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## DELAY DIFFERENTIAL EQUATIONS OF ODD ORDER SATISFYING PROPERTY $P_k$

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## Abstract

The property  $P_k$   $(k = 0, 1, \dots, n)$  is formulated. For k = 0, *n* this property reduces to conditions *A* and *B* defined by Kiguradze (1962) for a class of ordinary differential equations. Sufficient conditions are then given which guarantee that a class of delay differential equations of odd order possesses property  $P_k$ . The property  $P_k$  is also seen to be useful in reducing the number of types of positive solutions of a related nonhomogeneous delay differential equation.

The equation

(1)  $D^m y(t) + F[t, y(t)] = 0, \ m \ge 2$ 

has been considered by various authors subject to additional sign and monotone properties on F(t, u). Briefly, a solution of (1) or of (2) below is called oscillatory on  $[a, \infty)$  if for each  $\alpha > a$  there is a  $\beta > \alpha$  such that  $y(\beta) = 0$ . It is called nonoscillatory otherwise. Paralleling the development by Kiguradze (1962) we adopt the following terminology.

DEFINITION 1. For m = 2n + 1, a positive solution y of (1) is of type  $A_k$ ( $k = 0, \dots, n$ ) if for t sufficiently large  $D^iy(t) > 0$  for  $j = 0, \dots, 2k$  and  $(-1)^j D^j y(t) > 0$  for  $j = 2k + 1, \dots, 2n$ .

DEFINITION 2. For m = 2n, a positive solution y of (1) is of type  $A_k$ ( $k = 0, \dots, n-1$ ) if for t sufficiently large  $D^i y(t) > 0$  for  $j = 0, \dots, 2k+1$  and  $(-1)^{j+1}D^j y(t) > 0$  for  $j = 2k+2, \dots, 2n-1$ .

DEFINITION 3. Equation (1) is said to satisfy condition A if (1) has an oscillatory solution and every nonoscillatory solution tends to zero monotonically as  $t \rightarrow \infty$ .

DEFINITION 4. Equation (1) satisfies condition B if a solution y is either oscillatory or  $\lim_{t\to\infty} D^{m-1}y(t) = 0$ .

It has been shown in Kiguradze (1962) that a positive solution of (1) is necessarily of type  $A_k$  for some admissible k. For m = 2n, (1) fulfills condition A if, and only if, all solutions are oscillatory. For m = 2n + 1, (1) satisfies condition A if, and only if, there are no solutions of type  $A_r$   $(r = 1, \dots, n)$  and every solution of type  $A_0$  tends to zero monotonically as  $t \to \infty$ .

In section one we consider a homogeneous delay differential equation of odd order and formulate a property  $P_k$  which includes both conditions A and B as special cases. Section two is devoted to providing sufficient conditions for the equation to possess property  $P_k$ . In section three an *a priori* classification according to types  $C_k^R$  is introduced for the positive solutions of a nonhomogeneous delay differential equation of odd order. The property  $P_k$  is seen to be useful in reducing the kinds of positive solutions admissible.

1

In this section and the next we shall consider the homogeneous delay differential equation

(2) 
$$D^{2n+1-i}[r(t)D^{i}y(t)] + y_{\tau}(t)f[t, y_{\tau}(t)] = 0,$$

where  $0 < m \le r(t) \le M < \infty$ ,  $0 \le \tau(t) \le T < \infty$ ,  $y_{\tau}(t) = y[t - \tau(t)]$  and f(t, u) satisfies the following properties:

(F1) f(t, u) is a continuous real-valued function on  $[0, \infty) \times R$ ;

(F2) for each fixed  $t \in [0, \infty)$ , f(t, u) < f(t, v) for 0 < u < v; and

(F3) for each fixed  $t \in [0, \infty)$ , f(t, u) > 0 and f(t, -u) = f(t, u) for  $u \neq 0$ .

We first let

$$y_{j}(t) = \begin{cases} D^{i}y(t), & j = 0, \dots, i-1 \\ D^{j-i}[r(t)D^{i}y(t)], & j = i, \dots, 2n. \end{cases}$$

Analogous to Definition 1 we shall classify the positive solutions of (2).

DEFINITION 5. A positive solution y of (2) is of type  $C_k$  on  $[T_0, \infty)$  if for  $t \ge T_0 y_i(t) > 0$   $(j = 0, \dots, 2k)$  and  $(-1)^j y_i(t) > 0$   $(j = 2k + 1, \dots, 2n)$ .

As in Terry (1973, 1974), it is evident that a positive solution of (2) is necessarily of type  $C_k$  for some  $k = 0, \dots, n$ . Moreover, the following two lemmas may be established.

LEMMA 1. Let y be a solution of (2) of type  $C_k$ ,  $k \ge 1$ . Then there exist numbers  $N_j^k > 0$   $(j = 0, \dots, 2k)$  such that

$$(t - T_1)y_i(t) \le N_i^k y_{i-1}(t), t \ge T_1 = T_0 + T$$
 and

$$ty_i(t) \leq 2N_i^{\kappa}y_{j-1}(t), \qquad t \geq 2T_1.$$

LEMMA 2. Let y be a solution of (2) of type  $C_k$ ,  $k \ge 1$ . Then there exist numbers  $k_i > 0$  and  $t_i \ge T_1$   $(j = 0, \dots, 2k - 1)$  such that

$$y_{j\tau}(t) = y_j(t-\tau(t)) \ge k_j y_j(t), \qquad t \ge t_j.$$

While it is of interest to obtain specific estimates for the numbers  $N_{i}^{k}$ , this is unnecessary for the subsequent development of this paper. As in Terry (1973), these two lemmas and the later results may be extended to the case where  $\tau(t)$  satisfies either of the two conditions

(T1)  $0 \le \tau(t) \le \mu t$ ,  $0 \le \mu < m/(m+M)$ , or

(T2)  $0 \leq \tau(t) \leq \mu t^{\beta}$ ,  $0 \leq \mu < \infty$  and  $0 \leq \beta < 1$ ,

provided  $T_1$  is reinterpreted as min  $\{t > T_0: t - \tau(t) \ge T_0$  for  $t \ge T_1\}$ .

