MULTIGRID METHODS FOR THE BIHARMONIC EQUATION USING SOME NONCONFORMING PLATE ELEMENTS

LIMING MA¹ and QIANSHUN CHANG²

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Abstract

In this paper, multigrid methods for solving the biharmonic equation using some nonconforming plate elements are considered. An average algorithm is applied to define the transfer operator. A general analysis of convergence is given.

1. Introduction

The biharmonic equation is a typical elliptic equation of order four and possesses important theoretical value. The biharmonic equation is a basic mathematical model in structure mechanics and is used in the blending problem, image restoration, domain transforms, and so forth. In the blending problem, given two frame surfaces (or bodies) already located, a smoothly transferring surface is sought to connect the two frame surfaces along a certain boundary. Usually, the "smoothness" means that the blending surface and its tangent plane are continuous until the joint boundary. Thus, the displacement vector of the blending surface satisfies the biharmonic equation. In general, the nonconforming finite element method is applied in solving the biharmonic problem, since the degrees of freedom in each element, and hence the computational complexity, can be reduced.

Multigrid methods are very efficient iterative solvers for systems of algebraic equations arising from finite element and finite difference discretizations of elliptic boundary value problems. In recent years, multigrid methods of nonconforming plate elements have been studied (see, for example, [4, 9]). But, because the finite element spaces associated with nonconforming elements are not nested, that is, $V_{k-1} \not\subset V_k$, it is difficult to define the transfer operator in the multigrid method of some

¹Graduate School, Academia Sinica, Beijing 100039, China.

²Academy of Mathematics and Systems Sciences, The Chinese Academy of Sciences, Beijing 100080, China; e-mail: qschang@public.fhnet.cn.net.

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nonconforming plate elements, such as the Adini rectangular element, the Morley element, the complete cubic nonconforming element and the Zienkiewicz triangular element. S. C. Brenner (see [4]) has used the idea of taking averages in defining the transfer operator I_{k-1}^{k} for the Morley element. In this paper, we extend this idea to some of the nonconforming finite elements mentioned above and give a simpler convergence proof than Brenner's.

We know that the complete cubic nonconforming plate element is of the same convergence order as the Morley nonconforming element and the Adini element. However, the cubic element has two degrees of freedom fewer than that of the Adini element. Moreover, we can get the convergence order to be $O(h^2)$ when the compensation method is used. So we apply the complete cubic nonconforming plate element to develop an optimal-order multigrid method for the biharmonic equation in this paper.

The paper is organized as follows. We begin with a discussion of the complete cubic nonconforming plate element. In Section 3, the intergrid transfer operator is defined and its two properties are proved. The multigrid algorithm is given in Section 4. In the last section, the error order of the multigrid method is obtained.

2. The nonconforming complete cubic plate element

We consider the plate blending problem with clamped boundary condition

$$\begin{cases} \Delta^2 u = f & \text{in } \Omega, \\ u = \partial u / \partial n = 0 & \text{on } \partial \Omega, \end{cases}$$
(2.1)

where u denotes displacement, $f \in H^{-l}(\Omega)$, l = 0 or 1 and is the loading force, Ω is a rectangular domain and n is the outward normal direction of boundary $\partial \Omega$.

The boundary value problem (2.1) has a unique solution $u \in H^{4-l}(\Omega) \cap H_0^2(\Omega)$, which satisfies the following elliptic regularity (see [1]):

$$\|u\|_{H^{4-l}(\Omega)} \le C(\Omega) \|f\|_{H^{-l}(\Omega)}.$$
(2.2)

The problem (2.1) can be associated with the following variational problem: Find $u \in H_0^2(\Omega)$, such that

$$a(u, v) = (f, v), \qquad \forall v \in H_0^2(\Omega), \tag{2.3}$$

where

$$a(u, v) = \int_{\Omega} (\Delta u \Delta v + (1 - \sigma)(2u_{xy}v_{xy} - u_{xx}v_{yy} - u_{yy}v_{xx})) dx, \quad (f, v) = \int_{\Omega} f v dx,$$

and $0 < \sigma < 1/2$ is the Possion ratio.

