

Multi-scale steady solution for Rayleigh–Bénard convection

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We found a multi-scale steady solution of the Boussinesq equations for Rayleigh–Bénard convection in a three-dimensional periodic domain between horizontal plates with a constant temperature difference. This was realised using a homotopy from the wall-to-wall optimal transport solution provided by Motoki *et al.* (*J. Fluid Mech.*, vol. 851, 2018, R4). A connected steady solution, which is a consequence of bifurcation from a thermal conduction state at Rayleigh number $Ra \sim 10^3$, is tracked up to $Ra \sim 10^7$ using a Newton–Krylov iteration. The three-dimensional exact coherent thermal convection exhibits a scaling of $Nu \sim Ra^{0.31}$ (where Nu is the Nusselt number) as well as multi-scale thermal plume and vortex structures, which are quite similar to those in turbulent Rayleigh–Bénard convection. The mean temperature profiles and the root-mean-square of the temperature and velocity fluctuations are in good agreement with those of the turbulent states. Furthermore, the energy spectrum follows Kolmogorov’s $-5/3$ scaling law with a consistent prefactor, and the energy transfer to small scales with a nearly constant flux in the wavenumber space is in accordance with the turbulent energy transfer.

Key words: Bénard convection, turbulent convection

1. Introduction

Rayleigh–Bénard convection, a buoyancy-driven flow in a horizontal fluid layer heated from below and cooled from above, is one of the most canonical flows widely observed in nature, and also in engineering applications. The effect of buoyancy on a flow is characterised by the Rayleigh number Ra . When Ra exceeds a certain critical value Ra_c , the thermal conduction state becomes unstable and two-dimensional (2-D) steady convection rolls appear (Drazin & Reid 1981). At a higher Ra , the convection becomes

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time-dependent and subsequently exhibits turbulent states with multi-scale thermal and vortex structures. One of the primary interests in the Rayleigh–Bénard problem is the scaling of turbulent heat transfer with Ra , i.e. the dependence of the Nusselt number Nu on Ra . Over half a century ago, Priestley (1954) and Malkus (1954) simultaneously and independently proposed $Nu \sim Ra^{1/3}$. Priestley derived the scaling from a similarity argument based on dimensional analysis by assuming that the heat flux is independent of the height of the fluid layer, H , while leaving the Prandtl number Pr dependence unspecified. In contrast, Malkus obtained a scaling independent of Pr based on a marginal stability argument. Later Malkus' theory was reframed and developed by Howard (1966). Malkus (1954) also raised a question for the upper limit of the heat transfer in thermal convection, and the upper bounds of $Nu \sim Ra^{1/2}$ were derived via variational approaches (Howard 1963; Busse 1969). In the 1990s, Doering & Constantin (1996) derived a rigorous upper bound of $Nu \leq 0.167Ra^{1/2} - 1$ by employing a new variational approach called 'the background method' (Doering & Constantin 1992), and then the lowest asymptotic upper bound, $Nu - 1 = 0.02634Ra^{1/2}$, was obtained by Plasting & Kerswell (2003). Based on the mixing-length theory, apart from the upper-bound problems, a scaling of $Nu \sim Pr^{1/2}Ra^{1/2}$ was derived by Spiegel (1963). In 1961, his theory was already proposed as testified by Batchelor (1961) (see also Doering 2019). Shortly afterwards, Kraichnan (1962) modified Spiegel's theory, and predicted $Nu \sim Pr^{1/2}Ra^{1/2}(\ln Ra)^{-3/2}$ for a sufficiently large Ra , as a scaling in an asymptotic state with turbulent boundary layers. The logarithmic correction possibly varies from $(\ln Ra)^{-3/2}$ to $(\ln Ra)^{-3}$ (Chavanne *et al.* 1997); $Nu \sim Pr^{1/2}Ra^{1/2}$ is currently called 'ultimate' scaling. In conventional turbulent Rayleigh–Bénard convection, however, the ultimate scaling has not been observed yet. A prominent experiment by Niemela *et al.* (2000) for a very high Ra exhibits $Nu \sim Ra^{0.31}$ even at $Ra \sim 10^{17}$. A recent numerical simulation by Iyer *et al.* (2020) up to $Ra = 10^{15}$, in a slender cylindrical container with an aspect ratio of 1/10, exhibits $Nu \sim Ra^{0.33}$. In the 1990s, Shraiman & Siggia (1990) deduced $Nu \sim Pr^{-1/7}Ra^{2/7}$ by assuming the existence of turbulent boundary layers. In the 2000s, Grossmann & Lohse (2000, 2001, 2002, 2004) proposed a unifying scaling law of global properties for Ra and Pr , based on decomposing the total scalar and energy dissipation into contributions from the bulk region and the boundary layer. Their scaling argument results in two equations for the Nusselt number $Nu(Ra, Pr)$ and the Reynolds number $Re(Ra, Pr)$ with six adjustable parameters, and they are determined to fit experimental and numerical data. Many experiments and numerical simulations have demonstrated the validity of this scaling law (Ahlers, Grossmann & Lohse 2009; Stevens *et al.* 2013). Per the argument, the scaling $Nu \sim Ra^{1/3}$ is derived in the high- Ra regime $10^8 \lesssim Ra \lesssim 10^{14}$ for $Pr \sim 1$. The transition to the ultimate scaling is also predicted for $Ra \gtrsim 10^{14}$; however, the local effective behaviour is represented by $Nu \approx cRa^{0.38}$, where c is a fitting constant, due to logarithmic corrections (Grossmann & Lohse 2011). Although some results have shown the transition to $Nu \sim Ra^{0.38}$, the high- Ra scaling is still being discussed (Chillà & Schumacher 2012; Zhu *et al.* 2018; Doering, Toppaladoddi & Wettlaufer 2019*a,b*). In contrast, for $10^8 \lesssim Ra \lesssim 10^{11}$, a considerable amount of turbulent data exhibit the classical scaling $Nu \sim Ra^{1/3}$ (e.g. Niemela & Sreenivasan 2006; He *et al.* 2012).

Recently, Waleffe, Boonkasame & Smith (2015) found a scaling of $Nu = 0.115Ra^{0.31}$ in 2-D steady Rayleigh–Bénard convection for $10^7 \lesssim Ra \lesssim 10^9$ and $Pr = 7$ (see also Sondak, Smith & Waleffe 2015). In their work, 2-D steady solutions were obtained to maximise Nu by optimising the horizontal periods. The scaling is achieved by a family of 2-D solutions with a horizontal period that decreases with increasing Ra . Interestingly, the scaling is quite similar to the three-dimensional (3-D) turbulent data fit $Nu = 0.105Ra^{0.312}$

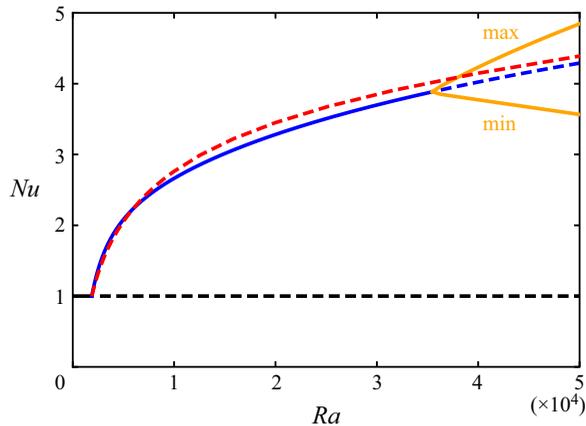


Figure 1. Nusselt number Nu as a function of Rayleigh number Ra . The red and blue curves represent the 3-D steady solution in the square periodic domain and 2-D steady solution with $L/H = \pi/2$ for $Pr = 1$ bifurcating from the conduction state (black) at $Ra \approx 1879$, respectively. The orange curves show the maximum and minimum values of Nu in the 3-D time-periodic solution. The dashed lines denote unstable solutions.

(He *et al.* 2012). Although the result suggests that simple and coherent structures can capture the essence of convective turbulence, it does not imply that this can be realised by any single 2-D steady solution with a fixed horizontal period (fundamental wavelength). More recently, a wall-to-wall optimal transport problem, which is a variational problem for finding a divergence-free velocity field optimising scalar transport between two parallel plates, has been discussed (Hassanzadeh, Chini & Doering 2014; Tobiasco & Doering 2017; Doering & Tobiasco 2019). Motoki, Kawahara & Shimizu (2018*a*) also numerically obtained 3-D time-independent velocity fields to be the optimal states maximising heat transfer between two isothermal no-slip parallel plates under the constraint of fixed total enstrophy. The optimal states exhibit ultimate scaling, which is quite close to the lowest rigorous upper bound obtained by Plasting & Kerswell (2003), and lead to hierarchical self-similar vortex structures. In the optimised 3-D velocity fields, smaller and stronger vortices appear closer to the walls as the total enstrophy increases. In velocity fields numerically optimised within a 2-D field, the emergence of such hierarchical flow structures has not been observed (Souza, Tobiasco & Doering 2020). Although the 3-D optimal state needs an external body force other than buoyancy, we proved that the optimal state found by Motoki *et al.* (2018*a*) could continuously connect to a steady solution of the Boussinesq equations using the homotopy continuation method (see appendix A).

