

MULTIPLE SOLUTIONS FOR A QUASILINEAR ELLIPTIC VARIATIONAL SYSTEM ON STRIP-LIKE DOMAINS

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Abstract We consider the quasilinear elliptic variational system

$$\begin{aligned} -\Delta_p u &= \lambda F_u(x, u, v) + \mu H_u(x, u, v) && \text{in } \Omega, \\ -\Delta_q v &= \lambda F_v(x, u, v) + \mu H_v(x, u, v) && \text{in } \Omega, \\ u = v &= 0 && \text{on } \partial\Omega, \end{aligned}$$

where Ω is a strip-like domain and λ and μ are positive parameters. Using a recent two-local-minima theorem and the principle of symmetric criticality, existence and multiplicity are proved under suitable conditions on F .

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1. Introduction

Very recently, in [1] Kristály studied the eigenvalue problem

$$\left. \begin{aligned} -\Delta_p u &= \lambda F_u(x, u, v) && \text{in } \Omega, \\ -\Delta_q v &= \lambda F_v(x, u, v) && \text{in } \Omega, \\ u = v &= 0 && \text{on } \partial\Omega, \end{aligned} \right\} \quad (S_\lambda)$$

where $\lambda > 0$ is a parameter and Ω is a strip-like domain in \mathbb{R}^N , i.e. $\Omega = \omega \times \mathbb{R}^l$, ω being a bounded open subset of \mathbb{R}^m with smooth boundary, $m \geq 1$, $l \geq 2$, $1 < p, q < N = m + l$, $F \in C^0(\Omega \times \mathbb{R}^2, \mathbb{R})$, and $\Delta_\alpha w = \operatorname{div}(|\nabla w|^{\alpha-2} \nabla w)$. Here, F_z denotes the partial derivative of F with respect to variable z . He applies a critical point result (see [5]) in order to obtain the existence of an open interval $A \subset (0, +\infty)$ such that, for every $\lambda \in A$, the system S_λ

* Because of a surprising coincidence of names within our department, we have to point out that the author was born on 4 August 1968.

has at least two distinct non-trivial solutions. Also, he assumes that the nonlinear term F is sub- p, q -linear; that is,

$$(1_F) \quad \lim_{u,v \rightarrow 0} \frac{F_u(x, u, v)}{|u|^{p-1}} = \lim_{u,v \rightarrow 0} \frac{F_v(x, u, v)}{|v|^{q-1}} = 0, \text{ uniformly w.r.t. } x \in \Omega.$$

Inspired by [1], we prove two multiplicity theorems, which extend the results contained in [1], for the system

$$\left. \begin{aligned} -\Delta_p u &= \lambda F_u(x, u, v) + \mu H_u(x, u, v) && \text{in } \Omega, \\ -\Delta_q v &= \lambda F_v(x, u, v) + \mu H_v(x, u, v) && \text{in } \Omega, \\ u = v &= 0 && \text{on } \partial\Omega, \end{aligned} \right\} (S_{\lambda, \mu})$$

where μ is a positive parameter. Our approach is based on a recent result of Ricceri [6, Theorem 4]; in a convenient form for our purposes it can be read as follows.

Theorem 1.1 (Ricceri). *Let X be a reflexive real Banach space, let $I \subseteq \mathbb{R}$ be an interval, and let $\Psi : X \times I \rightarrow \mathbb{R}$ be a function such that $\Psi(x, \cdot)$ is concave in I for all $x \in X$, while $\Psi(\cdot, \lambda)$ is continuous, coercive and sequentially weakly lower semicontinuous in X for all $\lambda \in I$. Further, assume that*

$$\sup_{\lambda \in I} \inf_{x \in X} \Psi(x, \lambda) < \inf_{x \in X} \sup_{\lambda \in I} \Psi(x, \lambda).$$

Then, for each $\rho > \sup_I \inf_X \Psi(x, \lambda)$ there exists a non-empty open set $A \subseteq I$ with the following property: for every $\lambda \in A$ and every sequentially weakly lower semicontinuous functional $\Phi : X \rightarrow \mathbb{R}$, there exists $\delta > 0$ such that, for each $\mu \in]0, \delta[$, the functional $\Psi(\cdot, \lambda) + \mu\Phi(\cdot)$ has at least two local minima lying in the set $\{x \in X : \Psi(x, \lambda) < \rho\}$.