DEFINITION 6. Equation (2) fulfills property  $P_k$  if, and only if, (2) has no solutions of types  $C_r$   $(r = k + 1, \dots, n)$  and for any solution y(t) of type  $C_k$  the intermediate function  $y_{2k}(t)$  tends to zero monotonically as  $t \to \infty$ .

When  $r \equiv 1$  and  $\tau \equiv 0$ , the classification of solutions of (2) according to types  $C_k$  coincides with that of Kiguradze (1962). Moreover, property  $P_0$  is the natural analogue of condition A; property  $P_n$  corresponds to condition B.

2

We now seek to prescribe conditions which ensure that equation (2) fulfills the property  $P_k$ .

THEOREM 1. Let y be a positive solution of (2) of type  $C_k$ . Then  $y_{2k}(t)$  tends to zero monotonically as  $t \to \infty$  if for all positive constants C

(3) 
$$\int_{0}^{\infty} t^{2n} f(t, Ct^{2k}) dt = +\infty.$$

PROOF. Let y be a solution of (2) of type  $C_k$  on  $[T_0, \infty)$ . Then for  $t \ge T_1$ ,  $y_r(t) > 0$ ,  $y_i(t) > 0$   $(j = 0, \dots, 2k)$  and  $(-1)^i y_i(t) > 0$   $(j = 2k + 1, \dots, 2n)$ . Multiplying (2) by  $t^{2n-2k}$  and integrating from  $T_1$  to  $t \ge T_1$ 

$$\int_{T_1}^t s^{2n-2k} Dy_{2n}(s) ds + \int_{T_1}^t s^{2n-2k} y_{\tau}(s) f[s, y_{\tau}(s)] ds = 0.$$

Integrating the first term by parts

$$I = \int_{T_1}^{t} s^{2n-2k} Dy_{2n}(s) ds = [s^{2n-2k}y_{2n}(s)]_{T_1}^{t}$$
$$-(2n-2k) \int_{T_1}^{t} s^{2n-2k-1}y_{2n}(s) ds.$$

An easy induction yields

(4)  
$$I = \left[\sum_{j=0}^{l} (-1)^{j} (2n-2k)_{j} s^{2n-2k-j} y_{2n-j}(s)\right]_{T_{1}}^{t} + (-1)^{l+1} (2n-2k)_{l+1} \int_{T_{1}}^{t} s^{2n-2k-l-1} y_{2n-l}(s) ds,$$

where  $0 \le j \le l \le 2n - i$ ,  $(n)_0 = 1$  and  $(n)_k = n \cdots (n - k + 1)$  for  $k \ge 1$ . If  $2k \ge i$ ,  $2n - 2k \le 2n - i$  and we may let l = 2n - 2k - 1 in (4) to obtain

(5)  
$$I = \left[\sum_{j=0}^{2n-2k-1} (-1)^{j} (2n-2k)_{j} s^{2n-2k-j} y_{2n-j}(s)\right]_{T_{1}}^{t}$$
$$+ (-1)^{2n-2k} (2n-2k)_{2n-2k} \int_{T_{1}}^{t} y_{2k+1}(s) ds.$$

On the other hand, if 1 < 2k < i, then 2n - 2k > 2n - i. We let l = 2n - i in (4) and observe that

$$(-1)^{i+1}y_{2n-i}(s) = (-1)^{2n-i+1}y_i(s) = (-1)^{i+1}y_i(s)$$
$$= (-1)^{i+1}r(s)D^iy(s)$$
$$\ge (-1)^{i+1}MD^iy(s).$$

Then (4) becomes

(6)  
$$I \ge \left[\sum_{j=0}^{2n-i} (-1)^{j} (2n-2k)_{j} s^{2n-2k-j} y_{2n-j}(s)\right]_{T_{1}}^{t} + (-1)^{2n-i+1} M (2n-2k)_{2n-i+1} \int_{T_{1}}^{t} s^{i-2k-1} D y_{i-1}(s) ds.$$

We now examine the latter integral. An integration by parts results in

$$J = \int_{T_1}^t s^{i-2k-1} Dy_{i-1}(s) ds = [s^{i-2k-1}y_{i-1}(s)]_{T_1}^t$$
$$-(i-2k-1) \int_{T_1}^t s^{i-2k-2}y_{i-1}(s) ds.$$

This serves as the anchor for another inductive argument based on further integration by parts. It follows that

$$J = \left[\sum_{j=1}^{L} (-1)^{j+1} (i-2k-1)_{j-1} s^{i-2k-j} y_{i-j}(s)\right]_{T_1}^t$$
  
+  $(-1)^L (i-2k-1)_L \int_{T_1}^t s^{i-2k-j-1} y_{i-L}(s) ds,$ 

where  $1 \leq j \leq L \leq i - 2k - 1$ . Combining (6) and (7), we obtain

$$I \ge \left[\sum_{j=0}^{2n-i} (-1)^{j} (2n-2k)_{j} s^{2n-2k-j} y_{2n-j}(s) + N_{1} \sum_{j=1}^{L} (-1)^{j+1} (i-2k-1)_{j} s^{i-2k-j} y_{i-j}(s)\right]_{T_{1}}^{t}$$
$$+ N_{1} N_{2} \int_{T_{1}}^{t} y_{i-L}(s) ds,$$

where  $N_1 = (-1)^{i+1} M (2n - 2k)_{2n-i+1}$  and  $N_2 = (-1)^L (i - 2k - 1)_L$ . We may let L = i - 2k - 1 in this and observe that

sgn 
$$N_1 N_2 = (-1)^{i+1} (-1)^L = (-1)^{i+1} (-1)^{i-2k-1} = +1.$$

It follows that

(8a) 
$$[F_{2k}(s)]_{T_1}^t + (2n - 2k)! \int_{T_1}^t y_{2k+1}(s) ds + \int_{T_1}^t s^{2n-2k} y_r(s) f[s, y_r(s)] ds = 0$$

for  $i \leq 2k$  and

(8b)  
$$[\bar{F}_{2k}(s)]_{T_{1}}^{t} + N_{1}N_{2}\int_{T_{1}}^{t} y_{2k+1}(s)ds + \int_{T_{1}}^{t} s^{2n-2k}y_{\tau}(s)f[s, y_{\tau}(s)]ds \leq 0$$

