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# Article

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# Calving rate linearly dependent on sub-aerial terminus cliff height at tidewater glaciers around the Antarctic Peninsula

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### Abstract

Calving is the process of ice loss through the breaking of ice from a glacier's terminus. Ice-flow models describe calving in various ways, although no consensus exists on the optimal approach. This is critical as the modelled calving rate can strongly influence projections of mass loss from glaciers and ice sheets. As the sub-aerial cliff height at a glacier's ice front can be considered an indicator of the terminus stress regime, we used a wealth of high-resolution remote-sensing datasets to perform a detailed investigation into the observed relationship between the terminus cliff height and calving rate of 15 tidewater glaciers around the Antarctic Peninsula. The overall long-term response of the assessed glaciers revealed a linearly increasing relationship between calving rate and sub-aerial terminus cliff height from which we derived a calving parameterisation intended for implementation in long-term modelling of tidewater glaciers in the Antarctic Peninsula. Further, other existing calving parameterisations which are based on the terminus ice geometry yielded a poor fit to the assessed observational data. With the availability of such high-resolution data, better validation and constraint of calving parameterisations are now possible, which could greatly improve confidence in the implementation of calving and reliability of outputs from modelling studies.

## 1. Introduction

Iceberg calving, the process of ice separating from a glacier's terminus, is a significant source of mass loss from Antarctica and Greenland (Depoorter and others, 2013; Rignot and others, 2013; Aschwanden and others, 2019; Greene and others, 2022). When calving events occur, upstream ice flow can be affected through structural changes at the ice front and increase rates of discharge to the oceans (Rückamp and others, 2019; Greene and others, 2024). Reliably accounting for mass loss through calving is, therefore, an essential component in the numerical modelling of Antarctic ice sheets and glaciers. However, as there is still no consensus on the best way to do this, the process of calving remains a major source of uncertainty in future sea level rise projections (Bulthuis and others, 2019; Alley and others, 2023; Seroussi and others, 2023).

There exists a need to numerically represent calving in a simple, computationally inexpensive manner that can be employed in large-scale modelling of ice sheets and glaciers over long timescales. Despite the complexity of calving processes, correlations between calving rates and simple glacial properties (for example including geometry and buoyancy conditions) have been observed in nature (Benn and others, 2007). Calving is, therefore, often parameterised in largescale models under the assumption that a primary mechanism may control the rate of iceberg calving, though such parameterisations generally rely upon empirical relationships which are often poorly constrained by observational data in both space and time. However, the recent availability of high-resolution satellite derived datasets detailing glacier geometry (Howat and others, 2022a) and ice-flow velocity (e.g. ENVEO and others, 2021) offers an invaluable opportunity to add better constraint to such relationships and improve confidence in assessing their applicability in varying regions and over different time periods. Further, as the derivation of calving parameterisations are often based upon data from either a single glacier or a limited number of glaciers, some parameterisations require tuning within a numerical modelling framework in order for the observed evolution of calving front positions to be reasonably reproduced when tested over a wider range of real-world geometries (Choi and others, 2018; Amaral and others, 2020; Wilner and others, 2023).

Some of the earliest attempts to parameterise calving considered relationships between calving rate and terminus properties including cliff height, ice thickness and water depth. These were derived through theoretical studies (Reeh, 1968; Fastook and Schmidt, 1982) and through the evaluation of observational data (Brown and others, 1982, 1983; Sikonia, 1982). Although observations appeared to show that a strong correlation with calving rate existed for both ice thickness and terminus water depth (Brown and others, 1982), the derived correlations may have been incidental due to a lack of assessed datasets (Pelto and Warren, 1991) or due to the focus being placed on glaciers holding a steady terminus position rather than being in a retreat phase (Van der Veen, 1996).

Following further investigation, the proportionality of the correlation between calving rate and water depth was shown to vary greatly between glaciers in different regions (Pelto and Warren, 1991; Haresign, 2004). This may not be a surprising result, as the physical explanation behind the correlation between water depth and calving rate is not entirely clear; however, links to ice thickness and terminus cliff height are more coherent.

