

THE λ -PROPERTY IN SCHREIER'S SPACE S AND THE LORENTZ SPACE $d(a, 1)$

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0. Abstract. We add Schreier's space S and the Lorentz space $d(a, 1)$ to the list of classical Banach spaces which enjoy the λ -property, investigate the extreme point structure of S , and show that $d(a, 1)$ has a λ -function which is continuous on $S_{d(a,1)}$, though not even uniformly so.

1. Introduction. Let X be a Banach space, B_X the unit ball of X , S_X the surface of B_X , and $\text{ext } B_X$ the set of extreme points of B_X . For points $x, y \in X$, we write $[x, y]$ for $\{\lambda x + (1 - \lambda)y : 0 < \lambda \leq 1\}$.

DEFINITION 1.1. (a) X has the λ -property, if for each $x \in B_X$, there exists $e \in \text{ext } B_X$, $y \in B_X$, $0 < \lambda \leq 1$ such that

$$x = \lambda e + (1 - \lambda)y.$$

In this case we say that the triple (e, y, λ) is *amenable* to x , and write $(e, y, \lambda) \sim x$.

(b) If X has the λ -property, for each $x \in B_X$, we define

$$\lambda(x) := \sup\{\lambda : (e, y, \lambda) \sim x\}.$$

(c) If there exists $\lambda_0 > 0$ such that $\lambda(x) \geq \lambda_0$, for all $x \in B_X$, we say that X has the *uniform λ -property*.

(d) Finally, we say that X has the *convex series representation property* (C.S.R.P.), if for each $x \in B_X$, there exist $\lambda_n \geq 0$, $e_n \in \text{ext } B_X$, ($n = 1, 2, \dots$), such that $x = \sum_n \lambda_n e_n$ and $\sum_n \lambda_n = 1$.

These notions were developed by R. Aron and R. H. Lohman in [1], where (among other results) they proved: the uniform λ -property implies C.S.R.P. An easy exercise shows that C.S.R.P. implies the λ -property. Spaces that enjoy either the λ -property or the uniform λ -property are not rare [1], [3], [4], [8], and it is our belief that some strong theorems are lurking behind these concepts. In an attempt to better understand these properties we decided to investigate a couple of "exotic" sequence spaces. We begin with Schreier's space S .

2. Schreier's space S .

DEFINITION 2.1. (a) Let $R^{(N)}$ denote the (vector) space of real sequences $x = (x(1), x(2), \dots)$ which are finitely-non-zero (i.e., have "finite support"). A subset E of the natural numbers N is *admissible*, if $E = \{n_1, n_2, \dots, n_k\}$, with $k \leq n_1 < n_2 < \dots < n_k$. We denote by \mathcal{A} the collection of all admissible subsets of N .

(b) For $x \in R^{(N)}$, we define

$$\|x\|_S := \sup_{E \in \mathcal{A}} \sum_{j \in E} |x(j)|.$$

(Routine calculations show that $\|\cdot\|_S$ is a norm on $R^{(N)}$.)

(c) *Schreier's space* S is the $\|\cdot\|_S$ -completion of $R^{(\mathbb{N})}$. (From here on, we will write “ $\|\cdot\|$ ”, for $\|\cdot\|_S$ ”.)

The space S has been studied extensively in [2], where it is shown that S is hereditarily- c_0 ; (hence l_1 does not embed in it). In this section we shall show that S has enough extreme points to enjoy C.S.R.P., even though we fall short of a useful characterization of $\text{ext } B_S$. First we note that S is not c_0 in disguise.

PROPOSITION 2.2. *S is not isomorphic to c_0 .*

Proof. If we denote by $\{s_n\}_{n=1}^\infty$ the canonical unit vector basis for S , then for each n , l_1^n is isometric to the norm-one complemented subspace of S spanned by $\{s_i : n + 1 \leq i \leq 2n\}$. Thus (see [6, p. 74]) S^* fails to have finite co-type. Hence S^* is not isomorphic to c_0^* , and so S is not isomorphic to c_0 .