In this paper, we discuss the connected 3-D steady solution. In the Rayleigh–Bénard convection between horizontal boundaries, a 3-D steady solution with convection cells also bifurcates from the conduction state at the same critical value of Ra as the 2-D steady solution (see figure 1). This is because convection rolls in any horizontal direction can exist simultaneously. Although the 3-D solution is not stable, it exists even at a high Ra . We demonstrate the ability of this invariant solution to capture key statistical features, as well as coherent thermal and flow structures in turbulent Rayleigh–Bénard convection. We then discuss the hierarchical multi-scale vortex structures and energy transfer in the 3-D steady solution.

The remainder of the paper is organised as follows. In § 2, we introduce the governing equations, boundary conditions and dimensionless parameters to characterise the thermal convection. We then describe the numerical procedures to obtain nonlinear solutions.

The statistical properties and spatial structures of the 3-D steady solution are presented in § 3, and the hierarchical vortex structures are discussed in § 4. Finally, a summary and conclusions are presented in § 5. In appendix A, we present the homotopy continuation analysis from the 3-D optimal solution of the Euler–Lagrange equations for the wall-to-wall optimal transport problem to the present 3-D steady solution of the Boussinesq equations. The parameter dependence of the 3-D steady solution and the adequacy of the spatial resolution are discussed in appendix B.

2. Boussinesq equations and numerical methods

Let us consider a fluid layer between two horizontal plates heated from below and cooled from above. We employ the Oberbeck–Boussinesq approximation, wherein the density variations are only significant in the buoyancy term. The time evolutions of velocity field $\mathbf{u}(\mathbf{x}, t) = ue_x + ve_y + we_z$ and temperature field $T(\mathbf{x}, t)$ are described by the Boussinesq equations

$$\nabla \cdot \mathbf{u} = 0, \tag{2.1}$$

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{u} + g\alpha T \mathbf{e}_z, \tag{2.2}$$

$$\frac{\partial T}{\partial t} + (\mathbf{u} \cdot \nabla) T = \kappa \nabla^2 T, \tag{2.3}$$

where $p(\mathbf{x}, t)$ is pressure and ρ, ν, g, α and κ are the mass density, kinematic viscosity, acceleration due to gravity, volumetric thermal expansivity and thermal diffusivity, respectively. Vectors \mathbf{e}_x and \mathbf{e}_y are mutually orthogonal unit vectors in the horizontal directions, while \mathbf{e}_z is a unit vector in the vertical direction. The two no-slip and impermeable horizontal plates are positioned at $z = 0$ and $z = H$, and the top (or bottom) wall surface is held at a lower (or higher) constant temperature:

$$\mathbf{u}(z = 0) = \mathbf{u}(z = H) = \mathbf{0}; \quad T(z = 0) = \Delta T > 0, \quad T(z = H) = 0. \tag{2.4a–c}$$

The velocity and temperature fields are supposed to be periodic in the x and y directions with the same period $L_x = L_y = L$. The thermal convection is characterised by the Rayleigh number Ra and the Prandtl number Pr :

$$Ra = \frac{g\alpha \Delta T H^3}{\nu \kappa}, \quad Pr = \frac{\nu}{\kappa}. \tag{2.5a,b}$$

The vertical heat flux is quantified by the Nusselt number:

$$Nu = \frac{-\kappa \langle \partial T / \partial z \rangle_{xyt} + \langle wT \rangle_{xyt}}{\kappa \Delta T / H} = 1 + \frac{H}{\kappa \Delta T} \langle wT \rangle_{xyzt}, \tag{2.6}$$

where $\langle \cdot \rangle_{xyt}$ and $\langle \cdot \rangle_{xyzt}$ represent the horizontal and time average and the volume and time average, respectively. The second equality is given by the volume and time average of (2.3).

Equations (2.1)–(2.3) are discretised employing a spectral Galerkin method based on the Fourier series expansion in the periodic horizontal directions and the Chebyshev polynomial expansion in the vertical direction. The nonlinear terms are evaluated using a spectral collocation method. Aliasing errors are removed with the aid of the 2/3 (or 1/2) rule for the Fourier (or Chebyshev) transform. Time advancement is performed

with the Crank–Nicholson scheme and the second-order Adams–Bashforth scheme for the diffusion terms and the rest, respectively. The nonlinear steady solutions are obtained using the Newton–Krylov iteration (for more details, see § 3 and appendix A in Motoki, Kawahara & Shimizu (2018b)).

In this paper, we present the steady solution and the turbulent states in the horizontally square periodic domain with $L/H = \pi/2 \approx 1.57$ for $Pr = 1$. The domain is the same as that of the optimal states derived by Motoki *et al.* (2018a). The numerical process is conducted on 128^3 grid points for $Ra < 10^7$ and 256^3 grid points for $Ra \geq 10^7$. In the smaller (or larger) domain with $L/H = 1$ (or $L/H = 2\pi/3.117 \approx 2.02$), we have confirmed that the effects of the domain size on the heat flux and the spatial structures are insignificant, which is described in the following sections. The domain size dependence is shown in appendix B with the Prandtl number dependence and the adequacy of the spatial resolution.

All the 3-D steady solutions presented in this paper satisfy the $\pi/2$ -rotation symmetry

$$[u, v, w, T](x, y, z) = [v, -u, w, T](y, -x, z) \quad (2.7)$$

as well as the reflection symmetry

$$[u, v, w, T](x, y, z) = [-u, v, w, T](-x, y, z) = [u, -v, w, T](x, -y, z) \quad (2.8)$$

and the shift-and-reflection symmetry

$$[u, v, w, T](x, y, z) = [u, v, -w, 1 - T](x + L/2, y + L/2, 1 - z). \quad (2.9)$$

These symmetries are not imposed on the solutions explicitly at $Ra \lesssim 10^6$. At $Ra \sim 10^7$, we impose the symmetries (2.7)–(2.9) in order to reduce the computational degrees of freedom.

3. Three-dimensional steady solution

3.1. The Nu – Ra scaling

The 3-D and 2-D steady solutions in the domain with $L/H = \pi/2$ for $Pr = 1$ bifurcate from the conduction state at $Ra \approx 1879$, as shown in figure 1. The 2-D roll solution is stable up to $Ra \approx 3.55 \times 10^4$, and subsequently a time-periodic 3-D solution appears (the stable periodic solution has been obtained by the time evolution). Figure 2 presents Nu in the 3-D and 2-D steady solutions as a function of Ra at a higher Ra . The red line shows the 3-D steady solution, and the open and filled circles represent the present turbulent data in the horizontally square periodic domain and the experimental data in a cylindrical container (Niemela & Sreenivasan 2006), respectively. The blue circles represent the 2-D optimised steady solutions for $Pr = 1$ obtained by Sondak *et al.* (2015). Although the 3-D steady solution at high Ra exhibits smaller Nu than the 2-D optimised solutions, it maintains larger Nu than the turbulent states even at $Ra \sim 10^7$. The inset shows Nu compensated by Ra^γ . The scaling exponent γ of turbulent states shows $2/7$ for $Ra \lesssim 10^7$; at higher Ra , it changes to 0.31. Such a transition has been experimentally and numerically observed for $Pr \sim 1$ (Castaing *et al.* 1989; Silano, Sreenivasan & Verzicco 2010). The exponent of the heat flux in the 3-D steady solution is greater than $2/7$ but less than $1/3$, with 0.31 being the closest, whereas that in the 2-D steady solution with fixed $L/H = \pi/2$ (blue line) is smaller than $2/7$. The bumps in the 3-D steady solution correspond to the remarkable changes in the thermal and flow structures, which will be shown in § 3.3. At $Ra \sim 10^4$ the heat flux of the 3-D steady solution surpasses maxima in