for i > 2k, where

$$F_{2k}(s) = \sum_{j=0}^{2n-2k-1} (-1)^{j} (2n-2k)_{j} s^{2n-2k-j} y_{2n-j}(s) \text{ and}$$
  
$$\bar{F}_{2k}(s) = \sum_{j=0}^{2n-i} (-1)^{j} (2n-2k)_{j} s^{2n-2k-j} y_{2n-j}(s)$$
  
$$+ N_{1} \sum_{j=1}^{i-2k-1} (-1)^{j} (i-2k-1)_{j} s^{i-2k-j} y_{i-j}(s).$$

We note that each term of  $F_{2k}(s)$  is positive on  $[T_1, \infty)$  since

$$(-1)^{i}y_{2n-i}(s) = (-1)^{2n-i}(s) = (-1)^{p}y_{p}(s)$$

and  $p = 2n - j \ge 2k + 1$  since  $0 \le j \le 2n - 2k - 1$ . Similarly, each term of  $\overline{F}_{2k}(s)$  is positive since

$$(-1)^{i+1}(-1)^{i+1}y_{i-j}(s) = (-1)^{i-j}y_{i-j}(s) = (-1)^{q}y_{q}(s)$$

and  $q = i - j \ge 2k + 1$  since  $j \le i - 2k - 1$ . Moreover,

$$\int_{T_1}^t y_{2k+1}(s)ds = y_{2k}(t) - y_{2k}(T_1) \quad \text{if} \quad 2k+1 \neq i$$
$$= \int_{T_1}^t r(s)D^i y(s) \quad \text{if} \quad 2k+1 = i$$
$$\geq M \int_{T_1}^t D^i y(s) = M[y_{2k}(t) - y_{2k}(T_1)].$$

Let us assume that  $\lim_{t\to\infty} y_{2k}(t) = \gamma > 0$ . Since  $y_{2k+1}(t) < 0$  on  $[T_1, \infty)$ ,  $y_{2k}(t)$  is a decreasing function of t on  $[T_1, \infty)$  and  $y_{2k}(t) \ge \gamma$ ,  $t \ge T_1$ . By Lemma 1

$$y(s) \ge Ns^{2k}y_{2k}(s) \ge N\gamma s^{2k}$$
, where  $N^{-1} = N_1^k N_2^k \cdots N_{2k}^k$ 

Hence,

$$y_{\tau}(s) \geq N\gamma[s-\tau(s)]^{2k} \geq N\gamma(1-\mu)^{2k}s^{2k}$$

if  $\tau$  satisfies (T1). On the other hand, if  $\tau$  satisfies (T2), there is a  $T_2 \ge T_1$  such that  $s - \tau(s) \ge s/2$  for  $s \ge T_2$ , which implies that  $y_{\tau}(s) \ge N\gamma 2^{-2k} s^{2k}$  for  $s \ge T_2$ . As we may replace  $T_1$  by  $T_2$  in the above considerations, we may assume, without loss of generality, that  $T_2 = T_1$ . Thus, in either case  $y_{\tau}(s) \ge Cs^{2k}$  on the appropriate interval so that

$$s^{2n-2k}y_{\tau}(s)f[s, y_{\tau}(s)] \ge s^{2n-2k}Cs^{2k}f[s, Cs^{2k}]$$
  
=  $Cs^{2n}f(s, Cs^{2k}).$ 

For  $i \leq 2k$  we substitute in (8a)

$$[F_{2k}(s)]_{T_1}^t + (2n - 2k)! [y_{2k}(s)]_{T_1}^t s^{2n} f(s, Cs^{2k}) ds \leq 0.$$

Transposing,

$$\int_{T_1}^t s^{2n} f(s, Cs^{2k}) ds \leq C^{-1} [F_{2k}(T_1) + (2n - 2k)! y_{2k}(t)].$$

This contradicts (3) in the case  $\tau$  satisfies (T1); if  $\tau$  satisfies (T2), we replace  $T_1$  by  $T_2$  and obtain the same contradiction. For i > 2k, we substitute in (8b) instead.

THEOREM 2. Let  $\phi$  be a function satisfying  $\phi(y) > 0$ ,  $\phi'(y) \ge 0$  and

(9a) 
$$\int_{-\infty}^{\infty} \frac{dy}{y\phi(y)} < \infty;$$

then (2) fulfills property  $P_k$  if for all positive constants C

(9b) 
$$\int_{-\infty}^{\infty} t^{2n} f(t, Ct^{2k}) \phi^{-1}(t) dt = +\infty.$$

PROOF. Suppose that y is a solution of (2) of type  $C_k$  on  $[T_0, \infty)$ , where  $k \ge 1$ . Then multiplying equation (2) by  $t^{2n} [\phi(t)y(t)]^{-1}$  and integrating from  $T_1$  to  $t > T_1$ 

(10) 
$$\int_{T_1}^t s^{2n} Dy_{2n}(s) [\phi(s)y(s)]^{-1} ds + \int_{T_1}^t s^{2n} \frac{f[s, y_{\tau}(s)]}{\phi(s)y(s)} ds = 0.$$

We denote the first integral by  $I_1$ . An integration by parts yields

(11) 
$$I_{1} = [\gamma(s)(\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \gamma(s)D((\phi(s)y(s))^{-1})ds$$

where  $\gamma(s) = D^{-1}(s^{2n}Dy_{2n}(s))$ . Specifically, one integration by parts gives

$$\gamma(s) = s^{2n} y_{2n}(s) - 2n D^{-1}(s^{2n-1} y_{2n}(s)).$$

We may establish by induction that

(12)  

$$\gamma(s) = \sum_{j=0}^{p} (-1)^{j} (2n)_{j} s^{2n-j} y_{2n-j}(s) + (-1^{p+1} (2n)_{p+1} D^{-1} [s^{2n-p-1} y_{2n-p}(s)]$$

for  $0 \le j \le p \le 2n - i$ . If  $2k \ge i$ ,  $2n - 2k \le 2n - i$  and we may let p = 2n - 2k in (12) to obtain