The problem (2.3) is discretized by the complete cubic nonconforming plate elements. Let $\{\tau_k\}, k \ge 1$, be a family of rectangular elements of Ω , where τ_{k+1} is obtained by connecting the midpoints of the edges of the rectangular elements in τ_k . Then we have $h_k = \max\{\text{diam } T, T \in \tau_k\} = 2h_{k+1}$.

Let V_k be the complete cubic nonconforming plate element space associated with τ_k . Then $v \in V_k$ possesses the following properties:

(i) $v|_T$ is a cubic polynomial for all $T \in \tau_k$;

(ii) the degrees of freedom are the values of the functions at the vertices of the rectangular $T \in \tau_k$ and the normal derivatives at the midpoints of the edges and the mean values of two derivatives of the third order;

(iii) v and $\partial v/\partial n$ vanish at the vertices and the midpoints on $\partial \Omega$, respectively.

Note that $V_{k-1} \not\subset V_k$ (that is, V_k is nonnested) and $V_k \not\subset H_0^2$ (that is, V_k is nonconforming).

The discrete problem of (2.3) is: Given $f \in L^2(\Omega)$, find $u_k \in V_k$, satisfying

$$a_k(u_k, v) = (f, v), \qquad \forall v \in V_k, \tag{2.4}$$

where

$$a_k(u, v) = \sum_{T \in \tau_k} \int_T (\Delta u \Delta v + (1 - \sigma)(2u_{xy}v_{xy} - u_{xx}v_{yy} - u_{yy}v_{xx})) dx$$

and

$$(f, v) = \sum_{T \in \tau_k} \int_T f v \, dx$$

Define the mesh-dependent energy norm as

$$\|v\|_k := \sqrt{a_k(v, v)}, \qquad \forall v \in V_k.$$

From [3], we have

$$\|u - u_k\| \le C(h_k |u|_{H^3} + h_k^2 |f|_4).$$
(2.5)

Thus, we modify the problem (2.4) to take the following form: Find $u_k^* \in V_k$, such that

$$a_k(u_k^*, v) = (f, v'), \qquad \forall v \in V_k, \tag{2.6}$$

where v' is a linear interpolation of v.

It is easy to prove the inequality

$$\|u - u_k^*\|_k \le Ch_k |u|_{H^3}. \tag{2.7}$$

Note that we don't need to make the above modification for the Zienkiewicz element and the Adini element, since $V_k \subset C^0(\overline{\Omega})$. In this paper, C denotes a generic positive constant, which may have different values in different occurrences.

3. The intergrid transfer operator and its properties

The intergrid operator $I_{k-1}^k : V_{k-1} + H^3(\Omega) \cap H_0^2(\Omega) \mapsto V_k$ is defined as follows. For $v \in V_{k-1} + H^3(\Omega) \cap H_0^2(\Omega)$,

(i) Let A be a vertex of element $T \in \tau_k$ inside Ω . If A is also a vertex of τ_{k-1} , then

$$(I_{k-1}^k v)(A) := v(A).$$

If A is the midpoint of the common edges of two rectangular elements T_1 and T_2 in τ_{k-1} , then

$$(I_{k-1}^{k}v)(A) := \frac{1}{2} [v|_{T_{1}}(A) + v|_{T_{2}}(A)].$$

If A is in the interior of a rectangular in τ_{k-1} , then

$$(I_{k-1}^k v)(A) := v|_{\tau_{k-1}}(A).$$

(ii) If the midpoint B of an edge in an element of τ_k is located in the interior of a rectangular in τ_{k-1} , then

$$\frac{\partial(I_{k-1}^k v(B))}{\partial n} := \frac{\partial v}{\partial n} \bigg|_{\tau_{k-1}} (B).$$

If **B** is on the common edges of two elements T_1 and T_2 in τ_{k-1} then

$$\frac{\partial (I_{k-1}^k v(B))}{\partial n} := \frac{1}{2} \left[\left. \frac{\partial v}{\partial n} \right|_{T_1} (B) + \left. \frac{\partial v}{\partial n} \right|_{T_2} (B) \right].$$

(iii) $I_{k-1}^k v := 0$ at the vertices of τ_k along $\partial \Omega$ and $\partial (I_{k-1}^k v) / \partial n = 0$ at the midpoints of the edges of $T \in \tau_k$ along $\partial \Omega$.