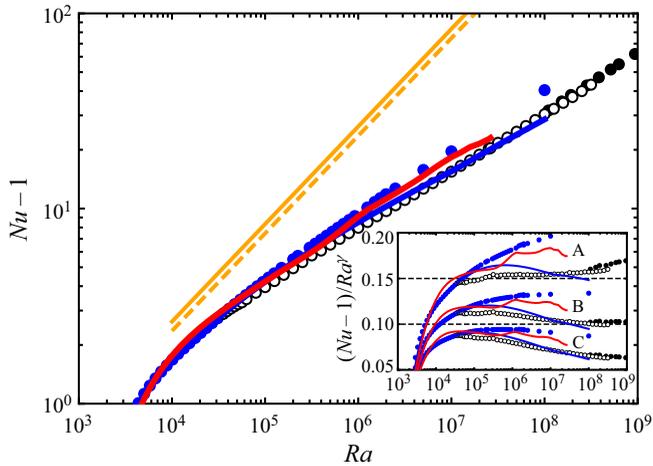


Figure 2. Nusselt number $Nu - 1$ as a function of Rayleigh number Ra . The red and blue solid lines represent the 3-D and 2-D steady solutions, respectively. The open black circles represent the present turbulent data obtained in the horizontally square periodic domain, and the filled ones are the experimental turbulent data in a cylindrical container (Niemela & Sreenivasan 2006). The blue filled circles indicate 2-D optimised steady solutions for $Pr = 1$ obtained by Sondak *et al.* (2015). The orange solid and dashed lines indicate the upper bound $Nu - 1 = 0.02634Ra^{1/2}$ (Plasting & Kerswell 2003) and the optimal scaling $Nu - 1 = 0.0236Ra^{1/2}$, respectively, evaluated from the wall-to-wall optimal transport states (Motoki *et al.* 2018a). The inset shows Nu compensated by Ra^γ : $\gamma = 2/7$ (plot A); $\gamma = 0.31$ (plot B); $\gamma = 1/3$ (plot C).

the 2-D steady solutions. As shown in appendix B, the 3-D steady solution with the smaller horizontal period ($L/H = 1$) shows larger Nu at $Ra \sim 10^5$. The results imply that a family of the 3-D steady solutions with optimised horizontal periods might achieve maximal heat transfer in the steady Rayleigh–Bénard convection. The orange dashed line indicates the optimal scaling $Nu - 1 = 0.0236Ra^{1/2}$ (Motoki *et al.* 2018a) given by the 3-D optimal states maximising the wall-to-wall transport, and it is quite close to the rigorous upper bound, $Nu - 1 = 0.02634Ra^{1/2}$ (Plasting & Kerswell 2003). Although the 3-D optimal states exhibiting significantly high heat flux require an external body force different from buoyancy, the optimal state can be continuously connected to the present 3-D steady solution of the full Boussinesq equations by a homotopy from the body force to the buoyancy, as shown in appendix A.

3.2. Mean temperature and root-mean-square profiles

Figure 3 compares the mean temperature $\langle T \rangle_{xyt}$, root-mean-square (RMS) temperature $T_{rms} = \langle (T - \langle T \rangle_{xyt})^2 \rangle_{xyt}^{1/2}$ and RMS vertical velocity $w_{rms} = \langle w^2 \rangle_{xyt}^{1/2}$ for the 3-D steady solution with those for the turbulent states at $10^5 \leq Ra \leq 10^7$. In figure 3(b,d,f) the distance to the wall, z , is normalised by δ , where δ is the thermal conduction layer thickness given by $\delta/H = 1/(2Nu)$. The mean temperature in the 3-D steady solution well follows that in the turbulent states; furthermore, the corresponding RMS values are also in good agreement with each other. In the bulk region, all mean temperature profiles are flattened, as a result of the nearly complete mixing by large-scale circulation. The temperature difference $\Delta T/2$ exists only at the thermal conduction layer, $0 \leq z \lesssim 2\delta/H = 1/Nu$, and T_{rms} exhibits a peak at $z/\delta \approx 1$. If the advection, diffusion and buoyancy terms in the

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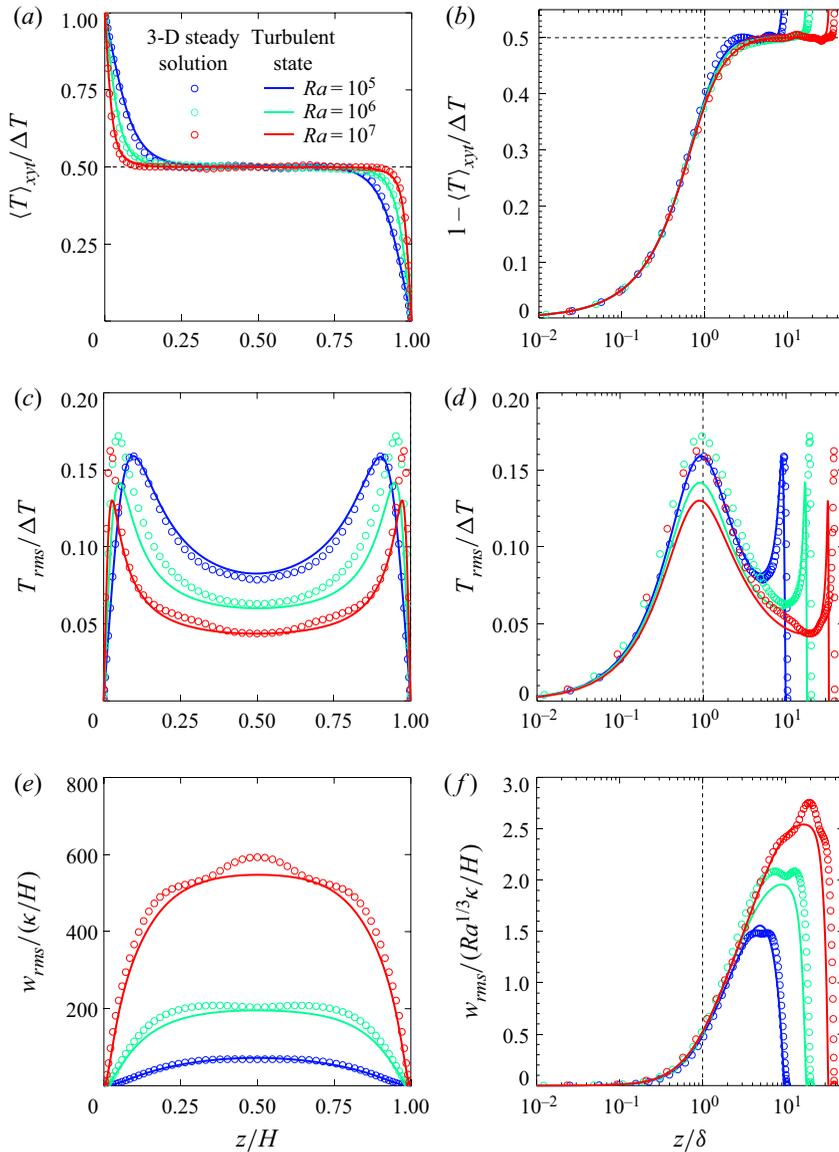


Figure 3. (a,b) Mean temperature, (c,d) RMS temperature and (e,f) RMS vertical velocity as a function of (a,c,e) z/H and (b,d,f) z/δ in the 3-D steady solution and the turbulent state. Here δ is the thermal conduction layer thickness that scales as $\delta/H = 1/(2Nu)$.

Navier–Stokes equation (2.2) at the conduction layer are balanced as

$$\frac{w'^2}{\delta} \sim \nu \frac{w'}{\delta^2} \sim g\alpha \Delta T \tag{3.1}$$

(the balance between the advection and diffusion terms is given by that in the energy equation (2.3) for $\nu \sim \kappa$), the near-wall vertical velocity would then be

$$w' \sim (g\alpha \Delta T \delta)^{1/2} \sim Ra^{1/3} \frac{\kappa}{H}, \tag{3.2}$$

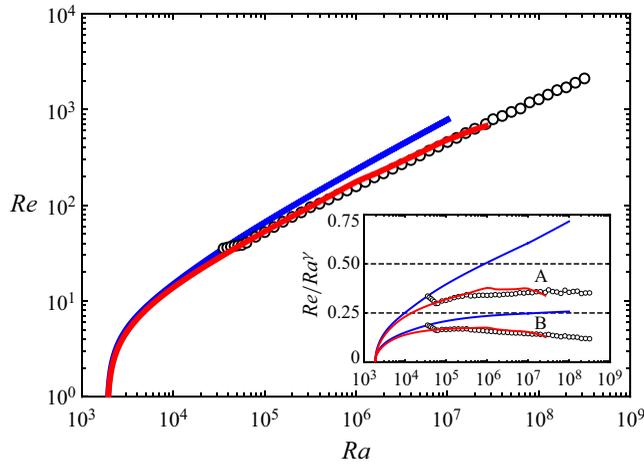


Figure 4. Reynolds number Re as a function of Rayleigh number Ra . The red and blue solid lines represent the 3-D and 2-D steady solutions, respectively. The open circles represent the present turbulent data obtained in the horizontally square periodic domain. The inset shows Nu compensated by Ra^γ : $\gamma = 4/9$ (plot A); $\gamma = 1/2$ (plot B).

yielding the scaling law

$$Nu \sim Ra^{1/3} \tag{3.3}$$

(Kawano *et al.* 2021), which has been given by Malkus’ theory (Malkus 1954) and the argument of Grossmann & Lohse (2000). As shown in figure 3(f), the RMS vertical velocity w_{rms} scales as $Ra^{1/3} \kappa/H$ near the wall $z/\delta \sim 1$.