Calving may be considered to be driven by horizontal deviatoric stress  $\tau_{xx}$ , at the ice front, which can be estimated through assessing the balance of vertically integrated stress in the ice column and the ocean pressure acting at the ice front (Van der Veen, 1996). This force balance approach yields an expression for horizontal deviatoric stress which is dependent on simple geometric parameters only as

$$\tau_{xx} = \frac{1}{4}\rho_i g H \left( 1 - \frac{\rho_w}{\rho_i} \left( \frac{D}{H} \right)^2 \right) \tag{1}$$

where  $\rho_i$  and  $\rho_w$  are the densities of ice and seawater respectively, g is the gravitational constant, H is the ice thickness and D is the submerged depth of the ice. This expression assumes that tangential deviatoric stress at the terminus is negligible. In the circumstance of a floating terminus and assuming uniform densities of ice and ocean water, Eqn (1) can be reduced and the deviatoric stress can be written as proportional to the sub-aerial height of the ice front

$$\tau_{xx} = CH_c \tag{2}$$

where C is a constant and  $H_c$  is the sub-aerial cliff height at the terminus.

Driven by extensional stress, a primary mechanism of calving is the formation and propagation of crevasses (Benn and others, 2007). The basis of calving parameterisations driven by this mechanism is that full thickness penetration of crevasses may occur once a threshold stress has been met. One approach to implementing this is by estimating the location of crevasse formation and depth of propagation using a zero stress criterion (Nye, 1957) which has been investigated in numerous studies (e.g. Benn and others, 2007, 2023; Nick and others, 2010; Pollard and others, 2015; Todd and others, 2018). Alternatively, crevasses which ultimately lead to calving may be initiated at the location of maximum tensile stress in the near-terminus region (Pralong and others, 2003; Pralong and Funk, 2005). Mercenier and others (2018) derived calving rates based on terminus ice thickness considering a predicted time to failure following crevasse formation under this scenario. It follows that the magnitude of maximum tensile stress and consequent time to failure may be reasonably indicated by the horizontal deviatoric stress at the terminus (Eqn (2)).

Links between glacier cliff height and calving rates have also been explored based upon the theorised structural shear failure of ice when a threshold terminus cliff height is reached (Bassis and Walker, 2012; Ultee and Bassis, 2016; Bassis and Ultee, 2019; Clerc and others, 2019; Parizek and others, 2019; Bassis and others, 2021). Piecewise linear (DeConto and Pollard, 2016; DeConto and others, 2021) and power law (Schlemm and Levermann, 2019; Crawford and others, 2021) relationships between cliff height and calving rates have been proposed, requiring the exceedance of a threshold cliff height before calving is assumed to occur.

Antarctica's ice mass holds the equivalent of 57.9 m in global mean sea level rise (Morlighem and others, 2020) and so these relationships are significant as should threshold cliff heights be exposed, the theorised resultant high calving rates could lead to a significant increase in Antarctica's near-future contribution to rising sea levels. Of particular note is the idea that the exposure of tall ice cliffs could lead to unstable terminus retreat, a process termed Marine Ice Cliff Instability (Bassis and Walker, 2012; DeConto and Pollard, 2016). The findings of DeConto and Pollard (2016) suggested that by the end of the century, Antarctica could contribute in excess of 1 m to global sea level rise should such an unstable retreat process be proven. However, the calving parameterisation that was implemented by the authors was not well constrained by observational data either spatially or temporally. Without sufficient constraint of calving rates against real-world observations, the timescales and magnitudes of future ice discharge from Antarctica remain highly uncertain. Despite this, abundant remote-sensing data from recent decades, in particular the highresolution digital elevation models from the Reference Elevation Model of Antarctica (REMA) (Howat and others, 2019, 2022a), provide a great opportunity for this to be re-assessed.

In reality, calving may occur as a result of the combined effects of both tensile and vertical shear stresses (Bassis and Walker, 2012) and the overall height of the ice cliff may influence which mode leads to failure (Schlemm and Levermann, 2019). The underlying theme of these stress-based calving parameterisations, regardless of the physics deemed responsible for calving, is that higher stresses are proportional to higher calving rates.