For each n , let $S_n := \text{span}\{s_i : i \leq n\}$. Since S_n is finite-dimensional, $\text{ext } B_n \neq \emptyset$ (where $B_n := B_{S_n}$). In fact we shall show that

$$\text{ext } B_n \cap \text{ext } B_S \neq \emptyset.$$

The reader can easily show (by using 1-sets introduced below) that the vectors $(1, 1)$, $(1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2})$, and $(1, \frac{2}{3}, \frac{1}{3}, \frac{1}{3}, \frac{1}{3}, \frac{1}{3})$ are all in $\text{ext } B_S$ (when we write $x = (x(1), x(2), \dots, x(n))$, we mean $x(j) = 0$ when $j > n$).

DEFINITION 2.3. Let $x \in B_S$.

(a) If $E \in \mathcal{A}$, and $\sum_{j \in E} |x(j)| = 1$, we say that E is a 1-set for x .

(b) If (in addition) $E = \{n_1 < n_2 < \dots < n_k\}$ and $k < n_1$, we say E is a non-maximal 1-set, for x .

Since for $E \in \mathcal{A}$, $x \rightarrow \sum_{j \in E} |x(j)|$ is a semi-norm, we clearly have the following result.

LEMMA 2.4. *Let $x, b, c \in B_S$ with $x = \lambda b + (1 - \lambda)c$ for some $0 < \lambda < 1$. Then any 1-set for x is a 1-set for b and c .*

A slight modification of the above shows that for vectors x, b_1, b_2, \dots in B_S and scalars $\lambda_1, \lambda_2, \dots$ each > 0 with $\sum_n \lambda_n = 1$ and $x = \sum_n \lambda_n b_n$, every 1-set for x is a 1-set for each b_n .

LEMMA 2.5. *Let $n \geq 1$ and $x \in \text{ext } B_n$. If x has a non-maximal 1-set E , then $x \in \text{ext } B_S$.*

Proof. Clearly we may assume that $\max E \leq n$. Suppose $x = \lambda b + (1 - \lambda)c$, for some $0 < \lambda < 1$ and some $b, c \in B_S$. If E is a non-maximal 1-set for x , then, by Lemma 2.4, E is a non-maximal 1-set for b and c . So $b(j) = 0 = c(j)$, for $j > n$, since $E \cup \{j\} \in \mathcal{A}$ for every $j > n$. But $x(j) = b(j) = c(j)$ for $j \leq n$, since $x \in \text{ext } B_n$. Thus $x = b = c$, and $x \in \text{ext } B_S$.

We note that $\text{ext } B_n \not\subset \text{ext } B_S$. Some calculations show that $(1, \frac{1}{2}, \frac{1}{3}, \frac{1}{3}, \frac{1}{3}) \in \text{ext } B_5 \sim \text{ext } B_S$, for instance. To show that S has C.S.R.P. we need some lemmata about certain representations.

LEMMA 2.6. *Let $x \in B_S$. Then for all $\epsilon > 0$, there exists N such that for $E \in \mathcal{A}$ with $N < \min E$, we have $\sum_{j \in E} |x(j)| < \epsilon$.*

Proof. If $x \in B_S$, then $\|x - y\| < \epsilon$ for some finite vector $y \in B_S$.