In the bulk region, where the effects of viscosity or thermal conduction are insignificant, the advection and buoyancy terms are balanced as

$$\frac{U_b^2}{H} \sim g\alpha\Delta T', \tag{3.4}$$

and the dominance of convective heat transfer in bulk and the scaling (3.3) give us

$$\frac{U_b\Delta T'}{\kappa\Delta T/H} \sim Ra^{1/3} \tag{3.5}$$

(Kawano *et al.* 2021). Equations (3.4) and (3.5) yield the bulk velocity scales as

$$U_b \sim Pr^{-2/3} Ra^{4/9} \nu/H. \tag{3.6}$$

The Reynolds number based on U_b scales with $Pr^{-2/3} Ra^{4/9}$, exhibiting consistency with the scaling suggested by Grossmann & Lohse (2000) when both energy and scalar dissipation are bulk-dominated. Figure 4 shows the Reynolds number Re defined as

$$Re = \frac{\langle w^2 \rangle_{xyzt}^{1/2} H}{\nu} \tag{3.7}$$

as a function of Ra . The Reynolds number Re of the 3-D steady solution is comparable with that of the turbulent states exhibiting $Re \sim Ra^{4/9}$ at a high Ra . In contrast, the 2-D steady solution with fixed $L/H = \pi/2$ seems to approach $Re \sim Ra^{1/2}$, implying that $\langle w^2 \rangle_{xyzt}^{1/2}$ scales with the buoyancy-induced terminal velocity $U = (g\alpha\Delta TH)^{1/2}$.

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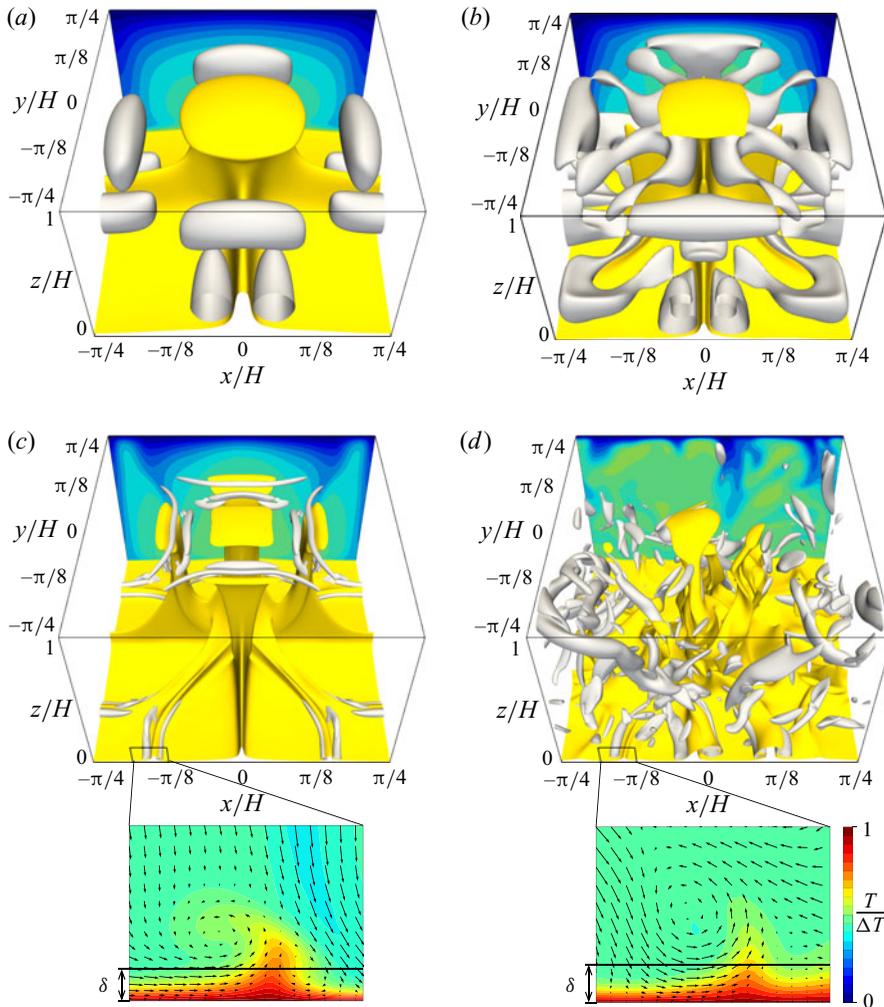


Figure 5. Thermal and flow structures in (a–c) the 3-D steady solution and (d) the turbulent state at (a) $Ra = 10^5$, (b) $Ra = 10^6$ and (c,d) $Ra = 10^7$. The yellow and grey objects represent the isosurfaces of the temperature $T/\Delta T = 0.6$ and the positive second invariant of the velocity gradient tensor, (a) $Q/(\kappa^2/H^4) = 1.28 \times 10^5$, (b) $Q/(\kappa^2/H^4) = 1.28 \times 10^6$ and (c,d) $Q/(\kappa^2/H^4) = 8 \times 10^7$, respectively. The contours represent temperature T in the plane $y/H = \pi/4 (= -\pi/4)$, and the velocity vectors (u, w) in the enlarged views in (c,d) are superposed.

3.3. Thermal and flow structures

Figure 5 visualises the thermal and flow structures in the 3-D steady solution and the turbulent state. The yellow objects represent the isosurfaces of temperature $T/\Delta T = 0.6$, representing high-temperature plumes; the grey objects represent the vortex structures visualised by the positive second invariant of the velocity gradient tensor

$$Q = -\frac{1}{2} \frac{\partial u_i}{\partial x_j} \frac{\partial u_j}{\partial x_i}. \quad (3.8)$$

At $Ra = 10^5$ (figure 5a), the 3-D steady solution consists of large-scale thermal plumes as well as accompanying near-wall small-scale plume and vortex structures near the

vertical planes $x/H = 0$ and $y/H = 0$. As Ra for the 3-D steady solution increases, smaller thermal plume structures (and relevant smaller and stronger tube-like vortex structures) appear near the walls without affecting the already existing large-scale structures. As Ra increases from 10^5 to 10^6 , thermal and vortex structures newly emerge along the diagonals $y = \pm x$ near the walls (figure 5*b*). As Ra increases further from 10^6 to 10^7 , smaller-scale structures appear along $x/H = \pm\pi/8$ and $y/H = \pm\pi/8$ near the walls, and the large secondary plumes approach the opposite wall (figure 5*c*). The bumps of Nu seen in figure 2 correspond to these remarkable changes in the thermal and vortex structures.

At $Ra = 10^7$ (figure 5*c*), we observe sheet-like thermal plumes with the smallest-scale vortices, which are quite similar to those observed in the snapshot of the turbulent state (figure 5*d*). The smallest-scale structures appear in the thermal conduction layer, and the sizes of the plumes and vortices scale with the thickness δ . In 2-D optimised steady solutions (Sondak *et al.* 2015; Waleffe *et al.* 2015), the appearance of small-scale thermal and vortex structures has been observed with the shrinking horizontal period as Ra increases, and the scaling $Nu \sim Ra^{0.31}$ is achieved by a family of solutions with smaller horizontal periods. It should be stressed that the single 3-D steady solution spontaneously reproduces the multi-scale coherent structures of convective turbulence.

4. Hierarchical vortices and energy transfer in wavenumber space

The 3-D steady solution is found to reproduce the near-wall coherent structures in convective turbulence; however, the flow in bulk should be addressed. The developed turbulence organises hierarchical coherent vortex structures of various scales (Goto, Saito & Kawahara 2017; Motoori & Goto 2019). The smallest-scale vortex structures can still be extracted by employing the isosurface of Q , as shown in figure 5; however, it is difficult to identify large- and intermediate-scale structures. To examine the hierarchy of multi-scale vortices in the 3-D steady solution, we consider coarse-graining the velocity field \mathbf{u} . The coarse-grained velocity field \mathbf{u}^* is obtained using the Gaussian low-pass filter (Lozano-Durán, Holzner & Jimenez 2016; Motoori & Goto 2019) as follows:

$$\mathbf{u}^*(\mathbf{x}) = \int_V a\mathbf{u}(\mathbf{x}') \exp\left\{-\left(\frac{\pi\Delta r}{\sigma}\right)^2\right\} d\mathbf{x}', \quad (4.1)$$

where $\Delta r = |\mathbf{x}' - \mathbf{x}|$, σ is the filter width and a is a constant such that the integral of the kernel over the control volume V is unity. In the wall-normal direction, the Gaussian filter is applied by reflecting it at the wall (Lozano-Durán *et al.* 2016). Figure 6 shows hierarchical vortex structures in the 3-D steady solution at $Ra = 2.6 \times 10^7$. Non-filtered structures are shown in figure 6*(a)*, and the isosurfaces of Q of the filtered velocity \mathbf{u}^* with $\sigma = H(= 2L/\pi)$, $L/2$, $L/4$, $L/8$ and $L/16$ are displayed in figure 6*(b–f)*, respectively. The blue objects in figure 6*(b)* are the largest-scale structures corresponding to the large-scale circulation, whereas the red ones in figure 6*(f)* are the smallest-scale structures of size $\sigma/2 = L/32 \approx 2\delta$, which coincides with the size of vortices observed in the non-filtered field (figure 6*(a)*). The light blue, green and light red objects in figure 6*(c,d,e)* illustrate the intermediate-scale vortex structures of eight, four and two times the size of the smallest-scale vortices, respectively. The smaller-scale vortex structures exist closer to the wall, while the intermediate-scale ones are observed in the bulk region in figure 6*(d,e)*.