In this study, we make use of high-resolution observational data from 15 tidewater glaciers around the Antarctic Peninsula to assess the relationship between sub-aerial cliff height and calving rate. Due to the coverage and quality of data, we assess a 9 year time period between 2015 and 2023. We consider that the sub-aerial terminus cliff height may be considered a proxy for the magnitude of either horizontal deviatoric stress (Eqn (2)) or vertical shear stress and that higher stresses may result in higher calving rates. We apply suitable spatial and temporal averaging of both sub-aerial cliff height and calving rate to assess this relationship and arrive at a cliff height dependent calving parameterisation which is representative of the long-term calving behaviour of tidewater glaciers in the Antarctic Peninsula.

#### 2. Study area

The Antarctic Peninsula is a mountainous region extending north from the Antarctic continent towards the southern tip of South America (Fig. 1). In the south of the peninsula, glaciers flow primarily into ice shelves whereas more tidewater glaciers are found further north. Significant glacier retreat has been observed around the Antarctic Peninsula since the 1950s (Cook and others, 2005) and in recent decades, 14% of the Antarctic Ice Sheet's total contribution to global sea level rise came from the region (Otosaka and others, 2023).

We focused on the northern region of the Antarctic Peninsula and considered glaciers where buttressing ice shelves and land-fast sea ice, which can influence calving behaviour (e.g. Mitcham and others, 2022; Ochwat and others, 2024; Parsons and others, 2024), were not present during the time period covered by the datasets that are fundamental to the study (Howat and others, 2019, 2022a). The quality and availability of data (see Table 1) led to the selection of 15 tidewater glaciers for analysis (Fig. 1), the characteristics of which are given in Table 1. As the assessed glaciers cover a range of



**Figure 1.** The study area covers the northern region of the Antarctic Peninsula, shown here on the Reference Elevation Model for Antarctica mosaic hill shade (Howat and others, 2022b) in polar stereographic projection. Latitude and longitude lines are also plotted for reference. The white line shows the estimated grounding line position (Morlighem, 2022). The assessed glaciers are outlined in red with the labelled numbers corresponding to the names and details of each glacier given in Table 1.

properties, this selection is anticipated to be representative of other tidewater glaciers in the region.

#### 3. Datasets

We make use of a wealth of high-resolution data products timestamped between October 2014 and September 2023 (Figure 2) to capture spatial and temporal variation in sub-aerial cliff height and calving rate at multiple tidewater glaciers. The datasets fundamental to this study are digital elevation models, used to determine the glacier terminus positions and cliff heights, and velocity maps which are required in the calculation of calving rates.

Digital elevation models were obtained from timestamped strips from the Reference Elevation Model for Antarctica (Howat and others, 2019, 2022a). These models are extracted from pairs of sub-metre resolution Maxar satellite imagery and are defined at 2 m spatial resolution. In the processing phase, each strip was vertically registered to satellite altimetry measurements from Cryosat-2 and ICESat, resulting in absolute uncertainties of <1 m. The digital elevation models are referenced to the WGS64 ellipsoid and were corrected for the geoid using values from BedMachine v3 (Morlighem and others, 2020; Morlighem, 2022).

Monthly averaged ice velocity maps at 200 m grid spacing were obtained from ENVEO. The maps were derived from successive Sentinel-1 interferometric wide single look complex image pairs (2014–23) using a combination of coherent and incoherent offset tracking techniques (Nagler and others, 2015, 2021; ENVEO and others, 2021).