(iv) Let

$$\int_T \frac{\partial^3 (I_{k-1}^k v)}{\partial x_1^3} dx_1 dx_2 = \int_T \frac{\partial^3 v}{\partial x_1^3} dx_1 dx_2$$

and

$$\int_T \frac{\partial^3 (I_{k-1}^k v)}{\partial x_2^3} \, dx_1 dx_2 = \int_T \frac{\partial^3 v}{\partial x_2^3} \, dx_1 dx_2, \quad T \in \tau_k.$$

Thus, we have the following two lemmas.

LEMMA 3.1 (Stability Property). For any $v \in V_{k-1} + H^3(\Omega) \cap H^2_0(\Omega)$, there exists a constant C independent of h_k , such that

$$\|I_{k-1}^{k}v\|_{k} \leq C\|v\|_{k-1}.$$

PROOF.

$$I_{k-1}^{k}v = (I_{k-1}^{k}v - \pi_{k}v) + (\pi_{k}v - v) + v$$

where π_k is an interpolation operator from $H^3(\Omega) \cap H^2_0(\Omega)$ to V_k . Thus, one gets

$$\|I_{k-1}^{k}v\| \leq \|I_{k-1}^{k}v - \pi_{k}v\|_{k} + \|\pi_{k}v - v\|_{k} + \|v\|_{k-1}.$$
(3.1)

Using the interpolation theorem of Sobolev space and the inverse inequality, we obtain

$$\|v - \pi_k v\|_k \le C \|v\|_{k-1}. \tag{3.2}$$

So, the key step is to estimate $||I_{k-1}^k v - \pi_k v||_k$.

From the definition of $\pi_k v$ and $I_{k-1}^k v$, we see

$$\begin{aligned} (\pi_{k}v - I_{k-1}^{k}v)|_{T} &= \frac{N_{2}}{2} \Big(v(A_{2})|_{T_{1}} - v(A_{2})|_{T_{2}} \Big) + \frac{N_{4}}{2} \Big(v(A_{4})|_{T_{1}} - v(A_{4})|_{T_{2}} \Big) \\ &+ \frac{M_{2}}{2} \left(\frac{\partial v(B_{2})}{\partial n} \Big|_{T_{1}} - \frac{\partial v(B_{2})}{\partial n} \Big|_{T_{3}} \right) + \frac{M_{4}}{2} \left(\frac{\partial v(B_{4})}{\partial n} \Big|_{T_{1}} - \frac{\partial v(B_{4})}{\partial n} \Big|_{T_{3}} \right), \end{aligned}$$

where $T \in \tau_k$, T_i (i = 1, 2, 3) are three neighboring elements in τ_{k-1} , M_i and N_i (i = 2, 4) are the shape functions, A_i (i = 1, 2, 3, 4) are the vertices of T and B_i (i = 1, 2, 3, 4) are the midpoints of the edges of the element T.

Applying the Bramble-Hilbert lemma and

$$\left|\frac{\partial^2 M_i}{\partial x_i \partial x_j}\right| \le Ch_k^{-1}, \quad \left|\frac{\partial^2 N_i}{\partial x_i \partial x_j}\right| \le Ch_k^{-1}, \quad i, j, = 1, 2,$$

the following inequality holds:

$$\left|\pi_{k}v-I_{k-1}^{k}v\right|_{2,T}\leq C\left(|v|_{2,T_{1}}+|v|_{2,T_{2}}+|v|_{2,T_{3}}\right).$$

Summing the above inequality for $T \in \tau_k$, we get

$$\|\pi_k v - I_{k-1}^k v\|_k \le C \|v\|_{k-1}.$$
(3.3)

Lemma 2.1 follows from inequalities (3.1)-(3.3).