Figure 6*(g,h)* shows the superposed structures, and from their spatial distribution, it is conjectured that the bulk flow is composed of multi-scale coherent structures. Figure 7*(a)* shows the energy spectrum $E(k, z)$ of the 3-D steady solution at the centre of the fluid

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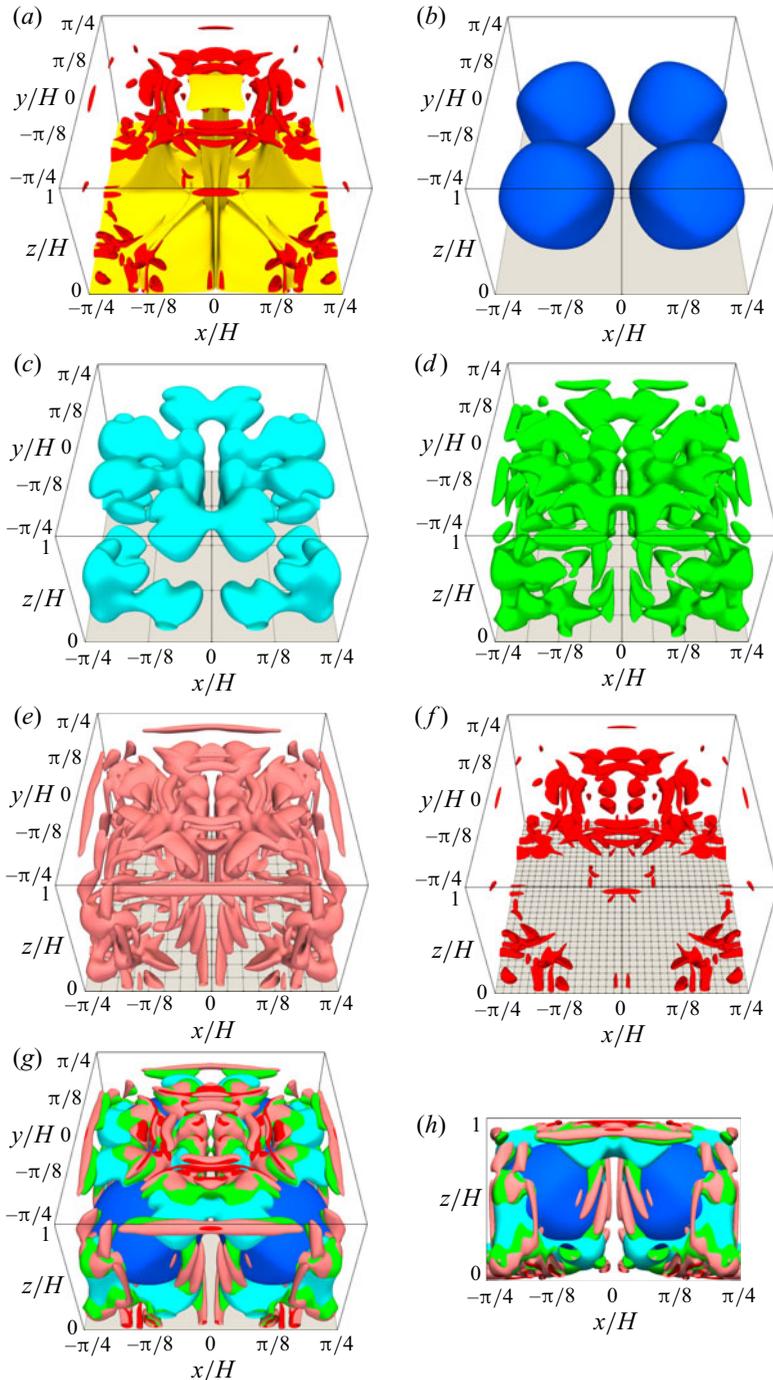


Figure 6. Hierarchical vortex structures visualised by coarse-graining with Gaussian low-pass filter. (a) The yellow and red objects represent the isosurfaces of the non-filtered $T/\Delta T = 0.6$ and $Q/(\kappa^2/H^4) = 2 \times 10^8$, respectively. (b–h) The vortex structures are visualised by the isosurfaces of $Q/(\kappa^2/H^4)$ of the filtered velocity field with filter widths of $\sigma = H (= 2L/\pi)$ (blue), $\sigma = L/4$ (light blue), $\sigma = L/8$ (green), $\sigma = L/16$ (light red) and $\sigma = L/32$ (red); they are superposed in (g,h). The isosurface levels are (blue) 5×10^5 , (light blue) 4×10^6 , (green) 1.2×10^7 , (light red) 3×10^7 and (red) 1.6×10^8 .

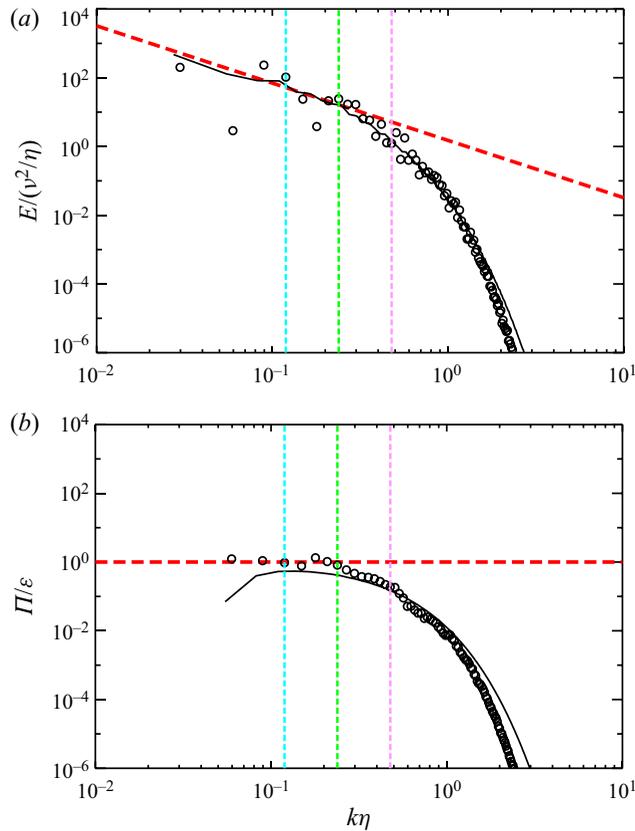


Figure 7. (a) Energy spectrum E and (b) energy flux Π at the centre of the fluid layer, $z = H/2$, in the 3-D steady solution (circles) and the turbulent state (lines) at $Ra = 2.6 \times 10^7$. The lateral and longitudinal axes are normalised by the kinematic viscosity ν and the energy dissipation rate ε at $z = H/2$, which yield the Kolmogorov micro-scale length $\eta = (\nu^3/\varepsilon)^{1/4}$. The red dashed lines represent $E = 1.5\varepsilon^{2/3}k^{-5/3}$ and $\Pi/\varepsilon = 1$, respectively. The light blue, green and light red colours indicate $k = 2\pi/(L/4)$, $2\pi/(L/8)$ and $2\pi/(L/16)$, respectively, normalised with η in the 3-D steady solution, corresponding to the intermediate-scale structures shown in figure 6.

layer, $z = H/2$, and the corresponding turbulence spectrum at $Ra = 2.6 \times 10^7$. The energy spectrum $E(k, z)$ is defined as

$$E(k, z) = \frac{L}{2\pi} \sum_{k-\Delta k/2 < |\mathbf{k}_{2D}| < k+\Delta k/2} \frac{1}{2} \langle |\tilde{\mathbf{u}}(\mathbf{k}_{2D}, z)|^2 \rangle_t, \quad (4.2)$$

where $\tilde{(\cdot)}$ indicates the Fourier coefficients in the periodic (x and y) directions and $\langle \cdot \rangle_t$ represents the time average. Here $\mathbf{k}_{2D} = (k_x, k_y)$ and $k = |\mathbf{k}_{2D}|$ are the wavenumber vector and its magnitude, respectively, and $\Delta k = 2\pi/L$. The lateral and longitudinal axes are normalised by the kinematic viscosity ν and the energy dissipation rate

$$\varepsilon(z) = \frac{\nu}{2} \left\langle \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)^2 \right\rangle_{xyt}, \quad (4.3)$$

which yield the Kolmogorov micro-scale length $\eta = (\nu^3/\varepsilon)^{1/4}$. The spectra of the 3-D steady solution and turbulent state are in good agreement at high wavenumber $k\eta \gtrsim 10^0$.