$$\gamma(s) = \sum_{j=0}^{2n-2k} (-1)^j (2n)_j s^{2n-j} y_{2n-j}(s) + N_0 D^{-1}[s^{2k-1} y_{2k}(s)],$$

where  $N_0 = (-1)^{2n-2k+1}(2n)_{2n-2k+1}$ . We define  $\gamma_0(s)$  by

$$\gamma(s) = \gamma_0(s) + N_0 D^{-1}[s^{2k-1}y_{2k}(s)].$$

Then, a substitution in (11) produces

$$I_{1} = [(\gamma_{0}(s) + N_{0}D^{-1}(s^{2k-1}y_{2k}(s)))(\phi(s)y(s))^{-1}]_{T_{1}}^{t}$$
  
$$- \int_{T_{1}}^{t} (\gamma_{0}(s) + N_{0}D^{-1}(s^{2k-1}y_{2k}(s))D((\phi(s)y(s))^{-1})ds$$
  
$$= [\gamma_{0}(s)(\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \gamma_{0}(s)D((\phi(s)y(s))^{-1})ds$$
  
$$+ N_{0}[D^{-1}(s^{2k-1}y_{2k}(s))/\phi(s)y(s)]_{T_{1}}^{t}$$
  
$$- N_{0}\int_{T_{1}}^{t} D^{-1}(s^{2k-1}y_{2k}(s))D((\phi(s)y(s))^{-1})ds.$$

Applying the integration-by-parts formula in reverse, we recombine the last two terms to obtain

$$I_{1} = [\gamma_{0}(s)(\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \gamma_{0}(s)D((\phi(s)y(s))^{-1})ds + N_{0}\int_{T_{1}}^{t} \frac{s^{2k-1}y_{2k}(s)}{\phi(s)y(s)}ds.$$

By Lemma 1 there is a number  $N_{2k} = N_1^k \cdots N_{2k}^k > 0$  such that

$$t^{2k}y_{2k}(t) \leq N_{2k}y(t)$$
 for  $t \geq 2T_1$ .

Thus

$$\frac{s^{2k-1}y_{2k}(s)}{\phi(s)y(s)} = \frac{s^{2k}y_{2k}(s)}{s\phi(s)y(s)} \le \frac{N_{2k}}{s\phi(s)}$$

Since  $N_0 = -|N_0| < 0$ ,

(13)  
$$I_{1} \ge [\gamma_{0}(s)(\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \gamma_{0}(s)D((\phi(s)y(s))^{-1})ds$$
$$- |N_{0}|N_{2k}\int_{2T_{1}}^{t} \frac{ds}{s\phi(s)}.$$

Otherwise, if 2k < i, we continue the inductive procedure defined by (12) until p = 2n - i. Then (12) becomes

$$\gamma(s) = \sum_{j=0}^{2n-i} (-1)^{j} (2n)_{j} s^{2n-j} y_{2n-j}(s) + N_{i} D^{-i} [s^{i-i} y_{i}(s)],$$

where  $N_1 = (-1)^{2n-i+1} (2n)_{2n-i+1}$ . Letting

$$\gamma(s) = \gamma_i(s) + N_1 D^{-1}[s^{i-1}y_i(s)];$$

it follows as before upon substitution in (11) that

$$I_{1} = [\gamma_{1}(s)(\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \gamma_{1}(s)D((\phi(s)y(s))^{-1})ds + N_{1}\int_{T_{1}}^{t} \frac{s^{i-1}y_{i}(s)}{\phi(s)y(s)}ds.$$

We observe that

$$N_{1}y_{i}(s) = |N_{1}|(-1)^{2n-i+1}y_{i}(s) = |N_{1}|(-1)^{i+1}y_{i}(s)$$
$$= |N_{1}|(-1)^{i+1}r(s)Dy_{i-1}(s)$$
$$\geq |N_{1}|(-1)^{i+1}MDy_{i-1}(s) = MN_{1}Dy_{i-1}(s).$$

Thus,

(14)  
$$I_{1} \ge [\gamma_{1}(s)(\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \gamma_{1}(s)D((\phi(s)y(s))^{-1})ds + N_{1}M\int_{T_{1}}^{t} \frac{s^{i-1}Dy_{i-1}(s)}{\phi(s)y(s)}ds.$$

458

Analogous to (11) we have

$$I_{2} = \int_{T_{1}}^{t} \frac{s^{t-1} Dy_{t-1}(s)}{\phi(s)y(s)} ds = [\gamma_{2}(s) \ (\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \gamma_{2}(s) D((\phi(s)y(s))^{-1}) ds,$$

where  $\gamma_2(s) = D^{-1}[s^{i-1}Dy_{i-1}(s)]$ . We find upon one integration that

$$\gamma_2(s) = s^{i-1}y_{i-1}(s) - (i-1)D^{-1}[s^{i-2}y_{i-1}(s)].$$

An inductive argument yields

$$\gamma_{2}(s) = \sum_{j=1}^{p} (-1)^{j+1} (i-1)_{j-1} s^{i-j} y_{i-j}(s) + (-1)^{p} (i-1)_{p} D^{-1} [s^{i-p-1} y_{i-p}(s)],$$

for  $i \leq j \leq p \leq i - 2k$ . Letting p = i - 2k results in

$$\begin{aligned} \gamma_2(s) &= \sum_{j=1}^{i-2k} (-1)^{j+1} (i-1)_{j-1} s^{i-j} y_{i-j}(s) \\ &+ (-1)^{i-2k} (i-1)_{i-2k} D^{-1} [s^{2k-1} y_{2k}(s)] \\ &= \gamma_3(s) + N_2 D^{-1} [s^{2k-1} y_{2k}(s)], \end{aligned}$$

where

$$\gamma_3(s) = \sum_{j=1}^{i-2k} (-1)^{j+1} (i-1)_{j-1} s^{i-j} y_{i-j}(s)$$

and

$$N_2 = (-1)^{i-2k} (i-1)_{i-2k}.$$

To simplify the expressions involved, let

$$\Gamma(s) = \gamma_1(s) + M N_1 \gamma_2(s)$$
  
=  $\gamma_1(s) + M N_1 [\gamma_3(s) + N_2 D^{-1}(s^{2k-1}y_{2k}(s))]$   
=  $\gamma_1(s) + M N_1 \gamma_3(s) + M N_1 N_2 D^{-1}[s^{2k-1}y_{2k}(s)]$   
=  $\Gamma_0(s) + M N_1 N_2 D^{-1}[s^{2k-1}y_{2k}(s)]$   
=  $\Gamma_0(s) - M |N_1 N_2| D^{-1}[s^{2k-1}y_{2k}(s)].$ 