LEMMA 2.7. *Let $x \in B_S$ have infinite support. Then there exist vectors $b, c \in B_S$ such that $x = \frac{1}{2}b + \frac{1}{2}c$, and b has finite support.*

Proof. Without loss of generality we may assume $\|x\| = 1$. Let

$$\alpha := \min\{|x(j)| : j \in E \in \mathcal{A}, E \text{ is a 1-set for } x, x(j) \neq 0\},$$

and

$$\epsilon := \min\left\{1 - \sum_{j \in E} |x(j)| : E \in \mathcal{A}, \sum_{j \in E} |x(j)| < 1\right\}.$$

Lemma 2.6 implies that $\epsilon > 0$. Choose an integer M larger than any element in any 1-set for x and larger than any element in any $E \in \mathcal{A}$ which determines ϵ . Finally, enlarge M (if needed) so that for $E \in \mathcal{A}$, $\min E \geq M$ implies

$$\sum_{j \in E} |x(j)| < \frac{1}{2} \min\{\alpha, \epsilon\}.$$

Now define vectors b and c by

$$\begin{cases} b(j) = x(j) = c(j), & \text{for } 1 \leq j < M, \\ b(j) = 0, & \text{for } j \geq M, \\ c(j) = 2x(j), & \text{for } j \geq M. \end{cases}$$

The only thing left to show is that $c \in B_S$. Towards this end, let $E \in \mathcal{A}$. If $\max E < M$, then $\sum_{j \in E} |c(j)| \leq \|x\| = 1$. If $\max E \geq M$, then

$$\sum_{j \in E} |c(j)| = \sum_{\substack{j \in E \\ j < M}} |c(j)| + \sum_{\substack{j \in E \\ j \geq M}} |c(j)| < 1 - \epsilon + 2 \cdot \frac{\epsilon}{2} = 1.$$

Note that for $x \in B_S$, applying the above Lemma recursively we obtain a representation $x = \sum_i 2^{-i} b_i$, where each $b_i \in B_S$ and each b_i has finite support. Also note that we immediately obtain the following result.

COROLLARY 2.8. *If $x \in \text{ext } B_S$, then x has finite support.*

In fact, we can show more.

LEMMA 2.9. *Let $x \in B_S$ have finite support. Then x can be represented as $x = \frac{1}{2}b + \frac{1}{2}c$, for two vectors $b, c \in B_S$ each of finite support, and each having a non-maximal 1-set.*

Proof. Without loss of generality, we may assume $x \neq 0$. Let $N = \max(\text{support } x) + 1$, and let $\epsilon = \min\left\{1 - \sum_{j \in E} |x(j)| : E = \{n_1, \dots, n_k\}, k < n_1 < N\right\}$. (If $\epsilon = 0$, then x already has a non-maximal 1-set, and we can choose $b = c = x$.) Choose $M > N$ such that $\frac{N-2}{M} < \epsilon$. (The case where $N \leq 2$ is trivial.)

Define vectors b and c via

$$\begin{cases} b(j) = x(j) = c(j), & \text{for } 1 \leq j \leq M, \\ b(j) = 0 = c(j), & \text{for } j > 2M, \\ b(j) = \frac{1}{M} = -c(j), & \text{for } M + 1 \leq j \leq 2M. \end{cases}$$

Clearly, $x = \frac{1}{2}b + \frac{1}{2}c$, and $\|b\| = \|c\|$.

To show that $\|b\| \leq 1$, let $E \in \mathcal{A}$. If $\min E \geq N$, then $\sum_{j \in E} |b(j)| \leq M \cdot \frac{1}{M} = 1$. If $\max E < N$, then $\sum_{j \in E} |b(j)| = \sum_{j \in E} |x(j)| \leq 1$. In the only remaining case

$$\begin{aligned} \sum_{j \in E} |b(j)| &= \left(\sum_{\substack{j \in E \\ j < N}} + \sum_{\substack{j \in E \\ j \geq N}} \right) |b(j)| \\ &\leq 1 - \varepsilon + \frac{N - 2}{M} < 1. \end{aligned}$$

So $\|b\| = \|c\| = 1$, and each has $\{M + 1, M + 2, \dots, 2M\}$ for a non-maximal 1-set.