Furthermore, in the wavenumber band $2\pi/(L/4) \lesssim k\eta \lesssim 2\pi/(L/16)$, corresponding to the intermediate-scale range, the energy spectrum follows Kolmogorov’s $-5/3$ power law, $E = C_K \varepsilon^{2/3} k^{-5/3}$ (Kolmogorov 1941), with the constant $C_K \approx 1.5$, which is consistent with that in the inertial subrange of high-Reynolds-number turbulence (Sreenivasan 1995; Ishihara *et al.* 2016).

In figure 7(b), we show the energy flux in the wavenumber space, $\Pi(k, z)$ (Mizuno 2016), defined as

$$\Pi(k, z) = \sum_{k' \geq k} \sum_{k - \Delta k/2 < |k_{2D}| < k + \Delta k/2} T^s(k_{2D}, z), \quad (4.4)$$

$$T^s(k_{2D}, z) = \text{Re} \left[\left(\partial_j \tilde{u}_i (\tilde{u}_i \tilde{u}_j)^\dagger \right)_t - \frac{1}{2} \frac{\partial (\tilde{u}_j (\tilde{u}_j w)^\dagger)}{\partial z} \right], \quad (4.5)$$

where $(\partial_1, \partial_2, \partial_3) = (ik_x, ik_y, \partial/\partial z)$ and \dagger denotes the complex conjugate. Here $T^s(k_{2D}, z)$ represents the energy transfer between the Fourier modes, and the sum of all spectral components does not contribute to the total energy budget, i.e. $\sum_{k_{2D}} T^s(k_{2D}, z) = 0$. In the intermediate-scale range, the energy flux exhibits positive values, that is, the energy is transferred from large to small scale, and it scales with the same order of energy dissipation rate.

In the optimised 2-D steady solution (Sondak *et al.* 2015; Waleffe *et al.* 2015), as Ra increases the horizontal scale of large-scale convective rolls reduces due to the shrinking of the horizontal period. The bulk flows at high Ra diverge from those in the turbulent states, although it is intriguing that the optimised steady solutions exhibit the turbulent scaling $Nu \sim Ra^{0.31}$. Meanwhile, the 3-D steady solution reproduces not only the near-wall coherent structures but also the turbulence in the bulk of the Rayleigh–Bénard convection.

5. Summary and conclusions

We have discovered a 3-D steady solution to the Boussinesq equations, exhibiting a scaling of $Nu \sim Ra^{0.31}$ and leading to multi-scale coherent structures, which are similar to those observed in turbulent Rayleigh–Bénard convection. The invariant solution bifurcates from the conduction state at $Ra \sim 10^3$, and it has been tracked up to $Ra \sim 10^7$ using the Newton–Krylov iteration. The heat flux of the 3-D steady solution can surpass maxima in the 2-D steady solutions (Sondak *et al.* 2015; Waleffe *et al.* 2015), and thus a family of the 3-D steady solutions with optimised horizontal periods might achieve maximal heat transfer in steady Rayleigh–Bénard convection. In contrast, in the 3-D steady solution with fixed horizontal periods, the horizontal-averaged temperature and the RMS of the temperature and velocity fluctuations are in good agreement with the horizontal and temporal averages obtained for the turbulent states. In the near-wall region of both the 3-D steady solution and the turbulent states, smaller-scale thermal plumes emerge with an increase in Ra . The size of the coherent thermal structures and relevant vortices is comparable with the thermal conduction layer thickness $\delta/H = 1/(2Nu)$, and the RMS vertical velocity at $z/\delta \sim 1$ scales with the velocity scale $Ra^{1/3} \kappa/H$, corresponding to $Nu \sim Ra^{1/3}$. The Reynolds number Re based on the RMS vertical velocity scales as $Re \sim Ra^{4/9}$, which is related to the scaling $Nu \sim Ra^{1/3}$. The bulk flow in the 3-D steady solution comprises hierarchical multi-scale vortices. We have extracted the large- and intermediate-scale vortex structures by employing the coarse-graining method. The ratio of the largest to the smallest length scales in the 3-D steady solution at $Ra = 2.6 \times 10^7$

is approximately 20. The energy spectrum at the centre of the fluid layer shows good agreement with that of the turbulent state. In the intermediate-scale range, the spectrum follows $E = 1.5\epsilon^{2/3}k^{-5/3}$, which is commonly observed in the inertial subrange of the developed turbulence. Furthermore, energy is transferred from large to small scales in the wavenumber space, and the energy flux balances the energy dissipation rate, in accordance with the Kolmogorov–Obukhov energy cascade view.

Recently, van Veen, Vela-Martín & Kawahara (2019) have found a time-periodic solution that reproduces inertial range dynamics in a triply periodic turbulence driven by a constant body force of the Taylor–Green type. They have obtained the invariant solution by applying large-eddy simulation based on the Smagorinsky-type eddy-viscosity model. Meanwhile, by introducing the buoyant force, we have succeeded in finding a multi-scale solution of the full incompressible Navier–Stokes equations without any empirical models. We believe that the current work and approaches based on multi-scale invariant solutions will trigger significant advances in the theoretical understanding and deductive modelling of coherent structures and energy transfer mechanisms in developed turbulence.

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Appendix A. Homotopy from wall-to-wall optimal transport solution

The wall-to-wall optimal transport problem (Hassanzadeh *et al.* 2014; Motoki *et al.* 2018a; Souza *et al.* 2020) involves maximising the heat flux between two parallel plates with a constant temperature difference, under the constraint of fixed total enstrophy, which is written as

$$\left. \begin{aligned} &\text{Maximise } Nu = 1 + \langle w\theta \rangle_{xyz}, \\ &\text{subject to } \nabla \cdot \mathbf{u} = 0, \\ &\quad (\mathbf{u} \cdot \nabla)\theta + w = \kappa \nabla^2 \theta, \\ &\quad Pe = \frac{\langle |\nabla \cdot \mathbf{u}|^2 \rangle_{xyz}^{1/2} H^2}{\kappa} = \text{const.} \\ &\quad \text{and the boundary conditions,} \end{aligned} \right\} \quad (\text{A1})$$

where $\theta = T - (1 - z)$ is the temperature fluctuation about a conduction state. The constraint optimisation is relevant to the maximisation of the objective functional

$$\mathcal{F}' = \left\langle w'\theta' - \phi'(x') \left[(\mathbf{u}' \cdot \nabla')\theta' + w' - \nabla'^2\theta' \right] + \psi'(x') (\nabla' \cdot \mathbf{u}') + \frac{\mu'}{2} \left(Pe^2 - |\nabla' \mathbf{u}'|^2 \right) \right\rangle_{xyz}, \quad (\text{A2})$$

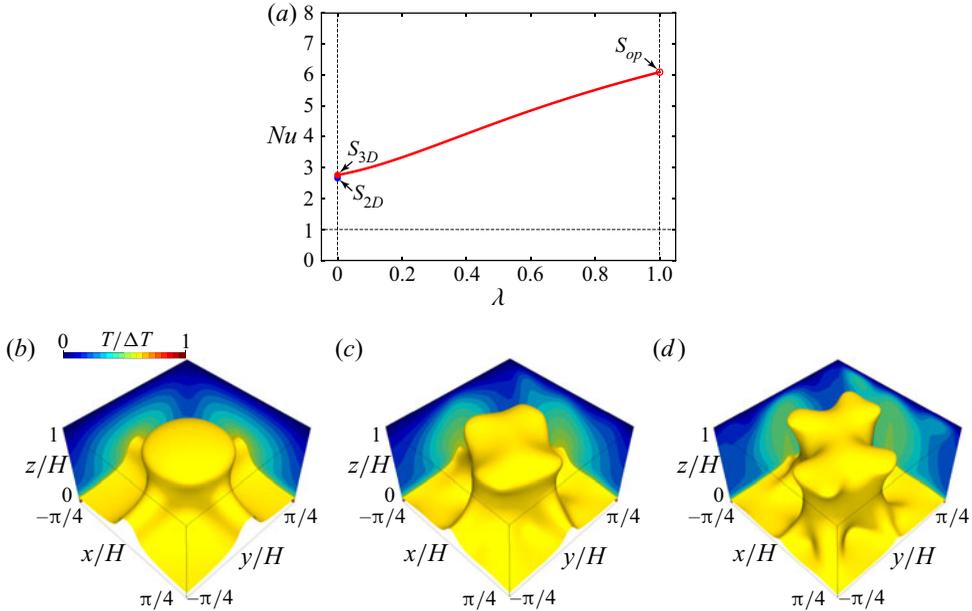


Figure 8. Homotopy from the wall-to-wall optimal transport solution at $Pe = 508$ (from Motoki *et al.* 2018a) to the present 3-D steady solution for a fixed $Ra = 10^4$ and $Pr = 1$. (a) Nusselt number Nu as a function of the homotopy parameter λ . The red open circle shows the optimal solution S_{op} of the Euler–Lagrange equations for the wall-to-wall optimal transport problem, and the red and blue filled circles represent the 3-D steady solution S_{3D} and the 2-D steady solution S_{2D} of the Boussinesq equations, respectively. (b–d) Isosurfaces of temperature $T/\Delta T = 0.6$ at (b) $\lambda = 0$, (c) $\lambda = 0.3$ and (d) $\lambda = 1.0$. The contours represent the temperature T in the planes $x/H = -\pi/4$ and $y/H = \pi/4$. The numerical computation is carried out on 64^3 grid points.