LEMMA 3.2 (Approximation Property). For any $v \in V_{k-1} + H^2(\Omega) \cap H^2_0(\Omega)$, there exists a constant C such that

$$\|v' - (I_{k-1}^k v)'\|_{H^1} \le Ch_k \|v\|_{k-1}$$

and

$$\|\pi_k w - I_{k-1}^k(\pi_{k-1}w)\|_k \le Ch_k \|w\|_{H^3}, \quad \forall w \in H^3(\Omega) \cap H^2_0(\Omega).$$

PROOF. The first inequality can be obtained as Corollary 1 in [4]. Using Lemma 2.1, the interpolation theorem in Sobolev space and

$$\pi_k w = I_{k-1}^k w, \quad \forall w \in H^3(\Omega) \cap H_0^2(\Omega),$$

the second inequality is obtained. Thus, the result of Lemma 2.2 is proved.

4. The multigrid algorithm

From the spectral theorem, there exist eigenvalues $0 \le \lambda_1 \le \lambda_2 \le \cdots \le \lambda_{N_k}$ and eigenfunctions $\phi_1, \phi_2, \ldots, \phi_{N_k}$, such that

$$a_k(\phi_i, v) = \lambda_i(\phi_i, v), \quad \forall v \in V_k,$$

and $(\phi_i, \phi_j) = \delta_{ij}$ (the Kronecker Delta). By the inverse inequality (see [7]) we have

$$\lambda_{n_k} \le C h_k^4. \tag{4.1}$$

Assuming $v = \sum_{i=1}^{N_k} c_i \phi_i$, the norm $||| \cdot |||_{s,k}$ is defined as follows:

$$|||v|||_{s,k}^2 := \sum_{i=1}^{N_k} \lambda_i^{s/2} c_i^2, \quad s \in R.$$

Obviously, $|||v|||_{0,k} = ||v||_{L^2}$ and $|||v|||_{2,k} = ||v||_k$.

Let z_0 be an initial guess value of the solution. Then an approximate solution $MG(k, z_0, G)$ of the multigrid algorithm is defined by the following problem: Find $z \in V_k$, such that

$$a_k(z, v) = G(v), \quad \forall v \in V_k, \quad G \in V_k', \tag{4.2}$$

where V_k denotes the conjugate space of V_k .

For k = 1, $MG(1, z_0, G)$ is the solution of (4.2) obtained from a direct method. For k > 1, $MG(k, z_0, v) := z_m + I_{k-1}^k q_p$, where z_m can be obtained by m smoothing steps:

$$(z_i - z_{i-1}, v) = \Lambda_k^{-1}(G(v) - a_k(z_{i-1}, v)), \quad \forall v \in V_k,$$
(4.3)

where $1 \le i \le m$, $\Lambda = Ch_k^{-4}$, (see (4.1)). The quantity q_p is obtained by the (k-1)th-level iteration being performed p times (p = 2, 3), that is,

$$q_0 = 0, \quad q_i = MG(k-1, q_{i-1}, \bar{G}), \quad 1 \le i \le p,$$

where

$$\bar{G} = G(I_{k-1}^k v) - a_k(z_m, I_{k-1}^k v) = a_k(z - z_0, I_{k-1}^k v), \quad \forall v \in V_{k-1}$$

The full multigrid method is defined as follows. Let \hat{u}_1 be the solution by a direct method. The approximations \hat{u}_k ($k \ge 2$) are obtained recursively by

$$u_0^i = I_{j-1}^j \hat{u}_{j-1},$$

$$u_l^j = MG(j, u_{l-1}^j, G), \quad 1 \le l \le r, \quad G(v) = \int_G f v \, dx_1 \, dx_2,$$

$$\hat{u}_j = u_r^j,$$

where r is a positive integer to be determined.