THEOREM 2.10. *Schreier's space S has C.S.R.P.*

Proof. Let $x \in B_S$. By the remark following Lemma 2.7, we may write $x = \sum_n 2^{-n} b_n$, where $\|b_n\| = 1$ and support b_n is finite, ($n = 1, 2, \dots$). Using Lemma 2.9 on each b_n , we can write $x = \sum_j \lambda_j c_j$, for some choices of λ_j and c_j such that $\sum_j \lambda_j = 1$, $\|c_j\| = 1$, and each vector c_j has finite support and a non-maximal 1-set. Now each vector c_j belongs to some S_n , where $n := n(j)$. Since S_n has C.S.R.P. [2], for each j we can write $c_j = \sum_i \lambda_{j,i} e_{j,i}$, a convex series where the $e_{j,i} \in \text{ext } B_n$. Finally $x = \sum_{i,j} \lambda_{j,i} e_{j,i}$, and the vectors $e_{j,i}$ all belong to $\text{ext } B_S$, by Lemmas 2.4 and 2.5.

This of course implies that S has the λ -property although we do not know whether it has the uniform λ -property. We mention here that the extreme points of B_S all have supports with even cardinality (we omit the proof). It is of interest to note the following result.

PROPOSITION 2.11. *ext B_S is countable.*

Proof. The earlier lemmas show that $\text{ext } B_S \subset \bigcup_n \text{ext } B_n$. We now show that each $\text{ext } B_n$ is finite. Since B_n is compact, it suffices to show that for each $x \in B_n$, there is a ball (in the B_n topology) of radius $\epsilon = \epsilon(x)$ such that this ball meets $\text{ext } B_n$ (at most) at the point x . Let $x \in B_n$, and assume $\|x\| = 1$. Define

$$\delta_1 = \min\{|x(j)| : x(j) \neq 0\},$$

$$\delta_2 = \min\left\{1 - \sum_{j \in E} |x(j)| : E \in \mathcal{A} \text{ and } \sum_{j \in E} |x(j)| < 1\right\}.$$

Let $\delta = \frac{1}{2} \min\{\delta_1, \delta_2\}$, and choose $\epsilon > 0$ so that $2n\epsilon < \delta$.

Suppose $y \in B_n$ with $\|x - y\| < \epsilon$. Note that by choice of ϵ , whenever $x(j) \neq 0$, $x(j)$

and $y(j)$ have the same sign. Now define z by

$$z(j) = \begin{cases} 0, & \text{if } j > n, \\ 2y(j) - x(j), & \text{if } j \leq n. \end{cases}$$

Clearly $z \in S_n$ and $y = \frac{1}{2}x + \frac{1}{2}z$. If we can show $z \in B_n$, then $y \notin \text{ext } B_n$, unless $y = x$ and $x \in \text{ext } B_n$. Note that ϵ was chosen small enough so that $x(j)$, $y(j)$, and $z(j)$ have the same sign as j ranges over the support of x . So for all j , we have

$$\begin{aligned} x(j) - z(j) &= 2(x(j) - y(j)), \\ |x(j)| - |z(j)| &= 2(|x(j)| - |y(j)|). \end{aligned}$$

Letting $E \in \mathcal{A}$, we may assume $E \subset \{1, \dots, n\}$. If E is not a 1-set for x , then

$$\sum_{j \in E} |z(j)| \leq \sum_{j \in E} |x(j)| + 2n\epsilon < 1.$$

If E is a 1-set for x , then letting $E_0 = \{j \in E : x(j) = 0\}$, and $E_1 = E \setminus E_0$, we have

$$\begin{aligned} \sum_{j \in E} |z(j)| &= \sum_{j \in E_1} |z(j)| + \sum_{j \in E_0} |z(j)| \\ &= \sum_{j \in E_1} |x(j)| - \sum_{j \in E_1} (|x(j)| - |z(j)|) + \sum_{j \in E_0} |z(j)| \\ &= \sum_{j \in E_1} |x(j)| - 2 \sum_{j \in E_1} (|x(j)| - |y(j)|) + 2 \sum_{j \in E_0} |y(j)| \\ &= 2 \sum_{j \in E} |y(j)| - \sum_{j \in E_1} |x(j)| \leq 1. \end{aligned}$$

Thus $\|z\| \leq 1$.