where $\phi'(x')$, $\psi'(x')$ and μ' are Lagrange multipliers and prime $(\cdot)'$ represents a non-dimensional variable based on H , ΔT , κ and ρ . The Euler–Lagrange equations are

$$\frac{\delta \mathcal{F}'}{\delta \mathbf{u}'} \equiv -\nabla' \psi' + \theta' \nabla' \phi' + \mu' \nabla'^2 \mathbf{u}' + (\theta' + \phi') \mathbf{e}_z = \mathbf{0}, \quad (\text{A3})$$

$$\frac{\delta \mathcal{F}'}{\delta \theta'} \equiv (\mathbf{u}' \cdot \nabla') \phi' + w' + \nabla'^2 \phi' = 0, \quad (\text{A4})$$

$$\frac{\delta \mathcal{F}'}{\delta \phi'} \equiv -(\mathbf{u}' \cdot \nabla') \theta' + w' + \nabla'^2 \theta' = 0, \quad (\text{A5})$$

$$\frac{\delta \mathcal{F}'}{\delta \psi'} \equiv \nabla' \cdot \mathbf{u}' = 0, \quad (\text{A6})$$

$$\frac{\partial \mathcal{F}'}{\partial \mu'} \equiv \frac{1}{2} \left(Pe^2 - |\nabla' \mathbf{u}'|^2 \right)_{xyz} = 0. \quad (\text{A7})$$

In our previous work (Motoki *et al.* 2018a), we obtained the optimal state to satisfy (A3)–(A7). Thus, to fulfil the Boussinesq equations, the optimal velocity and temperature field $(\mathbf{u}'_{op}, \theta'_{op})$ require an additional body force,

$$\mathbf{f}'(x') = -(\mathbf{u}'_{op} \cdot \nabla') \mathbf{u}'_{op} - \nabla' p'_{op} + Pr \nabla'^2 \mathbf{u}'_{op} + Pr Ra (1 - z' + \theta'_{op}) \mathbf{e}_z, \quad (\text{A8})$$

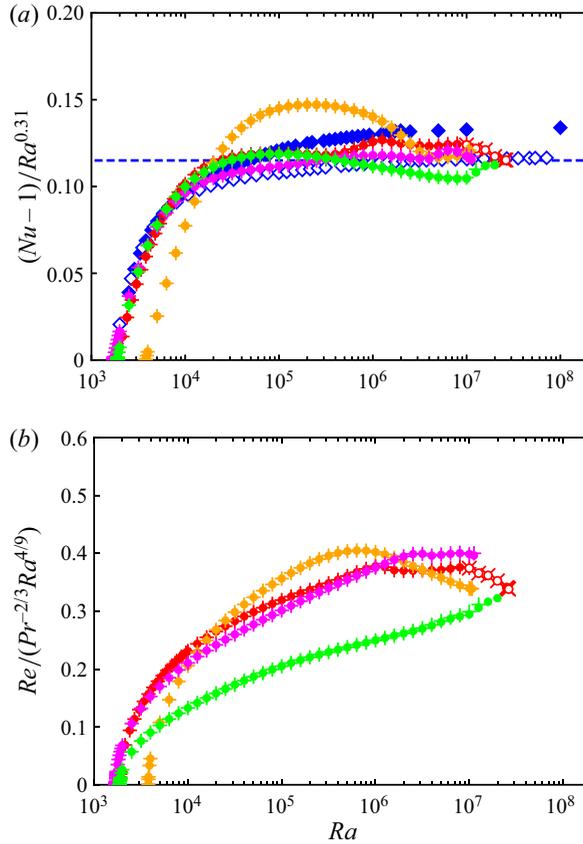


Figure 9. (a) Nusselt number Nu compensated by $Ra^{0.31}$ and (b) Reynolds number Re compensated by $Pr^{-2/3}Ra^{4/9}$ as a function of the Rayleigh number Ra in the 3-D steady solutions for different horizontal period L and Prandtl number Pr . The magenta, red and orange symbols represent $L/H = 2\pi/3, 11\pi/7$ and 1 , respectively, for $Pr = 1$, and the green symbols represent $L/H = \pi/2$ for $Pr = 7$. The blue filled and open diamonds represent the 2-D optimised steady solutions (Sondak *et al.* 2015) for $Pr = 1$ and 7 , respectively. The blue dashed line indicates the least square fit in the 2-D steady solutions for $Pr = 7$, $Nu - 1 = 0.115Ra^{0.31}$, determined in the range $10^7 < Ra \leq 10^9$ (Waleffe *et al.* 2015). The present solutions have been obtained on grid points of $+$, $(N_x, N_y, N_z) = (64, 64, 64)$; \bullet , $(128, 128, 128)$; \times , $(192, 192, 128)$; \circ , $(256, 256, 256)$.

which is different from the buoyant force, where p'_{op} is the pressure determined by the Poisson equation stemming from the Boussinesq equations. We consider homotopy from the Euler–Lagrange system to the steady Boussinesq system:

$$-(\mathbf{u}' \cdot \nabla') \mathbf{u}' - \nabla' p' + Pr \nabla'^2 \mathbf{u}' + PrRa (1 - z' + \theta') \mathbf{e}_z = \lambda \mathbf{f}', \tag{A9}$$

$$-(\mathbf{u}' \cdot \nabla') \theta' + w' + \nabla'^2 \theta' = 0, \tag{A10}$$

$$\nabla' \cdot \mathbf{u}' = 0, \tag{A11}$$

where λ is a homotopy parameter. For fixed $Ra = 10^4$, $Pr = 1$ and \mathbf{f}' , we have tracked the solution from $\lambda = 1$ to 0 using the Newton–Krylov method (figure 8). The connected solution S_{3D} is the present 3-D steady solution shown in §§ 3 and 4.

Multi-scale steady solution for Rayleigh–Bénard convection

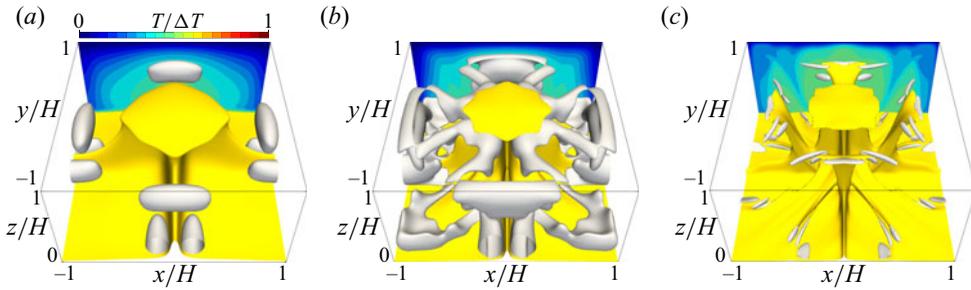


Figure 10. The 3-D steady solution in the domain with $L/H = 2\pi/3.117 \approx 2.02$ for $Pr = 1$ at (a) $Ra = 10^5$, (b) $Ra = 10^6$ and (c) $Ra = 10^7$. The yellow and grey objects represent the isosurfaces of $T/\Delta T = 0.6$ and (a) $Q/(\kappa^2/H^4) = 1.28 \times 10^5$, (b) $Q/(\kappa^2/H^4) = 8 \times 10^5$ and (c) $Q/(\kappa^2/H^4) = 8 \times 10^7$, respectively. The contours indicate T in the plane $y/H = \pi/3.117$.