We note here that sgn  $N_1 N_2 = (-1)^{2n-i+1} (-1)^{i-2k} = (-1)^1 = -1$ . Substituting in (14),

$$I_{1} \ge [\gamma_{1}(s)(\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \gamma_{1}(s)D((\phi(s)y(s))^{-1})ds$$
  
+  $MN_{1}[(\gamma_{3}(s) + N_{2}D^{-1}(s^{2k-1}y_{2k}(s)))/\phi(s)y(s)]_{T_{1}}^{t}$   
-  $MN_{1}\int_{T_{1}}^{t} (\gamma_{3}(s) + N_{2}D^{-1}(s^{2k-1}y_{2k}(s)))D((\phi(s)y(s))^{-1})ds$ 

$$= [\Gamma_0(s)(\phi(s)y(s))^{-1}]_{T_1}^t - \int_{T_1}^t \Gamma_0(s)D((\phi(s)y(s))^{-1})ds$$
  
+  $MN_1N_2\int_{T_1}^t \frac{s^{2k-1}y_{2k}(s)}{\phi(s)y(s)}ds.$ 

As in the discussion preceding (13) we conclude that

(15)  
$$I_{1}\tau[\Gamma_{0}(s)(\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \Gamma_{0}(s)D((\phi(s)y(s))^{-1})ds - M|N_{1}N_{2}|\int_{2T_{1}}^{t} \frac{ds}{s\phi(s)}.$$

We next consider the second integral in (10). By Lemma 2 there is a  $k_0 > 0$ and a  $t_0 > T_1$  such that  $y_r(s) \ge k_0 y(s)$  for  $s \ge t_0$ . Since  $y_{2k}(s) > 0$ ,  $y_{2k-1}(s)$  is increasing on  $[T_0, \infty)$  and there is a  $C_0 > 0$  such that  $y_{2k-1}(s) \ge C_0$  for  $s \ge T_1$ . Moreover, by Lemma 1 there is an  $N_{2k-1} = N_1^k \cdots N_{2k-1}^k$  such that  $s^{2k-1}y_{2k-1}(s) \le N_{2k-1}y(s)$  for  $s \ge 2T_1$ . Thus,

$$y_{\tau}(s) \ge k_0 y(s) \ge k_0 N_{2k-1}^{-1} s^{2k-1} y_{2k-1}(s) \ge k_0 N_{2k-1}^{-1} C_0 s^{2k-1}$$

By (iii)

$$s^{2n}f[s, y_{\tau}(s)]y_{\tau}(s)y^{-1}(s)\phi^{-1}(s) \ge k_0s^{2n}f(s, C_1s^{2k-1})\phi^{-1}(s),$$

where  $C_1 = k_0 N_{2k-1}^{-1} C_0$  and  $s \ge T_* = \max \{t_0, 2T_1\}$ . As a result,

(16)  
$$\int_{T_{1}}^{t} \frac{s^{2n} f[s, y_{\tau}(s)] y_{\tau}(s) ds}{\phi(s) y(s)} \ge \int_{T_{2}}^{t} \frac{s^{2n} f[s, y_{\tau}(s)] y_{\tau}(s) ds}{\phi(s) y(s)}$$
$$\ge k_{0} \int_{T_{2}}^{t} s^{2n} f(s, C_{1} s^{2k-1}) ds / \phi(s).$$

Substituting (16) together with (13) or (15) in (10), we obtain

$$\begin{aligned} & [\gamma_0(s)(\phi(s)y(s))^{-1}]_{T_1}^t - \int_{T_1}^t \gamma_0(s)D((\phi(s)y(s))^{-1})ds \\ & (17a) \\ & -|N_0|N_{2k}\int_{2T_1}^t \frac{ds}{s\phi(s)} + k_0\int_{T_*}^t s^{2n}f(s,C_1s^{2k-1})ds/\phi(s) \leq 0 \qquad \text{for } 2k \geq i \end{aligned}$$

$$[\Gamma_{0}(s)(\phi(s)y(s))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \Gamma_{0}(s)D((\phi(s)y(s))^{-1})ds$$
(17b)  

$$-M|N_{1}N_{2}|N_{2k}\int_{2T_{1}}^{t} \frac{ds}{s\phi(s)} + k_{0}\int_{T_{*}}^{t} s^{2n}f(s,C_{1}s^{2k-1})ds/\phi(s) \leq 0 \quad \text{for } 2k < i.$$

460

We note that each term of  $\gamma_0(s)$  or of  $\Gamma_0(s)$  is positive on  $[T_1, \infty)$ . Since  $k \ge 1$ ,  $y'(s) \ge 0$  and

$$-D((\phi(s)y(s))^{-1}) = \frac{D(\phi(s)y(s))}{[\phi(s)y(s)]^2} = \frac{\phi(s)y'(s) + \phi'(s)y(s)}{[\phi(s)y(s)]^2} > 0.$$

Consequently,

$$\int_{T}^{t} s^{2n} f(s, C_{1}s^{2k-1})\phi^{-1}(s)ds \leq \begin{cases} k_{0}^{-1}[\gamma_{0}(\phi y)(T_{1}) + |N_{0}|N_{2k}\int_{2T_{1}}^{t} \frac{ds}{s\phi(s)}] \\ k_{0}^{-1}\left[\Gamma_{0}(\phi y)(T_{1}) + M |N_{1}N_{2}|N_{2k}\int_{2T_{1}}^{t} \frac{ds}{s\phi(s)}\right]. \end{cases}$$

