) then gives $z^{n-1} = \frac{A_{0} + A_{1}x + \dots + A_{n-1}x^{n-1}}{a_{0} + a_{1}x + \dots + a_{n-1}x^{n-1}},$

and from (i) it follows that z = (ax + b)/(cx + d).

Hence also $\phi(x) = (cx+d)^{n-1}$, and the theorem follows at once. Thus if we take the equation

 $(ax^2 + \beta x + \gamma)^n y^{(n)} = ky$ where $ax^2 + \beta x + \gamma = (ax + b)(cx + d)$ and apply the substitution z = (ax + b)/(cx + d), $y = u(cx + d)^{n-1}$, it becomes $(ax + b)^n (cx + d)^n \frac{p^n}{(cx + d)^{n+1}} \frac{d^n u}{dz^n} = ku(cx + d)^{n-1}$,

i.e.
$$\left(\frac{ax+b}{cx+d}\right)^n \frac{d^n u}{dz^n} = k' u,$$

or

$$z^n \frac{du}{dz^n} = k'u,$$

which has the solution
$$u = \sum_{m=m_1}^{n} A_m z^m$$

where m_1, \ldots, m_n are the roots of the equation

where m_1, \ldots, m_n are the roots of the equation $m(m-1)\ldots(m-n+1)-k'=0.$

5.

Generally speaking, it is only when we are dealing with linear equations that the discovery of a particular integral helps us to the complete solution. Thus for the equation

$$9xy^2y''+2=0,$$

it is easy to find the particular integral $y = x^{1/3}$, but since the equation is not linear, this does not lead to a complete solution. If we apply the transformation z = 1/x, y = ux, which is a particular case of the transformation of §4, p = 1, and the equation reduces to

$$u^2u'' + 2/9 = 0.$$

The complete solution

$$\int \frac{du}{(1/u+c_1)^{1/2}} = 2/3(z+c_2) = 2/3(1/x+c_2)$$

is now easily obtained.

In this example we reduced the equation to a known form. We shall consider from this point of view the general equation

Putting z = f(x), and $y = u \cdot \phi(x)$, (1) becomes

$$\frac{d^2u}{dz^2} + \mathbf{P}\frac{du}{dz} + \mathbf{Q} = 0,$$

where
$$\mathbf{P} = \frac{\delta^2 \{z \cdot \phi\} - z \delta^2 \phi}{\phi \cdot (\delta z)^2} = \frac{2 \delta z \cdot \delta \phi + \phi \cdot \delta^2 z}{\phi \cdot (\delta z)^2}$$

and $Q = \frac{u\delta^2\phi + \psi(xy)}{\phi \cdot (\delta z)^2}.$

$$\frac{d\mathbf{Q}}{dz} = \frac{\phi \cdot \delta z \cdot u \cdot \delta^3 \phi + \phi \cdot \delta z \cdot \psi_x + \phi \cdot \delta z \cdot \psi_y \cdot u \delta \phi - (u \delta^2 \phi + \psi) \left(\delta \phi \cdot \delta z + 2\phi \cdot \delta^2 z\right)}{\phi^2 (\delta z)^4}$$
$$\frac{d\mathbf{P}}{dz} = \frac{2\phi \cdot (\delta z)^2 \cdot \delta^2 \phi - 2\phi \cdot \delta z \cdot \delta^3 z \cdot \delta \phi + \phi^2 \delta z \cdot \delta^3 z - 2(\delta z)^2 (\delta \phi)^2 - 2\phi^2 (\delta^2 z)^2}{\phi^2 (\delta z)^4}.$$

Hence P and Q are independent of z if

$$\phi \cdot \delta z \cdot u \delta^3 \phi + \phi \delta z \psi_x + \phi \delta z \psi_y u \delta \phi - (u \delta^2 \phi + \psi) (\delta \phi \cdot \delta z + 2\phi \cdot \delta^2 z) = 0, \quad (\mathbf{A})$$

and
$$2\phi(\delta z)^2\delta^2\phi - 2\phi\delta z\delta^2 z\delta\phi + \phi^2\delta z\delta^3 z - 2(\delta z)^2(\delta\phi)^2 - 2\phi^2(\delta^2 z)^2 = 0.$$
 (B)

We have a particular solution of (B) when P = 0, $\phi \delta^2 z + 2\delta \phi \cdot \delta z = 0 \quad (a)$ i.e. when

or
$$\delta z = a/\phi^2$$
 (β).
Using (a) in (A) it reduces to

$$\delta z \cdot \{\phi \cdot \psi_x + u\phi \cdot \delta\phi \cdot \psi_y + 3\delta\phi \cdot \psi + u(\phi\delta^3\phi + 3\delta^2\phi \cdot \delta\phi)\} = 0.$$

or $\phi\psi_x + y\delta\phi \cdot \psi_y + 3\delta\phi \cdot \psi + y\delta^3\phi + \frac{3y\delta^2\phi \cdot \delta\phi}{\phi} = 0$ [$\delta z \neq 0$], (C).