3. The Lorentz sequence space $d(a, 1)$. We consider here Lorentz sequence spaces of type $d(a, 1)$. These ‘‘weighted’’ versions of l_1 turn out to have the λ -property, while failing the uniform λ -property. This was demonstrated in Theorems 5 and 6 in [8], both of which we improve here by producing the exact form of the λ -function for norm-one vectors. This is then used to prove a continuity result. First we establish some definitions and notation.

DEFINITION 3.1. Let $a = (a_n) \in c_0 \setminus V_1$ be a positive strictly decreasing sequence with $a_1 = 1$. The space $d(a, 1)$ consists of all real sequences $x = (x(n)) \in c_0$ such that $\sup \sum |x(\pi(n))| a_n < \infty$, where the supremum is taken over all permutations π of the natural numbers. (If $\|x\|$ is taken to be this supremum, then $d(a, 1)$ is a Banach space.)

If $x = (x(n)) \in d(a, 1)$, and $x \neq 0$, we write

$$\begin{aligned} M_1(x) &= \|x\|_\infty, \quad \text{and} \quad F_1(x) = \{n : |x(n)| = M_1(x)\}, \\ M_2(x) &= \|x - x c_{F_1(x)}\|_\infty, \quad F_2(x) = \{n : |x(n)| = M_2(x)\}, \end{aligned}$$

where $c_{F_1(x)}$ is the characteristic function of $F_1(x)$, etc. Then $M_k(x) \downarrow 0$, and if $M_k(x) > 0$, then $M_k(x) > M_{k+1}(x)$. Also $F_k(x)$ and $F_j(x)$ are disjoint if $M_k(x), M_j(x) > 0$ and $k \neq j$. Let $N(x) = \{k : M_k(x) - M_{k+1}(x) > 0\}$, and for $k \in N(x)$, define $n_k(x) = \text{card} \left(\bigcup_{i=1}^k F_i(x) \right)$, and

$$s_k(x) = \sum_{n=1}^{n_k(x)} a_n.$$

If we let $n_0(x) = 0$, then we can write $\|x\|$ as

$$\|x\| = \sum_{k \in N(x)} M_k(x) \cdot (s_k(x) - s_{k-1}(x)).$$

Importantly, for $x \in d(a, 1)$, $\|x\|$ can also be realized in another way.

PROPOSITION 3.2. For any $x \in d(a, 1)$,

$$\|x\| = \sum_k M_k(x) \cdot [s_k(x) - s_{k-1}(x)] = \sum_n [M_n(x) - M_{n+1}(x)] \cdot s_n(x).$$

Proof. It suffices to note that either sum is equal to

$$\sum_k \sum_{j \geq k} (M_k(x) - M_{k+1}(x))(s_j(x) - s_{j-1}(x))$$

The extreme points of $B_{d(a,1)}$ were characterized by W. J. Davis [10].

PROPOSITION 3.3. $e \in \text{ext } B_{d(a,1)}$ if and only if e has the form

$$e = \left(\sum_{n=1}^k a_n \right)^{-1} \left(\sum_{n=1}^k \epsilon_n x_{i_n} \right),$$

for some integer k , $i_1 < i_2 < \dots < i_k$, and signs $\epsilon_1, \epsilon_2, \dots, \epsilon_k$, (where (x_i) is the canonical unit vector basis of $d(a, 1)$.)

Using this characterization, we can establish the following result.

PROPOSITION 3.4. The space $d(a, 1)$ has C.S.R.P.