#### 4. Methodology

The difference between the ice-flow speed and the change in terminus position over time is the rate of frontal ablation, which collectively describes the processes of iceberg calving and subaqueous melt (Truffer and Motyka, 2016). From the observational datasets, we could make no distinction between these two processes, however, we considered that melt rates in the Antarctic Peninsula are expected to be orders of magnitude lower than the total frontal ablation rates (Dryak and Enderlin, 2020) and, therefore, assumed that calving is the dominant process in frontal ablation. The calving rate c can, therefore, be written as

$$c = (\mathbf{v} - \mathbf{u}_c) \cdot \hat{\mathbf{n}} \tag{3}$$

where  $\boldsymbol{v}$  is the material velocity of the ice,  $\boldsymbol{u}_c$  is the velocity of the calving front, i.e. the rate by which the position of the calving front changes over time, and  $\hat{\boldsymbol{n}}$  is a (horizontal) unit normal vector to the calving front.

For the purpose of incorporating calving in continuous ice-flow models for long-term modelling of glaciers, we were interested in the time-averaged pattern of calving rather than in capturing individual calving events. To remove the abrupt advance-retreat oscillation due to individual calving events, we applied a multipleyear window to derive the long-term trend of the ice front calving rate. As such, seasonal variation in calving rates, for example due to the impacts of melange buttressing (e.g. Greene and others, 2018; Kneib-Walter and others, 2021; Gomez-Fell and others, 2022) or enhanced subaqueous melt rates (e.g. Sciascia and others, 2013; Wood and others, 2018), is also neglected. The results of cliff heights and calving rates presented in this study are, therefore, assessed over a 3 year average moving window.

Similarly, it was necessary to incorporate spatial averaging in order to capture the variability in terminus position change, cliff height and flow speed over a glacier's width. We, therefore, drew a rectilinear box over the outlet region of each glacier, sub-dividing this into ten equally spaced segments and aligning with the fjord geometry and direction of ice flow (Fig. 3). The box segments were defined at a length that covered the maximum change in terminus positions over the assessed time period, with the terminus positions digitised from each digital elevation model.

To calculate the change in terminus position over time, we first calculated the area covered by the glacier in each box segment, i.e. the area in the box covered by the upstream segment boundary to the terminus. The width-averaged change in position between sequential digital elevation models was calculated by dividing the change in area of glacier coverage by the width of the box segment. Similar approaches to assessing spatially averaged terminus position changes have been used in numerous studies (e.g. Moon and Joughin, 2008; Howat and Eddy, 2011).

**Table 1.** Details of the studied glaciers, including names, number of high quality digital elevation models (DEMs) available and characteristics of the glacier termini. The reference number corresponds to the numbers labelled in Figure 1 and the dates and time periods covered by the available DEMs are demonstrated in Figure 2

Ref. No.	Name	No. DEMs	Terminus width (m)	Cliff height (m)		Terminus flow speed (m a <sup>-1</sup> )	
				Max <sup>a</sup>	Mean <sup>b</sup>	Max <sup>a</sup>	Mean <sup>b</sup>
1	Drygalski	11	3954	74.9	41.9	2617	1481
2	Pyke & Eliason	12	3242	69.7	31.5	885	544
3	Sjögren	13	2520	70.6	20.3	744	498
4	Boydell	13	1670	49.7	27.6	737	306
5	Landau	6	1007	81.5	31.0	608	371
6	Breguet	10	1354	62.6	32.6	1499	1006
7	Sikorsky	8	495	39.1	29.4	106	79
8	Trooz	14	1982	87.1	51.8	2688	1655
9	Funk	15	1170	50.8	33.0	1348	1115
10	Comrie	7	2030	110.1	62.2	3049	1821
11	Hugi	10	3513	91.9	55.9	2536	2080
12	Erskine	7	2720	98.4	48.2	2090	1557
13	Hopkins	6	1688	53.0	36.6	1073	766
14	Drummond	10	1952	77.8	44.9	1821	1521
15	Widdowson	10	1520	63.6	36.4	2127	1510

<sup>a</sup>Maximum single value across all terminus coordinates at any time.

<sup>b</sup>Mean value across all terminus coordinates and over all time periods.



Figure 2. The dates that digital elevation models were available for each of the studied glaciers are represented by the black crosses. The lines show the overall extent of the assessed time period for each glacier, which was bound by the first and last available digital elevation models.