5. The convergence analysis

First, we give the following statement:

 (S_k) When the kth-level iteration is applied to the variational problem, we have

$$||z - MG(k, z_0, G)||_k \leq \gamma ||z - z_0||_k,$$

where $\gamma \in (0, 1)$ is a constant independent of k.

THEOREM 5.1. If the number of smoothing steps m is large enough, then we have in the energy norm

$$(S_{k-1}) \rightarrow (S_k).$$

PROOF. Let $e_0 := z - z_0$, $e_i := z - z_i$ $(1 \le i \le m + 1)$. Recall that q satisfies

$$a_{k-1}(q, v) = G(v) = a_k(e_0, I_{k-1}^k v), \quad \forall v \in V_{k-1}$$

Let $\bar{z}_1 := z_0 + I_{k-1}^k q$, $\bar{e}_1 := z - \bar{z}_1$, then $\bar{z}_i (2 \le i \le m+1)$ can be obtained recursively by

$$(\bar{z}_{i} - \bar{z}_{i-1}, v) = \frac{1}{\Lambda_{k}} (G(v) - a_{k}(\bar{z}_{i-1}, v)), \quad \forall v \in V_{k}.$$
(5.1)

Thus we can get

$$\|z - MG(k, z_0, G)\|_k = \|z - z_{m+1}\|_k = \|e_{m+1}\| \le \|e_{m+1} - \bar{z}_{m+1}\| + \|\bar{z}_{m+1}\|_k.$$
(5.2)

From (4.3) and (5.1), we have that

$$(e_i - e_{i-1}, v) = -\frac{1}{\Lambda_k} a_k(e_{i-1}, v)$$
(5.3)

and

$$(\bar{e}_i - \bar{e}_{i-1}, v) = -\frac{1}{\Lambda_k} a_k(\bar{e}_{i-1}, v).$$
 (5.4)

Subtracting (5.4) from (5.3) implies that

$$(e_i - \bar{e}_i - e_{i-1} + \bar{e}_{i-1}, v) = -\frac{1}{\Lambda_k}(e_{i-1} - \bar{e}_{i-1}, v).$$

Let $p_i = e_i - \bar{e}_i$, then

$$(p_i - p_{i-1}, v) = -\frac{1}{\Lambda} a_k(p_{i-1}, v), \quad \forall v \in V_k.$$

Assume that $p_1 = \sum_{i=1}^{n_k} c_i \phi_i$, then $p_{m+1} = \sum_{i=1}^{n_k} c_i (1 - \lambda_i / \Lambda_k)^m \phi$. Thus

$$\|e_{m+1} - \bar{e}_{m+1}\|_k^2 = \|p_{m+1}\|_k^2 = \sum_{i=1}^{n_k} c_i^2 \left(1 - \frac{\lambda_i}{\Lambda}\right)^{2m} \lambda_i.$$

Using $\lambda_i \leq \Lambda_k \leq Ch_k^{-4}$, we finally get $||e_{m+1} - \bar{z}_{m+1}||_k^2 \leq ||p_1||_k^2 = ||e_1 - \bar{z}_1||_k^2$, that is,

$$\|e_{m+1} - \bar{e}_{m+1}\|_{k} \le \|e_{1} - \bar{e}_{1}\|_{k}.$$
(5.5)

Using $||e_1 - \overline{e}_1||_k = ||I_{k-1}^k(q_p - q)||_k$ and Lemma 2.1, we have the inequality

$$\|e_1 - \bar{e}_1\|_k \le C\gamma^p \|q\|_{k-1}.$$
(5.6)

On the other hand, q satisfies the equation

 $a_{k-1}(q, v) = a_k(e_0, I_{k-1}^k v), \quad \forall v \in V_{k-1}.$

Thus we have

$$\|q\|_{k-1} \le \|e_0\|_k. \tag{5.7}$$

Combining (5.5), (5.6) and (5.7) implies

$$\|e_{m+1} - \bar{e}_{m+1}\|_k \le C\gamma^p \|e_0\|_k.$$
(5.8)