Thus the condition

$$\int_{\infty}^{\infty} t^{2n} f(t, Ct^{2k-1}) \phi^{-1}(t) dt = \infty, \qquad k \ge 1$$

will imply that (2) has no C<sub>r</sub>-solutions  $(r = k, \dots, n)$ , that is the condition

$$\int_{0}^{\infty} t^{2n} f(t, Ct^{2k+1}) \phi^{-1}(t) dt = \infty, \qquad k \ge 0$$

will imply that (2) has no  $C_r$ -solution  $r = k + 1, \dots, n$ ). A fortiori, (9b) implies that (2) has no  $C_r$ -solutions  $(r = k + 1, \dots, n)$ , where  $k \ge 0$ . In addition, the conditions  $\phi > 0$  and  $\phi' \ge 0$  show that there is a k > 0 such that  $\phi(t) \ge k$  so that

$$\int_{\infty}^{\infty} t^{2n} f(t, Ct^{2k}) dt = k \left[ \frac{1}{k} \int_{\infty}^{\infty} t^{2n} f(t, Ct^{2k}) dt \right]$$
$$\geq k \int_{\infty}^{\infty} t^{2n} f(t, Ct^{2k}) \phi^{-1}(t) dt.$$

Thus, the integral condition of (9b) implies that of (3). By Theorem 1, any  $C_k$ -solution y of (2) will satisfy  $\lim_{t\to\infty} y_{2k}(t) = 0$ . It follows that (2) possesses property  $P_k$ .

By modifying the conditions on f and  $\phi$ , we may obtain a simpler criterion for the presence of property  $P_k$ .

DEFINITION 7. The function f is nonlinear with strength coefficient 2n + 1 - j( $j = 0, \dots, 2n + 1$ ) if, and only if, there is a function  $\phi$  satisfying  $\phi(u) > 0$ ,  $\phi'(u) \ge 0$ ,

$$\int^{\infty} \frac{du}{u\phi(u)} < \infty$$

and  $f(t, u) \ge \phi(u)f(t, Ct^{i})$ .

When j = 0, the strength coefficient is maximal and f(t, u) is called strongly nonlinear.

In the presence of some degree of nonlinearity, the hypotheses of Theorem 2 may be proportionately weakened. Suppose that f is nonlinear with strength coefficient 2n + 1 - 2j and  $\phi''(u) < 0$ . Then, multiplying (2) by  $t^{2n}[\phi(y)y]^{-1}$ , we obtain as in the proof of Theorem 2

$$[\gamma_{0}(s)(y(s)\phi(y(s)))^{-1}]_{T_{1}}^{t} - \int_{T_{1}}^{t} \gamma_{0}(s)D((y(s)\phi(y(s)))^{-1})ds$$
$$-\int_{T_{1}}^{t} \frac{s^{2k-1}y_{2k}(s)}{y(s)\phi(y(s))}ds + \int_{T_{1}}^{t} s^{2n}y_{\tau}(s)f[s,y_{\tau}(s)]ds/\phi(y(s))y(s) = 0$$

C

$$0 \ge [\Gamma_0(s)(y(s)\phi(y(s)))^{-1}]_{T_1}^t - \int_{T_1}^t \Gamma_0(s)D((y(s)\phi(y(s)))^{-1})ds$$
  
-  $M|N_1N_2| \int_{T_1}^t \frac{s^{2k-1}y_{2k}(s)}{y(s)\phi(y(s))}ds$   
+  $\int_{T_1}^t s^{2n}y_r(s)f[s, y_r(s)]ds/y(s)\phi(y(s)).$ 

Since  $\phi > 0$ ,  $\phi' \ge 0$  and  $\phi'' \le 0$ ,  $\phi'$  is a positive decreasing function on  $[T_0,\infty)$  so that

$$\phi(t)-\phi(T_1)=\int_{T_1}^t \phi'(s)ds \ge (t-T_1)\phi'(t),$$

that is.

$$(t-T_1)\phi'(t) \leq \phi(t) - \phi(T_1) < \phi(t)$$

for  $t \ge T_1$ . Thus,  $t\phi'(t) \le \phi(t)$  for  $t \ge 2T_1$ . Either of these inequalities implies that  $\lim_{t\to\infty} \phi'(t)/\phi(t) = 0$ . We consider

$$\left|\frac{\phi(y_{\tau}(t))}{\phi(y(t))} - 1\right| = \frac{\phi(y(t)) - \phi(y_{\tau}(t))}{\phi(y(t))} = \frac{\tau(t)\phi'(\mu)}{\phi(y)}$$

for some  $\mu$ , where  $y_r(t) < \mu < y(t)$ . Since  $\phi$  is an increasing function,  $\phi(y_t(t)) < \phi(\mu) < \phi(y(t))$ , which implies that  $1/\phi(y(t)) < 1/\phi(y_t(t))$ . Similarly,  $\phi'$  is a decreasing function so that  $\phi'(\mu) < \phi'(y_r(t))$ . Thus,  $\phi'(\mu)/\phi(y(t)) < \phi'(y_{\tau}(t))/\phi(y_{\tau}(t))$ . Moreover, because  $k \ge 1$ ,  $\lim_{t \to \infty} y_{\tau}(t) = \infty$ , which shows that

$$\lim_{t\to\infty}\frac{\phi(y_\tau(t))}{\phi(y(t))}=1.$$

Thus, for any  $\varepsilon$  with  $0 < \varepsilon < 1$ , there is a  $t_{\varepsilon} \ge T_1$  such that

$$\phi(y_{\tau}(t)) \geq (1-\varepsilon)\phi(y(t)), \qquad t \geq t_{\epsilon}.$$

By Lemma 2, there is a  $k_0 > 0$  and a  $t_0 \ge T_1$  such that  $y_r(t) \ge k_0 y(t)$  for  $t \ge t_0$ . Thus, for  $s \ge T = \max \{t_0, t_r, 2T_1\}$ 

$$s^{2n} \frac{y\tau(s)}{y(s)} \frac{f[s, y, (s)]}{\phi(y(s))} \ge k_0(1-\varepsilon)s^{2n} \frac{f[s, y, (s)]}{\phi(y(s))}$$
$$\ge k_0(1-\varepsilon)s^{2n}f(s, Cs^i).$$

By Lemma 1 and a change of variables

$$\int_{T_1}^t \frac{s^{2k-1}y_{2k}(s)}{y(s)\phi(y(s))} ds \ge N_{2k} \int_{T_1}^t \frac{y'(s)ds}{y(s)\phi(y(s))}$$
$$N_{2k} \int_{y(T_1)}^{y(t)} \frac{du}{u\phi(u)}.$$

We may now duplicate the rest of the arguments of the proof of Theorem 2 to obtain the following result.