Coordinates were defined at regularly spaced 10 m intervals along each digitised terminus. Starting from the date of the first digital elevation model, monthly average velocity maps were linearly interpolated onto these coordinates up to the date of the next sequential digital elevation model. The velocity maps were projected to the direction normal to the terminus and the mean velocity at each terminus coordinate between sequential digital elevation models was calculated. In turn, the mean coordinate velocities were averaged over each box segment, resulting in a boxaverage velocity between the dates of sequential digital elevation models. Comparing this to the width-averaged change in terminus position over time, the calving rate in each box segment was determined using Eqn (3).

The cliff height was also assessed at each terminus coordinate. We took the mean surface elevation over a distance 100 m upstream and in the direction normal to the terminus. This process ensured that the extracted heights were not influenced by crevasses or local damage at the ice front and additionally to negate any positional error associated with the digitisation of the terminus location (e.g. Moon and Joughin, 2008; Hill and others, 2017). As per the approach taken to assessing flow velocities, the cliff heights associated with each terminus coordinate were averaged over the width of each box segment to leave a box-average cliff height. Cliff heights and calving rates corresponding to each box segment were compared considering a moving average over a 3 year period and weighted by the durations between each sequential digital elevation model.

The variables used in the averaging processes described above were chosen pragmatically and we anticipated that these may influence the results to some degree. Considering a reference case as described by the variables above, to ensure the employed methodology was robust, we tested the sensitivity of the results to the number of equally spaced box segments (5, 10, 15, 20), resolution of coordinate spacing along the terminus (5 m, 10 m, 20 m, 50 m, 100 m) and time period of the moving window (1 year, 3 years).

#### 5. Results

A correlation between sub-aerial cliff height and calving rate exists, with calving rates seen to increase with greater elevations at the ice front (Fig. 4). A maximum box-average terminus cliff height of 73.1 m was seen at Comrie glacier and corresponded to a box-average calving rate of  $2154 \text{ m a}^{-1}$  over the same 3 year window. The maximum observed calving rate was  $2456 \text{ m a}^{-1}$  which was seen at Drygalski glacier alongside an average cliff height of 51.4 m.

We derived a calving parameterisation based on the terminus sub-aerial cliff height  $H_c$ , considering a linear fit to the collated data (Fig. 4). Using this parameterisation, calving rate *c* is predicted



for all cliff heights as

$$c = 39.08H_c - 456.87\tag{4}$$

for  $H_c > 456.87/39.08 = 11.69$  m and  $H_c = 0$  otherwise, where  $H_c$  is measured in metres and the calving rate, *c*, in metres per annum.

When glaciers are assessed individually, the relationship between calving rate and sub-aerial cliff height generally holds; however, a number of glaciers do not follow this trend line (Fig. 4). Landau glacier displayed relatively low average calving rates throughout the assessed time period with no increase corresponding to cliff height. Calving rates were observed at close to 500 m  $a^{-1}$  over the entire range of observed box-averaged cliff heights at Landau, which ranged from 11.3 m to 61.5 m. Sikorsky also showed little variation in calving rate (< 350 m  $a^{-1}$ ) though the corresponding observed box-averaged cliff heights also covered a small range (21.2–35.5 m). Conversely, Sjögren and Boydell differed from the trendline by displaying a wide variation in calving rates despite cliff heights remaining within a small range (Fig. 4).

As the spatial and temporal averaging processes may impact the observed correlation between cliff height and calving rate, we tested the sensitivity of the results to changing (1) the number of box segments that the glaciers are divided into; (2) the resolution at which the terminus is sampled; and (3) the time period over which the results are averaged.