The Lagrangian Subsidiary System is

$$\frac{dx}{\phi} = \frac{dy}{y \cdot \phi'} = \frac{d\psi}{-3\phi'\psi - y\phi''' - \frac{3y\phi''\phi'}{\phi}}$$
$$\frac{dx}{\phi} = \frac{dy}{y\phi'} \text{ gives } \frac{d\phi}{\phi} = \frac{dy}{y}.$$
$$\therefore \quad y/\phi = a(\text{const.}).$$

Using this in the last equation, we have

$$\frac{d\psi}{d\phi} + \frac{3}{\phi} \cdot \psi + a \frac{\phi''}{\phi'} + 3a \frac{\phi''}{\phi} = 0,$$

i.e.
$$\frac{d}{d\phi} \{ \phi^3(\psi + a\phi'') \} = 0.$$
$$\phi^3(\psi + a\phi'') = b$$

Hence

or

$$\phi^{s}\left(\psi+y\frac{\phi''}{\phi}\right)=b \text{ (const.).}$$

Hence the general solution of (C) may be written

$$\psi = \frac{1}{\phi^3} \chi(y/\phi) - y/\phi \cdot \phi'' \quad [\chi \text{ arbitrary}],$$
$$= \frac{1}{\gamma} \chi(y/\phi) - y/\phi \cdot \phi''.$$

or

 $= \frac{-}{y^3} \chi(y/\phi) - y/\phi \cdot \phi .$ Hence $\frac{d^2y}{dx^2} + \frac{1}{y^3} \chi(y/\phi) - y/\phi \cdot \phi'' = 0$ can be reduced to

 $\frac{d^2u}{dz^2} + Q = 0$, where Q does not contain z, by means of the substitution

$$y = u\phi, \ z = \int \frac{1}{\phi^2} dx.$$

Special cases :

1°
$$\phi'' = 0, \therefore \phi = ax + b$$
 and $\psi = \frac{1}{y^s} \chi\left(\frac{y}{ax+b}\right)$, and from $(\beta), z = \frac{cx+d}{ax+b}$.
Hence substitution $y = u(ax+b), z = \frac{cx+d}{ax+b}$ will reduce the equation

equation

6.

The substitution z = (ax + b)/(cx + d), $y = u(cx + d)^{n-1}$ will reduce the more general equation $\frac{d^n y}{dx^n} + \psi(xy) = 0$ to a known form if

$$\psi = \frac{1}{(cx+d)^{n-1}} \chi \left(\frac{1}{(cx+d)^{n-1}} \right), \quad \chi \text{ arbitrary.}$$

7.

The equation $\frac{d^2y}{dx^2} + \frac{1}{y^3}\chi(y/x) = 0$ (1) is homogeneous in the sense that all the terms are of the same order when y and x are considered of order 1, and y" of order -3. In certain cases it is also homogeneous when y is considered of order n, y' of order n-1, etc., and x of order 1, when it will be reducible to an equation of the 1st order by the substitution $x = e^t$, $y = ux^*$ (2).

Therefore, corresponding to the cases where (1) is homogeneous in both senses, we have a soluble class of equations of the 1st order.

(1) is homogeneous in the 2nd sense when and only when 4n-2=a(n-1) (3), and the equation is $y^3y'' = A(y/x)^a$.

Using (2) and putting $p = \frac{du}{dz}$, this equation becomes

$$p\frac{dp}{du} + (2n-1)p + n(n-1)u - \frac{A}{u^{3-a}} = 0.$$

Hence $p\frac{dp}{du} + (2n-1)p + n(n-1)u + Au^{\frac{n+1}{n-1}} = 0$

is a soluble class of equations.

Examples :

1°

$$yrac{d^2y}{dx^2} - y^2 = \sec^2 x ext{ can be put in the form}$$

 $rac{d^2y}{dx^2} = rac{1}{\cos^3 x} \cdot \left(rac{\cos x}{y}
ight) + y,$

which is of the form of §5 when $\phi'' = -\phi$, *i.e.* $\phi = \cos x$.

Therefore substitution $z = \tan x$, $y = u \cos x$ reduces this equation. So for $yy'' + y^2 = \operatorname{sech}^2 x$.

2°

$$z = \frac{1}{x^{3}}, y = ux^{2} \text{ reduces}$$

$$y'' = 2y\left(\frac{1}{x^{5}} - \frac{1}{x^{2}}\right).$$
3°

$$p\frac{dp}{du} + 3p + 2u + u^{3} = 0.$$

$$p\frac{dp}{du} - 3p + 2u + 1 = 0$$

$$p\frac{dp}{du} - p + \frac{1}{u} = 0$$

are of soluble type of §7.

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