COROLLARY 1. Let f be nonlinear with strength coefficient 2n + 1 - j. Let the associated function  $\phi$  satisfy  $\phi''(u) < 0$ . Then (2) fulfills property  $P_0$  if for all positive constants C

$$\int_{0}^{\infty}t^{2n}f(t,Ct^{j})dt=\infty.$$

REMARK 1. If  $\tau \equiv 0$ , the ratio  $y_{\tau}(t)/y(t)$  does not occur and the condition  $\phi''(u) < 0$  may be omitted.

REMARK 2. When  $r \equiv 1$ ,  $\tau \equiv 0$  and  $k \equiv 0$ , Theorem 1 reduces to the sufficiency of Theorem 1 of Kiguradze (1962). Under the same conditions the conclusion of Theorem 2 is that (2) satisfies property  $P_0$ , that is, condition A; Theorem 2 then coincides with Theorem 3 of Kiguradze (1962). In view of Remark 1, when  $r \equiv 1$ ,  $\tau \equiv 0$  and j = 0, Theorem 3 reduces to the sufficiency of Theorem 5 of Kiguradze (1962).

REMARK 3. When  $r \equiv 1$ ,  $\tau \equiv 0$ , k = n, the conclusion of Theorem 2 is that any  $C_n$ -solution y(t) of (2) must satisfy  $\lim_{t \to \infty} y_{2n}(t) = 0$ . This is not quite condition B since we have not shown that any positive solution of (2) has this property. If  $r(t) \equiv 1$ , property  $P_n$  reduces to condition B. For suppose that y(t)is any solution of (2) of type  $C_k$ , where k < n, then  $D^{2n-1}y(t) = y_{2n-1}(t) < 0$ . We now invoke a lemma most recently stated in generalized form by Ladas (1971) which we adapt here as follows.

LEMMA 3. Let y be a positive solution of (2) on  $[t_0,\infty)$  with  $r \equiv 1$ . Then

$$\lim_{t\to\infty} D^{2n}y(t) = \lim_{t\to\infty} (j-1)! (t-t_0)^{1-j} D^{2n+1-j}y(t)$$

where  $j = 1, \dots, 2n + 1$ .

Letting j = 2, we note that  $D^{2n}y(t) > 0$  so that  $\lim_{t\to\infty} D^{2n}y(t) \ge 0$ . On the other hand,  $D^{2n-1}y(t) < 0$ , which implies that the limit on the right-hand side is nonpositive and  $\lim_{t\to\infty} D^{2n}y(t) = 0$ .

When  $r(t) \neq 1$ , the statement of this lemma is more complicated. We may, however, state a weak analogue.

LEMMA 3'. Let y(t) be a positive solution of (2) on  $[t_0,\infty)$  with  $j \ge 2n + 1 - i$ . Then

$$\lim_{t\to\infty} y_{2n}(t) = \lim_{t\to\infty} (j-1)! (t-t_0)^{1-j} y_{2n+1-j}(t),$$

where  $j = 1, \dots, 2n + 1 - i$ .

Now let y be a  $C_k$ -solution of (2) on  $[T_0, \infty)$  for  $k = 0, \dots, n-1$ . Then  $y_{2n-1}(t) < 0$  for  $t \ge T_0$ . We see then that if  $i \le 2n-1$ ,  $2n-i \ge 1$  and  $2n-i+1 \ge 2$ . Thus, we may let j = 2 in the statement of Lemma 3' to obtain as before that  $\lim_{t\to\infty} y_{2n}(t) = 0$ . It follows that if  $i \le 2n-1$ , the conclusion of Theorem 2 may be restated as: (2) fulfills condition B. Specifically, property  $P_n$  and condition B coincide for the equation

$$D^{n+1}[r(t)D^n y(t)] + y_{\tau}(t)f[t, y_{\tau}(t)] = 0, \qquad n \ge 1$$

since  $i = n \leq 2n - 1$  if  $n \geq 1$ . The same remark holds for

$$D^{n}[r(t)D^{n+1}y(t)] + y_{\tau}(t)f[t, y_{\tau}(t)] = 0, \qquad n \ge 2$$

since  $i = n + 1 \leq 2n - 1$  if  $n \geq 2$ .

REMARK 4. Use of the preliminary transformation Y(t) = -y(t) will enable us to formulate criteria for the nonexistence of negative solutions y of (2) for which -y is of type  $C_k$   $(k = 0, \dots, n)$ . Moreover, if (2) has property  $P_k$ , then there are no negative solutions y such that -y is of type  $C_r$  $(r = k + 1, \dots, n)$  and any negative solution y for which -y is of type  $C_k$  will satisfy  $\lim_{t\to\infty} y_{2k}(t) = 0$ .

3

In this section we consider the nonhomogeneous delay differential equation

(18) 
$$D^{2n+1-i}[r(t)D^{i}y(t)] + y_{\tau}(t)f[t, y_{\tau}(t)] = Q(t).$$

Following the procedure introduced and used most effectively by Kartsatos and Manougian (to appear), we shall assume that R is a solution of the ordinary differential equation

(19) 
$$D^{2n+1-i}[r(t)D^{i}R(t)] = Q(t).$$

This permits the transformation of (18) to a homogeneous delay equation of order 2n + 1 for which the methods of the previous sections may be applied.

order 2n + 1 for which the methods of the previous sections may be applied. Let us assume that y is a positive solution of (18) and let u(t) = y(t) - R(t). Then

$$D^{2n+1-i}[r(t)D^{i}u(t)] = D^{2n+1-i}[r(t)D^{i}y(t)] - D^{2n+1-i}[r(t)D^{i}R(t)]$$
  