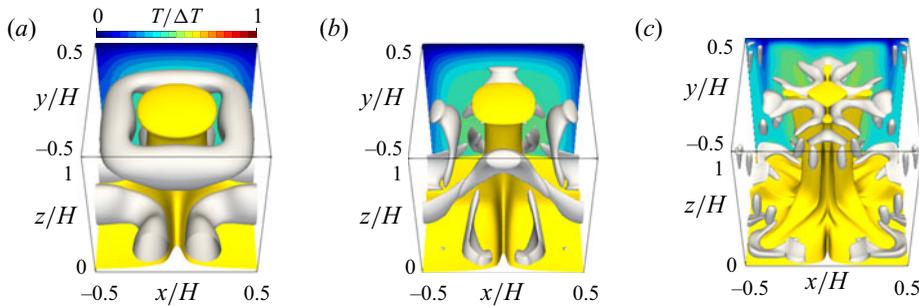


Figure 11. The 3-D steady solution in the domain with $L/H = 1$ for $Pr = 1$ at (a) $Ra = 10^5$, (b) $Ra = 10^6$ and (c) $Ra = 10^7$. The yellow and grey objects represent the isosurfaces of $T/\Delta T = 0.6$ and (a) $Q/(\kappa^2/H^4) = 1.28 \times 10^5$, (b) $Q/(\kappa^2/H^4) = 2.4 \times 10^6$ and (c) $Q/(\kappa^2/H^4) = 5 \times 10^7$, respectively. The contours indicate T in the plane $y/H = 0.5$.

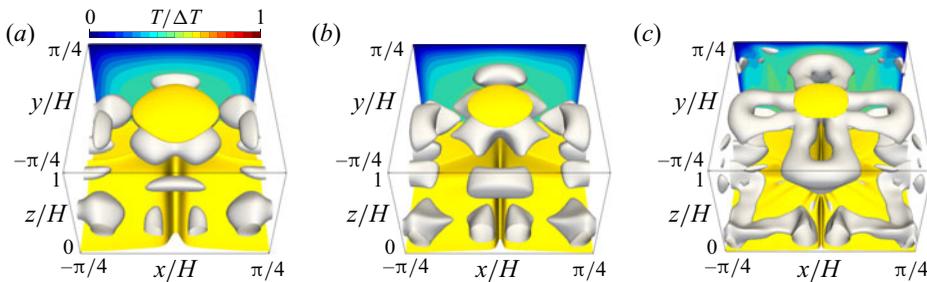


Figure 12. The 3-D steady solution in the domain with $L/H = \pi/2 \approx 1.57$ for $Pr = 7$ at (a) $Ra = 10^5$, (b) $Ra = 10^6$ and (c) $Ra = 10^7$. The yellow and grey objects represent the isosurfaces of $T/\Delta T = 0.6$ and (a) $Q/(\kappa^2/H^4) = 1 \times 10^5$, (b) $Q/(\kappa^2/H^4) = 1 \times 10^6$ and (c) $Q/(\kappa^2/H^4) = 1.28 \times 10^7$, respectively. The contours indicate T in the plane $y/H = \pi/2$.

Appendix B. Dependence of multi-scale steady solution on domain size, Prandtl number and spatial resolution

Figure 9 shows the Nusselt number Nu compensated by $Ra^{0.31}$ and the Reynolds number Re compensated by $Pr^{-2/3}Ra^{4/9}$ as a function of the Rayleigh number Ra in the 3-D steady solutions for different horizontal period L and Prandtl number Pr . The magenta, red and

	Ra	(N_x, N_y, N_z)	$\Delta x/H$ $\times 10^{-2}$	$\Delta z/H$ $\times 10^{-2}$	$\langle \eta \rangle_z/H$ $\times 10^{-2}$	$\eta _c/H$ $\times 10^{-2}$	δ/H $\times 10^{-2}$	$\tau/(U/H)$
3-D steady solution	10^5	(128, 128, 128)	1.22	0.0153–1.24	3.92	4.25	9.57	—
	10^6	(128, 128, 128)	1.22	0.0153–1.24	1.82	2.08	4.95	—
	10^7	(256, 256, 256)	0.611	0.00379–0.616	0.859	1.01	2.59	—
	$10^{7.42}$	(256, 256, 256)	0.611	0.00379–0.616	0.638	0.746	2.08	—
Turbulent states	10^5	(128, 128, 128)	1.22	0.0153–1.24	3.99	4.85	10.1	7906
	10^6	(128, 128, 128)	1.22	0.0153–1.24	1.88	2.05	5.57	2500
	10^7	(256, 256, 256)	0.611	0.00379–0.616	0.897	0.945	3.04	1028
	$10^{7.42}$	(256, 256, 256)	0.611	0.00379–0.616	0.657	0.685	2.34	513

Table 1. Numerical details of the 3-D steady solution and the turbulent states for $L/H = \pi/2$ and $Pr = 1$. Here Δx and Δz are the spatial resolutions in the x and z directions; $\langle \eta \rangle_z$ and $\eta|_c$ represent the Kolmogorov micro-scale length $\eta = (v^3/\varepsilon)^{1/4}$ based on the vertical averaged energy dissipation rate, $\langle \varepsilon \rangle_z = (v/2)\langle (\partial u_i/\partial x_j + \partial u_j/\partial x_i)^2 \rangle_{xyt}$, and that at the centre of the fluid layer, $\varepsilon|_{z=H/2}$, respectively; δ is the thermal conduction layer thickness, $\delta/H = 1/(2Nu)$; τ is the integral time to obtain the statistics; and $U = (g\alpha\Delta TH)^{1/2}$ is the buoyancy-induced terminal velocity.

orange symbols represent $L/H = 2\pi/(k_c H) \approx 2.02$, $\pi/2 \approx 1.57$ and 1, respectively, for $Pr = 1$, where $k_c = 3.117/H$ is the wavenumber corresponding to the minimal critical Rayleigh number $Ra_c = 1708$ (Drazin & Reid 1981). Although there is a variation for small Ra , the three solutions show similar Nu at $Ra \gtrsim 10^6$. The green symbols represent $L/H = \pi/2$ for $Pr = 7$, and the dependence of Nu on Pr is minor. The dependence of Nu on the domain size and Pr (for $1 \lesssim Pr \lesssim 10$) is expected to not be significant at a high Ra , since the emergence of the small-scale plume and vortex structures near the walls, which are robustly observed for different values of L and Pr (figures 5, 10, 11 and 12), might be a key ingredient in the vertical heat flux. In contrast, a variation in Re exists; however, all the solutions are comparable at $Ra \sim 10^7$. The blue filled and open diamonds in figure 9(a) indicate the 2-D optimised steady solutions for $Pr = 1$ and 7, respectively, obtained by Sondak *et al.* (2015). The 3-D steady solutions can exceed the maximal heat flux in the 2-D steady solutions. Meanwhile, at $Ra \gtrsim 10^6$ the present 3-D steady solutions with $1 \leq L/H \lesssim 2$ exhibit smaller Nu than those of the 2-D optimised steady solutions at the same Pr .

In figure 9 the symbols +, •, × and ○ show the results obtained on different grid points $(N_x, N_y, N_z) = (64, 64, 64)$, (128, 128, 128), (192, 192, 128) and (256, 256, 256), respectively, and the effects of the spatial resolutions on Nu and Re are minor. For our main results with $L/H = \pi/2$ and $Pr = 1$, the grid points $(N_x, N_y, N_z) = (128, 128, 128)$ are enough to evaluate the characteristics of the 3-D steady solution at $Ra \lesssim 10^7$; $(N_x, N_y, N_z) = (256, 256, 256)$ are sufficient at $Ra \sim 10^7$. Furthermore, the Kolmogorov micro-scale length η and the thermal conduction layer thickness δ in the 3-D steady solution and the turbulent states at $Ra = 10^5, 10^6, 10^7$ and $10^{7.42} \approx 2.6 \times 10^7$ are summarised in table 1 together with the grid sizes. Since the energy dissipation rate is a function of the wall-normal coordinate z , $\varepsilon(z) = (v/2)\langle (\partial u_i/\partial x_j + \partial u_j/\partial x_i)^2 \rangle_{xyt}$, η also depends on z . Here $\langle \eta \rangle_z$ and $\eta|_c$ are based on the total energy dissipation rate, $\langle \varepsilon \rangle_z$, and that at the centre of the fluid layer, $\varepsilon|_{z=H/2}$, respectively, and $\langle \eta \rangle_z < \eta|_c$ in all cases. The grid size in the x direction, $\Delta x (= \Delta y)$, and the maximal value of z , Δz , are comparable with η and less than one-third of δ . Therefore, the spatial resolution is sufficient to resolve

the smallest-scale thermal and flow structures in the 3-D steady solution and the turbulent states. The present turbulent direct numerical simulation data are obtained by averaging time of more than 200 convective time units based on the buoyancy-induced terminal velocity $U = (\alpha\Delta TH)^{1/2}$.

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