Proof. Assume first that $\|x\| = 1$, and that x has the form

$$x = (x(1) \geq x(2) \geq \dots \geq x(k) > 0).$$

For any j , define $s_j = \sum_{i=1}^j a_i$, and denote by e_m that extreme point with non-negative coefficients and support = $\{1, 2, \dots, m\}$. Further denote by v^n that vector defined by $v^n(i) = 1$, if $1 \leq i \leq n$, and 0, otherwise. Then

$$\begin{aligned} x &= (x(1), x(2), \dots, x(k), 0, \dots) \\ &= x(k) \cdot v^k + (x(1) - x(k), \dots, x(k-1) - x(k), 0, \dots) \\ &= \dots = x(k)v^k + (x(k-1) - x(k))v^{k-1} \\ &\quad + (x(k-2) - x(k-1))v^{k-2} + \dots + (x(2) - x(3))v^2 + (x(1) + x(2))v^1 \\ &= [x(k)s_k]e_k + [(x(k-1) - x(k))s_{k-1}]e_{k-1} \\ &\quad + [(x(k-2) - x(k-1))s_{k-2}]e_{k-2} + \dots \\ &\quad + [(x(2) - x(3))s_2]e_2 + [(x(1) - x(2))s_1]e_1. \end{aligned}$$

Let $\alpha_l = (x(l) - x(l+1))s_l$, ($l = k, k-1, \dots, 2, 1$) and note that

$$\begin{aligned} \alpha_k + \alpha_{k-1} + \dots + \alpha_1 &= x(k)(s_k - s_{k-2}) + x(k-1)(s_{k-1} - s_{k-2}) \\ &\quad + \dots + x(2)(s_2 - s_1) + x(1)s_1 \\ &= x(k)a_k + x(k-1)a_{k-1} + \dots + x(2)a_2 + x(1)a_1 \\ &= \|x\| = 1. \end{aligned}$$

Now assume that $\|x\| = 1$ and that x has the form $x = (x(1) \geq x(2) \geq \dots > 0)$. Then (using the notation above) $1 = \|x\| = \lim_k \sum_{i=1}^k a_i x(i) = \lim_k \sum_{i=1}^k \alpha_i$. Arbitrary vectors x with $\|x\| = 1$ are an isometry away from the two cases already considered, and if $\|x\| < 1$,

$$x = \|x\| \cdot \frac{x}{\|x\|} + \frac{1 - \|x\|}{2} \cdot e + \frac{1 - \|x\|}{2} (-e)$$

(where e is any extreme point), leads to a convex series representation.

Proposition 3.4 implies that $d(a, 1)$ has the λ -property, but we can say more. In [8] a lower bound is proven for the λ -function.

$$\text{If } x \in B_{d(a,1)}, x \neq 0, \text{ then } \lambda(x) \geq \sup_{k \in N(x)} [M_k(x) - M_{k+1}(x)]s_k(x). \quad (*)$$

In the same paper an exact formula is given for unit vectors of finite support.

If $x \in d(a, 1)$ with $\|x\| = 1$, and support x is finite, then

$$\lambda(x) = \max_{k \in N(x)} [M_k(x) - M_{k+1}(x)]s_k(x). \quad (**)$$

Proposition 3.2 allows us to replace the ‘sup’ in (*) by a ‘max’, and we can now remove the hypothesis about support x in (**).

Using the results above, we can also establish the following theorems.

THEOREM 3.5. Assume $x \in d(a, 1)$, $\|x\| = 1$. Then

$$\lambda(x) = \max_n [M_n(x) - M_{n+1}(x)] \cdot s_n(x)$$

THEOREM 3.6. The λ -function for $d(a, 1)$ is continuous on $\{x : \|x\| = 1\}$, Lipschitz-continuous on $\{x : \|x\| \leq r\}$, ($0 < r < 1$), though not even uniformly continuous on $\{x : \|x\| = 1\}$.

Consideration of space forces us to omit proofs of these last two results, which will appear in [9].

REMARK. R. H. Lohman [7] has recently shown that for Banach spaces the λ -property is equivalent to the C.S.R.P.

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