=  $-y_{\tau}(t)f[t, y_{\tau}(t)] = -(u+R)_{\tau}(t)f[t, (u+R)_{\tau}(t)],$ 

so that u is a solution of the homogeneous equation

(20) 
$$D^{2n+1-i}[r(t)D^{i}u(t)] + (u+R)_{\tau}(t)f[t,(u+R)_{\tau}(t)] = 0.$$

Since y(t) > 0 for  $t \ge T_0$ ,  $(u + R)_{\tau}(t) > 0$  for  $t \ge T_1$  and  $D^{2n+1-i}[r(t)D^iu(t)] < 0$  for  $t \ge T_1$ , which implies that u(t) is a nonoscillatory solution of (20). If u(t) < 0, then we further transform the equation by letting v(t) = -u(t). It follows that v is a positive solution of

(21) 
$$D^{2n+1-i}[r(t)D^{i}v(t)] - (R-v)_{\tau}(t)f[t,(R-v)_{\tau}(t)] = 0.$$

DEFINITION 8. A positive solution y of (18) is of type  $C_k^R$  on  $[T_0, \infty)$  for  $k = 0, \dots, n$  if u = y - R is a positive solution of (20) of type  $C_k$  on  $[T_0, \infty)$ .

DEFINITION 9. A positive solution y of (18) is of type  $\hat{C}_k^R$  on  $[T_0, \infty)$  for  $k = 0, \dots, n-1$  if v = R - y is a positive solution of (21) which for  $t \ge T_0$  satisfies

 $v_i(t) > 0, i = 0, \dots, 2k + 1$  and  $(-1)^{i+1}v_i(t) > 0, i = 2k + 2, \dots, 2n$ .

It is of type  $\hat{C}_n^R$  if  $v_i(t) > 0$  for  $i = 0, \dots, 2n$ .

DEFINITION 10. Equation (18) has property  $P_k^R$  if, and only if, (20) has property  $P_k$ .

A positive solution of (18) is evidently of type  $C_k^R$   $(k = 0, \dots, n)$  or of type  $\hat{C}_k^R$   $(k = 0, \dots, n)$  for some k. We now formulate criteria under which (18) possesses property  $P_k^R$ .

THEOREM 3. Let R be a solution of (19). Any solution y of type  $C_k^R$  will satisfy

(22) 
$$\lim [y(t) - R(t)]_{2k} = 0$$

if for all positive constants C

(23) 
$$\int_{-\infty}^{\infty} t^{2n-2k} (R_r(t) + Ct^{2k}) f[t, R_r(t) + Ct^{2k}] dt = \infty.$$

**PROOF.** Let y be a solution of (18) of type  $C_k^R$  on  $[T_0, \infty)$ . As in Theorem 1, we obtain

$$\int_{a}^{b} s^{2n-2k} Dy_{2n}(s) ds + \int_{a}^{b} s^{2n-2k} (u+R)_{\tau}(s) f[s, (u+R)_{\tau}(s)] ds = 0.$$

The first integral is handled as in Theorem 1. It remains to estimate the second integral. Since u is of type  $C_k$  on  $[T_0, \infty)$ , there are numbers  $k_0 > 0$ ,  $N_{2k} > 0$ , C > 0 such that

$$u_{\tau}(t) \ge k_0 u(t) \ge k_0 N_{2k}^{-1} t^{2k} u_{2k}(t) \ge k_0 N_{2k}^{-1} C t^{2k}$$

provided we assume that  $\lim_{t\to\infty} u_{2k}(t) = C > 0$ . The above inequalities will lead to the same contradiction as in the proof of Theorem 1.

THEOREM 4. Suppose that R is as in the hypothesis of Theorem 3 and that  $\phi$  is a function satisfying  $\phi(y) > 0$ ,  $\phi'(y) \ge 0$  and (9a). Equation (18) possesses property  $P_k^R$  if in addition to (23) for all positive constants C

(24) 
$$\int_{-\infty}^{\infty} t^{2n} f(t, R_{\tau}(t) + Ct^{2k}) st/\phi(t) = \infty.$$

PROOF. As in the proof of Theorem 2, we first show that

$$\int^{\infty} t^{2n} f(t, R_{\tau}(t) + Ct^{2k-1}) dt / \phi(t) = \infty, \qquad k \ge 1$$

is sufficient to exclude solutions of type  $C_s^R$  ( $s = k, \dots, n$ ). Then

$$\int_{-\infty}^{\infty} t^{2n} f(t, R_{\tau}(t) + Ct^{2k+1}) dt / \phi(t) = \infty, \qquad k \ge 0$$

and hence (24) will exclude solutions of (18) of type  $C_s^R$  ( $s = k + 1, \dots, n$ ). The details are left to the reader.

**REMARK** 5. If R(t) > 0, the condition of Theorem 3 may be replaced by

(25) 
$$\int_{-\infty}^{\infty} t^{2n} f(t, Ct^{2k}) dt = \infty.$$

The same replacement in Theorem 4 may be made. Thus (25) will ensure that (18) has property  $P_{k}^{R}$ .

**REMARK** 6. If R is oscillatory or negative, there can be no solutions of (18) of type  $\hat{C}_{k}^{R}$ . The conclusion of Theorem 4 is thereby strengthened.

REMARK 7. Use of the transformation  $w_k(t) = y_{2n}(t)y_{2k-1}^{-1}(t)$  results in a stronger criterion for the nonexistence of  $C_k^R$ -solutions of (18) independent of the existence of an auxiliary function  $\phi(t)$  satisfying the hypotheses of Theorem 4. Specifically, we may obtain:

THEOREM 5. Let R be a solution of (19) with  $R(t) = 0(t^{2k-1-\epsilon})$  for some  $\epsilon$  such that  $0 < \epsilon < 2k-1$ ; (18) has no positive solutions of type  $C_s^R$  (s = k,...,n) if for all positive constants C

466

Delay differential equations

$$\int_{-\infty}^{\infty} t^{2k-1}f(t,R_{\tau}(t)+Ct^{2k-1})dt = \infty.$$

REMARK 8. As in Remark 4, the preliminary transformation Y(t) = -y(t) will enable us to formulate analogous criteria for the nonexistence of certain negative solutions y of (18) for which -y is a positive  $C_k^{-R}$ -solution of the transformed non-homogeneous delay differential equation.

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