In the present paper, the function F is assumed to be a $C^0(\Omega \times \mathbb{R}^2, \mathbb{R})$ function such that

(2_F) F is axially symmetric in the first variable; that is,

$$F((x_1, x_2), s, t) = F((x_1, gx_2), s, t) \quad \text{for all } x_1 \in \omega, x_2 \in \mathbb{R}^l, g \in O(l), (s, t) \in \mathbb{R}^2;$$

(3_F) $(s, t) \rightarrow F(x, s, t)$ is of class C^1 and $F(x, 0, 0) = 0$ for all $x \in \Omega$.

Moreover, let $\alpha^* = N\alpha/(N - \alpha)$, $\alpha \in \{p, q\}$, be the critical Sobolev exponent and we assume that

(4_F) there exist $\varepsilon > 0$, and $r \in]p, p^*[$, $s \in]q, q^*[$, with $ps = qr$, such that

$$\begin{aligned} |F_u(x, u, v)| &\leq \varepsilon(|u|^{p-1} + |v|^{(p-1)q/p} + |u|^{r-1}), \\ |F_v(x, u, v)| &\leq \varepsilon(|v|^{q-1} + |u|^{(q-1)p/q} + |v|^{s-1}) \end{aligned}$$

for each $x \in \Omega$ and $(u, v) \in \mathbb{R}^2$.

Throughout this paper, the norm on $W_0^{1,\alpha}(\Omega)$ is defined by

$$\|u\|_\alpha = \left(\int_\Omega |\nabla u|^\alpha \right)^{1/\alpha}, \quad \alpha \in \{p, q\}.$$

As Kristály points out in [1], since Ω is unbounded, the loss of compactness of the Sobolev embedding $W_0^{1,\alpha}(\Omega) \hookrightarrow L^\beta(\Omega)$, $\beta \in [\alpha, \alpha^*]$, $\alpha \in \{p, q\}$, makes standard variational techniques more delicate. For this reason, we consider the subgroup G of $O(l)$ defined by $G = \text{id}^m \times O(l)$. The action of G on $W_0^{1,\alpha}(\Omega)$ is defined by

$$gu(x_1, x_2) = u(x_1, g_1^{-1}x_2)$$

for each $(x_1, x_2) \in \omega \times \mathbb{R}^l$, $g = \text{id}^m \times g_1 \in G$ and $u \in W_0^{1,\alpha}(\Omega)$. Let

$$W_{0,G}^{1,\alpha}(\Omega) = \text{Fix } W_0^{1,\alpha}(\Omega) = \{u \in W_0^{1,\alpha}(\Omega) : gu = u, \forall g \in G\}.$$

Hence, the elements of $W_{0,G}^{1,\alpha}(\Omega)$ are the axially symmetric functions of $W_0^{1,\alpha}(\Omega)$.

Obviously, the action G on $W_{0,G}^{1,\alpha}(\Omega)$ is isometric, that is

$$\|gu\|_\alpha = \|u\|_\alpha, \quad \text{for all } g \in G.$$

Since $l \geq 2$, the embedding $W_{0,G}^{1,\alpha}(\Omega) \hookrightarrow L^\beta(\Omega)$, $\alpha < \beta < \alpha^*$, $\alpha \in \{p, q\}$, is compact [2]. In the space $W_0^{1,p}(\Omega) \times W_0^{1,q}(\Omega)$, endowed with the norm

$$\|(u, v)\|_{p,q} = \|u\|_p + \|v\|_q,$$

one has

$$\begin{aligned} \text{Fix}_G(W_0^{1,p}(\Omega) \times W_0^{1,q}(\Omega)) &= \{(u, v) \in W_0^{1,p}(\Omega) \times W_0^{1,q}(\Omega) : g(u, v) = (u, v), \forall g \in G\} \\ &= W_{0,G}^{1,p}(\Omega) \times W_{0,G}^{1,q}(\Omega). \end{aligned}$$

2. Main result

Our main result is the following.

Theorem 2.1. *Let $F : \Omega \times \mathbb{R}^2 \rightarrow \mathbb{R}$ be a continuous function that satisfies conditions (1_F) – (4_F) . Furthermore, assume that*

$$(5) \quad \limsup_{|(\xi, \eta)| \rightarrow +\infty} \frac{F(x, \xi, \eta)}{|\xi|^p + |\eta|^q} \leq 0 \text{ uniformly for every } x \in \Omega;$$

$$(6) \quad \text{there exists } (u_0, v_0) \in W_{0,G}^{1,p}(\Omega) \times W_{0,G}^{1,q}(\Omega) \text{ such that}$$

$$\int_\Omega F(x, u_0(x), v_0(x)) \, dx > 0.$$

Then there exist a number σ and a non-degenerate compact interval $C \subseteq [0, +\infty[$ such that, for every continuous function $H : \Omega \times \mathbb{R}^2 \rightarrow \mathbb{R}$ satisfying conditions (1_H) – (4_H) and for every $\lambda \in C$, there exists $\delta > 0$ such that, for each $\mu \in]0, \delta[$, the problem $(S_{\lambda, \mu})$ has at least two solutions, denoted by $(u_{\lambda, \mu}^i, v_{\lambda, \mu}^i)$, $i \in \{1, 2\}$, with $u_{\lambda, \mu}^i$ and $v_{\lambda, \mu}^i$ axially symmetric and with norms less than σ .