We found that the correlation between increasing sub-aerial cliff height and calving rate is robust and not sensitive to methods



**Figure 3.** An example of the spatial averaging method, shown at Drygalski Glacier. The base image is a hill shade obtained from the Reference Elevation Model for Antarctica digital elevation model strips (Howat and others, 2022a), dated 27 March 2015. A rectilinear box was drawn over the width of the glacier where velocity data spanned the terminus and was aligned with the direction of ice flow. The box was then split into equally spaced segments (solid black lines). The length of each box segment covered the maximum variation in terminus coordinates digitised from each of the digital elevation models (dashed blue lines). Velocity vectors corresponding to the mean velocities over 2015 are plotted for reference (ENVEO and others, 2021).

applied in processing the datasets (Fig. 5). The number of segments that the glacier width was divided into had little impact upon the results. Small changes to the gradient of the linear best fit line were observed and  $r^2$  and root-mean-square error (RMSE) values ranged between 0.499–0.594 and 386.2–419 m a<sup>-1</sup>, respectively (Fig. 5a). Considering the terminus sample resolution, the sensitivities again showed little impact upon the derived best fit line; however, increased scatter was observed at 50 m and 100 m resolutions. At 50 m and 100 m resolution,  $r^2$  values reduced to 0.351 and 0.242, and RMSE values increased to 530 and 673 m a<sup>-1</sup>, respectively (Fig. 5b). A shallower gradient in the best fit line was derived from the yearly averaged results (Fig. 5c) with higher scatter compared to the reference case ( $r^2 = 0.392$ , RMSE = 523 m a<sup>-1</sup>).

#### 6. Discussion

The comparison between observed sub-aerial cliff height and calving rate (Fig. 4) considers (1) spatial differences at each glacier by separating the width of the termini into different boxes and (2) temporal changes by considering the same regions of the termini at different points in time. This results in an overall time-averaged correlation which accounts for geometric and dynamic variation across a glacier's terminus. Despite this, outliers are seen at Landau, Sjögren, Boydell and Sikorsky, which each display slow flow speeds and thin ice at their fronts (Table 1). In addition, Sikorsky may be considered an exception in terms of terminus width (Table 1) and Landau has relatively few digital elevation models to constrain the



Figure 4. Calving rate is plotted against sub-aerial cliff height for 15 tidewater glaciers around the Antarctic Peninsula. Each data point corresponds to the 3 year moving average values for each single box segment across all glaciers. The solid black line shows the best linear fit (Eqn (4)) with  $r^2 = 0.529$  and root-mean-square error = 419 m a<sup>-1</sup>.

relationship between calving rate and cliff height despite a significant difference seen between the maximum and mean cliff heights over the time period assessed.

In contrast to the terminus properties (Table 1), direct measurements are lacking for other factors which may contribute to these outliers. Local geometric features in the bed topography may cause pinning points, modulating the magnitude of terminus stresses and suppressing calving. However, we are unable to confirm whether such locations exist due to uncertainty in present bedrock datasets for the Antarctic Peninsula (Shahateet and others, 2023). Due to these uncertainties, we also assume that the glacier termini are at or close to flotation, which allows us to simplify Eqn (1) leaving an expression showing deviatoric stress being proportional to the sub-aerial cliff height at the terminus (Eqn (2)). Again, without reliable knowledge of the bed topography, it is unclear whether some glaciers are grounded and how the ratio between ice thickness and submerged depth (D/H) may vary between glaciers. Different values of the ratio D/H will impact the calculated deviatoric stress at the terminus compared to when flotation is assumed and, therefore, the same linear relationship between sub-aerial cliff height and calving rate may no longer hold.

Given these limitations in knowledge of the terminus geometries, it was important to avoid further reliance upon the understanding of other unknowns. We, therefore, avoided distinguishing between the specific mechanisms driving the observed rates of calving, which is in contrast to the assumptions behind existing calving parameterisations which are based upon the terminus geometry (Mercenier and others, 2018; Schlemm and Levermann, 2019). As we constrain the proportionality between cliff height and calving rate based upon observational data alone, we consider that the long-term calving behaviour of a glacier may be a result of either a single mechanism or a combination of several.