Now we analyse the term $\|\bar{e}_{m+1}\|_k$ of (5.2). Let $\bar{e}_1 = \sum_{i=1}^{n_k} c_i \phi_i$, then we get from the above analysis that

$$\bar{e}_{m+1} = \sum_{i=1}^{n_k} c_i \left(1 - \frac{\lambda_i}{\Lambda_k}\right)^m \phi_i.$$

In view of the definition of $||| \cdot |||_{s,k}$, we obtain

$$\|e_{m+1}\|_{k}^{2} = \sum_{i=1}^{n_{k}} c_{i}^{2} \left(1 - \frac{\lambda_{i}}{\Lambda_{k}}\right)^{2m} \lambda \leq C \frac{h_{k}^{-2}}{\sqrt{4m+1}} \|\|\bar{e}_{1}\|\|_{1,k}^{2},$$

that is,

$$\|\bar{e}_{m+1}\|_{k} \leq C \frac{h_{k}^{-1}}{\sqrt[3]{4m+1}} \|\|\bar{e}_{1}\|\|_{1,k}.$$
(5.9)

From [4] we know that

$$\|\|\bar{e}_1\|\|_{1,k} \le C(\|\bar{e}_1'\|_{H^1} + h_k\|\bar{e}_1\|_k).$$
(5.10)

Let $\bar{e}'_1 \in H^1_0(\Omega)$, then $-\Delta \bar{e}'_1 = \phi \in H^{-1}(\Omega)$ and

$$\|\phi\|_{H^{-1}} = \sup_{\varphi \in H_0^1} \frac{|(\phi, \varphi)|}{\|\varphi\|_{H_0^1(\Omega)}}$$

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By means of Green's formula and the Cauchy-Schwarz inequality, we get

$$|(\phi, \varphi)| \leq |\bar{e}_1^l|_{H^1} \|\varphi\|_{H^1}.$$

Thus

$$\|\phi\|_{H^{-1}(\Omega)}\leq |\tilde{e}_1^I|_{H^1(\Omega)}.$$

Now let $\xi \in H_0^2(\Omega) \cap H^3(\Omega)$ be the solution of the biharmonic equation with righthand side $\phi \in H^{-1}$, that is,

$$\begin{cases} \Delta^2 \xi = \phi & \text{in } \Omega, \\ \xi = \partial \xi / \partial n & \text{on } \partial \Omega. \end{cases}$$

From the elliptic regularity, one gets

$$\|\xi\|_{H^3} \leq C \|\phi\|_{H^{-1}} \leq C |\bar{e}_1'|_{H^1}.$$

Assume
$$\xi_k \in V_k$$
 and $\xi_{k-1} \in V_{k-1}$ satisfy

$$a_k(\xi_k, v) = (\phi, v'), \quad \forall v \in V_k$$

and

$$a_{k-1}(\xi_{k-1}, v) = (\phi, v'), \quad \forall v \in V_{k-1}.$$

Then we have

$$\|\xi - \xi_k\|_k \le Ch_k |\xi|_{H^3}, \qquad \|\xi - \xi_{k-1}\|_{k-1} \le Ch_{k-1} |\xi|_{H^3}$$

and

$$|\bar{e}_1'|_{H^1} = \left[(\phi, \bar{e}_1') - a_k(\xi, e_0 - q) \right] + a_k(\xi, e_0 - q) := I_1 + I_2.$$

Let

$$I_1 = (\phi, \tilde{e}_1^l) - a_k(\xi, e_0 - q)$$

= $a_k(\xi_k - \xi, e_0) + a_{k-1}(\xi - \xi_{k-1}, q) - (\phi, (I_{k-1}^k q)^l - q^l),$

then it holds that

$$|I_1| \leq Ch_k |\bar{e}_1'|_{H^1} ||e_0||_k.$$

Let

$$I_2 = a_k(\xi, e_0 - q) = a_k(\xi - \pi_k \xi, e_0) + a_k(\pi_k \xi - I_{k-1}^k(\pi_{k-1} \xi), e_0) - a_{k-1}(\xi - \pi_{k-1} \xi, q),$$

then the approximation property implies $|I_2| \leq Ch_k |\bar{e}_1^l|_{H^1} ||e_0||_k$. Therefore the following inequality holds:

$$|\bar{e}_1'|_{H^1} \le Ch_k ||e_0||_k.$$
(5.11)