Proof. Let $X = W_{0,G}^{1,p}(\Omega) \times W_{0,G}^{1,q}(\Omega)$. We define two functionals Φ and \mathcal{F} by setting, for each $(u, v) \in X$,

$$\begin{aligned}\Phi(u, v) &= \frac{1}{p}\|u\|_p^p + \frac{1}{q}\|v\|_q^q, \\ \mathcal{F}(u, v) &= - \int_{\Omega} F(x, u(x), v(x)) \, dx.\end{aligned}$$

In view of (3_F) and (4_F), and using the Sobolev embeddings, we can prove that \mathcal{F} is a class- C^1 function; its differential is given by

$$\mathcal{F}'(u, v)(w, y) = - \int_{\Omega} [F_u(x, u, v)w + F_v(x, u, v)y] \, dx.$$

By the same arguments as used in the proof of [1, Theorem 2.2], owing to (1_F), (3_F) and (6) there exists $\rho > 0$ such that the functional

$$\mathcal{G}(u, v, \lambda) = \Phi(u, v) + \lambda\mathcal{F}(u, v) + \lambda\rho$$

satisfies the inequality

$$\sup_{\lambda \in I} \inf_{(u,v) \in X} \mathcal{G}(u, v, \lambda) < \inf_{(u,v) \in X} \sup_{\lambda \in I} \mathcal{G}(u, v, \lambda),$$

where $I = [0, +\infty[$. Now, we wish to apply Theorem 1.1 to the continuous functional \mathcal{G} . Clearly, for each $(u, v) \in X$, the functional $\mathcal{G}(u, v, \cdot)$ is concave in I .

Fix $\lambda \in I$. Since $W_G^{1,\alpha}(\Omega) \hookrightarrow L^\alpha(\Omega)$ is continuous, there exist two positive constants, c_1 and c_2 , such that

$$\|u\|_{L^p} \leq c_1\|u\|_p \quad \text{and} \quad \|v\|_{L^q} \leq c_2\|v\|_q.$$

Let

$$a < \min \left\{ \frac{1}{\lambda p c_1^p}, \frac{1}{\lambda q c_2^q} \right\}.$$

Since (5) holds, there exists a function $k_a \in L^1(\Omega)$ such that

$$F(x, \xi, \eta) \leq a(|\xi|^p + |\eta|^q) + k_a(x)$$

for all $(\xi, \eta) \in \mathbb{R}^2$ and $x \in \Omega$.

Fix $(u, v) \in X$. From the last inequality we deduce that

$$\int_{\Omega} F(x, u(x), v(x)) \, dx \leq a(c_1^p\|u\|_p^p + c_2^q\|v\|_q^q) + \|k_a\|_{L^1}.$$

So,

$$\mathcal{G}(u, v, \lambda) \geq \left(\frac{1}{p} - \lambda c_1^p a \right) \|u\|_p^p + \left(\frac{1}{q} - \lambda c_2^q a \right) \|v\|_q^q - \lambda \|k_a\|_{L^1} + \lambda\rho,$$

i.e. $\mathcal{G}(\cdot, \cdot, \lambda)$ is coercive.

Fix $\lambda \in I$. In view of (1_F) and (4_F) , by [1, Lemma 3.4], the functional \mathcal{F} is sequentially weakly continuous on X . Thus, the functional $\mathcal{G}(\cdot, \cdot, \lambda)$ is sequentially weakly lower semicontinuous in X .