We see similarities to the calving parameterisation presented by Mercenier and others (2018), in that calving rates are obtained at low cliff heights and increase approximately linearly (Fig. 6). This parameterisation is the only one which we compare to that is derived based upon a tensile failure process, suggesting that the calving behaviours observed in this study may be primarily driven by the same process. The Mercenier and others (2018) parameterisation overestimates the calving rates which we observed for all cliff heights above 23 m and the derived calving rates diverge with increasing cliff height (Fig. 6). This fundamental difference may be due to the choice of some parameters (such as the fluidity parameter and flow law exponent) in the authors' idealised case study, which considered a laterally unconfined ice slab lying on a flat bed. As our study is based on observational datasets only, there is no reliance upon assumptions of modelling parameters and our results could, therefore, provide further constraint to any modelling work in this region.

DeConto and Pollard (2016); Crawford and others (2021) and Schlemm and Levermann (2019) all considered shear failure to be dominant in the derivation of their calving parameterisation. Each of these share the need for a critical cliff height to be reached before calving is predicted. Assuming the terminus is at flotation, Schlemm and Levermann (2019) required a cliff height of 31 m before the onset of calving. Threshold cliff heights for DeConto and Pollard (2016) and Crawford and others (2021) were 80 m and 136 m, respectively, which both exceed the maximum box-average cliff heights observed in our datasets (Fig. 6). If implemented in an ice-flow model, these parameterisations would all yield calving rates lower than those seen in the observations across large regions of the Antarctic Peninsula leading to unrealistically advancing ice fronts. The accuracy of modelling projections using these parameterisations would, therefore, significantly underestimate mass loss from this region.

Indeed, a notable difference exists between the observed calving rates presented in this study and the rates predicted by all of the existing calving parameterisations (Fig. 6). While Mercenier and others (2018) calibrated their parameterisation against observational data from a number of tidewater glaciers in the Arctic, the geometric and velocity data that the authors assessed were limited to point data along the calving fronts and at a few snapshots in time. Wider spatial and temporal analysis of the terminus properties may have impacted the observed relationship and altered



Figure 5. Sensitivity of results to the parameters considered in spatial and temporal averaging. Each colour corresponds to a single sensitivity case encompassing all 15 glaciers. The reference case is given in black and the solid lines represent lines of best fit. (a) Spatial averaging—sensitivity to the number of boxes that the width of each glacier was divided into. (b) Spatial averaging—sensitivity to the resolution at which the terminus was sampled. (c) Temporal averaging—sub-aerial cliff heights and calving rates were assessed considering a yearly average and a 3 year moving window.

the calibration. Despite this, the expectation was that their calving parameterisation would be valid globally for any tidewater glacier (Mercenier and others, 2018), though this does not hold for the data assessed around the Antarctic Peninsula.

For the other parameterisations presented in Figure 6, no direct comparison of ice geometry, flow velocity or retreat rate is made against observations. Accurately representing calving in ice-flow models is essential in order to allow for reproduction of realistic glacier dynamics and reliable estimates of ice mass loss, in particular as calving has the potential to induce regimes of unstable retreat that could rise global mean sea level by >1 m within the century (DeConto and Pollard, 2016; Lee and others, 2023). With the necessary data for assessing observed calving rates now available in high resolution (Howat and others, 2019, 2022a), the methodology presented in this study can be used to assess the accuracy with which calving parameterisations proposed through theoretical bases may fit observed data, either locally, regionally or on a global scale. The deviation between Eqn (4) and the parameterisations shown in

Figure 6 suggest that these parameterisations may not be indicative of the behaviours seen at tidewater glaciers around the Antarctic Peninsula and validation against data from other regions would be important to demonstrate how suitable they may be more generally.

Theoretical bounds on the stability of ice cliffs have been discussed in numerous studies with the onset of shear failure being controlled by the exceedance of either a prescribed yield strength (Bassis and Walker, 2012; Ultee and Bassis, 2016; Bassis and Ultee, 2019; Bassis and others, 2021) or fracture toughness of ice (Clerc and others, 2019; Parizek and others, 2019). The prescribed material properties ultimately determine the rate at which cliffs fail, however, in practice, high uncertainty exists in real-world material properties due to initiation and transport of damaged ice (Borstad and others, 2012; Mobasher and others, 2016; Lhermitte and others, 2020). For the purposes of large-scale modelling, many difficulties exist in attempting to meaningfully capture the variation in ice rheology and damage both within individual glaciers and between regions. By analysing a wide range of data both spatially