However,

$$\|\tilde{e}_1'\|_k = \|z - z_0\|_k = \|e_0 - I_{k-1}^k q\|_k \le \|e_0\|_k + \|I_{k-1}^k q\|_k \le C \|e_0\|_k.$$

In view of (5.10), we finally get

$$\|\|\bar{e}_1\|\|_{1,k} \le Ch_k \|e_0\|_k. \tag{5.12}$$

Combining (5.9) and (5.12), we obtain

$$\|\bar{e}_{m+1}\|_{k} \leq \frac{C}{\sqrt[4]{4m+1}} \|e_{0}\|_{k}.$$
(5.13)

It follows from (5.8) and (5.13) that

$$||z - MG(k, z_0, G)||_k \le \left(C\gamma^p + \frac{C}{\sqrt[4]{4m+1}}\right) ||e_0||_k.$$

Choosing $\gamma \in (0, 1)$ and m such that

$$\left(C\gamma^{p}+\frac{C}{\sqrt[4]{4m+1}}\right)\leq\gamma,$$

we have $||z - MG(k, z_0, G)||_k \le \gamma ||e_0||_k$. The proof is now complete.

THEOREM 5.2. If \hat{u}_k and \hat{u}_k^* are the solutions of the full multigrid algorithm for the problems (2.4) and (2.6), then there exists a constant C such that

 $||u - \hat{u}_k||_k \le Ch_k(|u|_{H^3} + h_k||f||_{L^2})$

and

$$||u - \hat{u}_k^*||_k \leq Ch_k |u|_{H^3}.$$

PROOF. We only prove the first inequality, since the proof of the second inequality is similar to the first. By (2.5) and Theorem 5.1, one obtains

$$\|u - \hat{u}_{k}\|_{k} = \|u - u_{r}^{k}\|_{k}$$

$$\leq \|u - u_{k}\|_{k} + \|u_{k} - u_{r}^{k}\|_{k}$$

$$\leq \|u - u_{k}\|_{k} + C\gamma^{r}\|u_{k} - I_{k-1}^{k}\hat{u}_{k-1}\|_{k}$$

$$\leq C[h_{k}|u|_{2} + h_{k}^{2}\|f\|_{L^{2}}] + C\gamma^{r}\|u_{k} - I_{k-1}^{k}\hat{u}_{k-1}\|_{k}.$$

But

$$\begin{aligned} \|u_{k} - I_{k-1}^{k} \hat{u}_{k-1}\|_{k} &\leq \|u_{k} - u\|_{k} + \|u - \pi_{k}u\|_{k} + \|\pi_{k}u - I_{k-1}^{k}(\pi_{k-1}u)\|_{k} \\ &+ \|I_{k-1}^{k}(\pi_{k-1}u) - I_{k-1}^{k} \hat{u}_{k-1}\|_{k} \\ &\leq C(h_{k}|u|_{3} + h_{k}^{2}\|f\|_{L^{2}}) + \|u - \hat{u}_{k-1}\|_{k-1}. \end{aligned}$$

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Thus

$$\|u - \hat{u}_k\|_k \leq Ch_k(|u|_{H^3} + h_k \|f\|_{L^2}) + \frac{Ch_k \gamma^r}{1 - 2C\gamma^r}(|u|_{H^3} + h_k \|f\|_{L^2}).$$

Choosing γ such that $1 - 2C\gamma^r > 0$, we then have

$$||u - \hat{u}_k||_k \leq C(h_k|u|_{H^3} + h_k^2 ||f||_{L^2}).$$

Theorem 5.2 follows by the above analysis.

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