Now, fixing $\gamma > \sup_{\lambda \in I} \inf_{(u,v) \in X} \mathcal{G}(u, v, \lambda)$, Theorem 1.1 ensures that there exists a non-empty open set $A \subseteq I$ with the following property: for every $\lambda \in A$ and every continuous function $H : \Omega \times \mathbb{R}^2 \rightarrow \mathbb{R}$ satisfying conditions (1_H) – (4_H) , there exists $\delta > 0$ such that, for each $\mu \in]0, \delta[$, the functional

$$E_{\lambda, \mu}(u, v) = \mathcal{G}(u, v, \lambda) + \mu \mathcal{H}(u, v)$$

has at least two local minima lying in the set $\{(u, v) \in X : \mathcal{G}(u, v, \lambda) < \gamma\}$, namely $(u_{\lambda, \mu}^i, v_{\lambda, \mu}^i)$, $i \in \{1, 2\}$, where \mathcal{H} is the sequentially weakly continuous functional defined by

$$\mathcal{H}(u, v) = - \int_{\Omega} H(x, u(x), v(x)) \, dx.$$

Since F and H are axially symmetric in the first variable, and each $g \in G$ is isometric, the function $E_{\lambda, \mu}$ is G -invariant, i.e.

$$E_{\lambda, \mu}(g(u, v)) = E_{\lambda, \mu}(gu, gv) = E_{\lambda, \mu}(u, v)$$

for each $g \in G$, $(u, v) \in W_0^{1,p}(\Omega) \times W_0^{1,q}(\Omega)$. As

$$\text{Fix}(W_0^{1,p}(\Omega) \times W_0^{1,q}(\Omega)) = W_{0,G}^{1,p}(\Omega) \times W_{0,G}^{1,q}(\Omega),$$

by the principle of symmetric criticality of [3], we find that $(u_{\lambda, \mu}^i, v_{\lambda, \mu}^i)$, $i \in \{1, 2\}$, are also the critical points of $E_{\lambda, \mu}$ and then weak solutions of the problem $(S_{\lambda, \mu})$.

Finally, let $[a, b] \subset A$ be any non-degenerate compact interval. Observe that

$$\begin{aligned} \bigcup_{\lambda \in [a, b]} \{(u, v) \in X : \mathcal{G}(u, v, \lambda) \leq \gamma\} \\ \subseteq \{(u, v) \in X : \mathcal{G}(u, v, a) \leq \gamma\} \cup \{(u, v) \in X : \mathcal{G}(u, v, b) \leq \gamma\}. \end{aligned}$$

This implies that the set

$$S := \bigcup_{\lambda \in [a, b]} \{(u, v) \in X : \mathcal{G}(u, v, \lambda) \leq \gamma\}$$

is bounded. Hence, the local minima of $E_{\lambda, \mu}$ have norm less than or equal to σ , taking $\sigma = \sup_{(u,v) \in S} \|(u, v)\|_{p,q}$. This concludes the proof. \square

Now, we give an example in which the hypotheses of Theorem 2.1 are satisfied.

Example 2.2. Let $\Omega = \omega \times \mathbb{R}^2$, where ω is a bounded open interval in \mathbb{R} . Let $\alpha, \beta : \Omega \rightarrow \mathbb{R}$ be two continuous, non-negative, not identically zero, axially symmetric functions with compact support in Ω . Then there exist a number σ and a non-degenerate compact

interval $C \subseteq [0, +\infty[$ such that, for every $a \in]\frac{3}{2}, 3[$, $b \in]\frac{9}{4}, 9[$, $\lambda \in C$, there exists $\delta > 0$ such that, for each $\mu \in]0, \delta[$, the system

$$\begin{aligned} -\Delta_{3/2}u &= \frac{5}{2}\lambda\alpha(x)|u|^{1/2}u \cos(|u|^{5/2} + |v|^3) + \mu\beta(x)au|u|^{a-2} && \text{in } \Omega, \\ -\Delta_{9/4}v &= 3\lambda\alpha(x)|v|v \cos(|u|^{5/2} + |v|^3) + \mu\beta(x)bv|v|^{b-2} && \text{in } \Omega, \\ u = v &= 0 && \text{on } \partial\Omega, \end{aligned}$$

has at least two solutions with the properties from Theorem 2.1.

In this case we have

$$F(x, \xi, \eta) = \alpha(x) \sin(|\xi|^{5/2} + |\eta|^3) \quad \text{and} \quad H(x, \xi, \eta) = \beta(x)(|\xi|^a + |\eta|^b)$$

for each $(x, \xi, \eta) \in \Omega$. It is easy to observe that conditions (1_F) – (3_F) and (1_H) – (3_H) hold immediately, while (4_F) is verified by choosing $r = \frac{11}{4}$, $s = \frac{33}{8}$, and (4_H) is verified choosing $r \in]a, 3[$, $s \in]b, 9[$ with $s = \frac{3}{2}r$. Finally, (5) is obvious and (6) follows by putting $u_0(x) = (\frac{1}{2}\pi)^{2/5}$ for every $x \in \text{supp } \alpha$ and $v_0(x) = 0$ for every $x \in \Omega$.

By the same arguments as used in the proof of Theorem 2.1, but applying also the Palais–Smale properties, we obtain the result below. We recall that a Gâteaux differentiable functional S on a real Banach space X is said to satisfy the Palais–Smale condition if each sequence $\{x_n\}$ in X such that $\sup_{n \in \mathbb{N}} |S(x_n)| < +\infty$ and $\lim_{n \rightarrow +\infty} \|S'(x_n)\|_X = 0$ admits a strongly converging subsequence.

Theorem 2.3. *Assume that the hypotheses of Theorem 2.1 hold.*

Then there exists a non-empty open set $A \subseteq [0, +\infty[$ such that, for every $\lambda \in A$ and for every continuous function $H : \Omega \times \mathbb{R}^2 \rightarrow \mathbb{R}$ satisfying conditions (1_H) – (4_H) and

$$(5_H) \quad \limsup_{(|\xi, \eta|) \rightarrow +\infty} \frac{H(x, \xi, \eta)}{|\xi|^p + |\eta|^q} < +\infty \quad \text{uniformly for every } x \in \Omega,$$

there exists $\delta > 0$ such that, for each $\mu \in]0, \delta[$, the problem $(S_{\lambda, \mu})$ has at least three solutions axially symmetric.

Proof. Let A and $E_{\lambda, \mu}$ have the same meaning as in the proof of Theorem 2.1, $H : \Omega \times \mathbb{R}^2 \rightarrow \mathbb{R}$ being a continuous function satisfying (5_H) . Reasoning as in the proof of Theorem 2.1, there exists $\delta_1 > 0$ such that, for each $\mu \in]0, \delta_1[$, the problem $(S_{\lambda, \mu})$ has at least two solutions.

First of all, the functional $E_{\lambda, \mu}$ is coercive. In fact, from (5_H) , there exist a positive constant $b \in \mathbb{R}$ and a function $k_b(x) \in L^1(\Omega)$ such that

$$H(x, \xi, \eta) \leq b(|\xi|^p + |\eta|^q) + k_b(x)$$

for all $x \in \Omega$ and $(\xi, \eta) \in \mathbb{R}^2$.

Fix $(u, v) \in X$. From the previous inequality we deduce that

$$\mathcal{H}(u, v) = - \int_{\Omega} H(x, u(x), v(x)) \, dx \geq -b(c_1^p \|u\|_p^p + c_2^q \|v\|_q^q) - \|k_b\|_{L^1}.$$

Let

$$\delta < \min \left\{ \delta_1, \frac{1}{b} \left(\frac{1}{pc_1^p} - \lambda a \right), \frac{1}{b} \left(\frac{1}{qc_2^q} - \lambda a \right) \right\}.$$

So, for each $\lambda \in A$ and $\mu \in]0, \delta[$, we have

$$\begin{aligned} E_{\lambda, \mu}(u, v) &= \mathcal{G}(u, v, \lambda) + \mu \mathcal{H}(u, v) \\ &\geq \left(\frac{1}{p} - c_1^p(\lambda a + \mu b) \right) \|u\|_p^p + \left(\frac{1}{q} - c_2^q(\lambda a + \mu b) \right) \|v\|_q^q - \lambda \|k_a\|_{L^1} + \lambda \rho - \mu \|k_b\|_{L^1} \end{aligned}$$

for all $(u, v) \in X$. This ensures the coercivity of the functional $E_{\lambda, \mu}$ for each $\lambda \in A$ and $\mu \in]0, \delta[$.

Now, let us check the Palais–Smale condition for $E_{\lambda, \mu}$. To this end, let $\{(u_n, v_n)\}$ be a sequence in X satisfying

$$\sup_{n \in \mathbb{N}} |E_{\lambda, \mu}(u_n, v_n)| \leq M, \quad \lim_{n \rightarrow \infty} \|E'_{\lambda, \mu}(u_n, v_n)\|_{X^*} = 0. \quad (2.1)$$

Since the functional $E_{\lambda, \mu}$ is coercive, the sequence $\{(u_n, v_n)\}$ is bounded in X . So, applying [1, Lemma 3.5] to the functional $E_{\lambda, \mu}(\cdot, \cdot)$ we obtain that $\{(u_n, v_n)\}$ contains a strongly convergent subsequence in X .

Since the functional $E_{\lambda, \mu}$ is C^1 in X , our conclusion follows by [4, Corollary 1], which ensures that there exists a third critical point of the functional $E_{\lambda, \mu}$ which is a solution of problem $(S_{\lambda, \mu})$. \square

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