**Figure 6.** Comparison of parameterisations in which calving rates are dependent upon terminus sub-aerial cliff height. Where submerged depths are required in the parameterisation (Mercenier and others, 2018; Schlemm and Levermann, 2019), the terminus is assumed to be at flotation ( $\frac{D}{H} = 0.89$ ). The grey box encompasses the area where sub-aerial cliff heights exceed the maximum box-averaged cliff height found in the data analysed in this study and the black dashed line represents where Eqn (4) has been extrapolated over this region. The dashed orange lines show alternative parameterisations due to varying ice temperature and basal slipperiness as described by Crawford and others (2021).

and temporally, we arrived at an expression for calving rate which does not directly rely upon knowledge of these varying material properties. However, our study is limited by the maximum subaerial cliff heights observed in our analysed datasets. While we observed significant calving rates below the theorised threshold cliff heights required for the onset of shear failure (DeConto and Pollard, 2016; Crawford and others, 2021), we cannot further constrain the upper bound calving rates under this failure process as these exceed the maximum cliff heights found in the assessed observational datasets (73.1 m box-average). Applying the calving parameterisation derived in this study (Eqn (4)) to cliff heights above this value should, therefore, be done with caution.

Within the analysis of observational data, uncertainty exists from several sources. Firstly, the glacier cliff height may be influenced by uncertainty in the digital elevation model, although errors in the vertical plane are expected to be <1 m (Howat and others, 2019). Further, we make the assumption that the assessed calving fronts are fully vertical. An incline at the terminus may affect the stress regime at the calving front (Mercenier and others, 2018); however, it is difficult to assess such slopes from the analysed datasets. As a variety of real-world glaciers have been assessed, it is anticipated that a range of inclines at the calving fronts are inherently accounted for in the data. However, due to the affect that this variation may have on the terminus deviatoric stresses, the terminus slope is a potential source of scatter in the results. Errors also exist within each monthly averaged velocity dataset, as well as the fact that the dates of the digital elevation models from which the terminus locations are extracted do not fully align with the dates of the velocity products. These uncertainties were negated to a certain extent by deriving the calving parameterisation using a 3 year moving average of both cliff height and calving rate, which allowed for a degree of smoothing in the data compared to averaging over a shorter timescale (Fig. 5c). Validation of the calving parameterisation (Eqn (4)) in a numerical ice-sheet model is required in order to determine its suitability in a modelling application, and whether an adjustment to the parameterisation is needed to make up for data uncertainties.

In addition to uncertainties within datasets, it is noted that the relationship between cliff height and calving rate presented here is derived over a relatively short time period (2015–23). These temporal constraints are due to the first availability of the high-resolution digital elevation models used to constrain the height of the terminus ice cliffs. Variability of ice dynamics over longer timescales (Hanna and others, 2024) may, therefore, not be captured by this calving parameterisation and its applicability to past and future climates is uncertain.

Finally, the calving parameterisation derived in this study (Eqn (4)) is based upon a dataset limited to tidewater glaciers around the Antarctic Peninsula. Further work is required in order to determine the applicability of this parameterisation to tidewater glaciers in different regions, as well as to varying geometries of ice shelves around Antarctica.

#### 7. Conclusion

Through analysis of high-resolution data at 15 tidewater glaciers around the Antarctic Peninsula, a linear relationship between terminus sub-aerial cliff height and calving rate was found. The subaerial cliff height is considered a proxy for the near terminus stress regime, with higher stress attributed to increasing calving rates due to multiple driving mechanisms including crevasse propagation and vertical shear.

We showed that existing calving parameterisations which are based upon terminus sub-aerial cliff height offer a poor fit to the observed patterns at these glaciers in the Antarctic Peninsula. With the recent availability of data necessary for high-resolution analysis of both ice geometry and calving rate, better validation and constraint of such calving parameterisations are now possible. An understanding of how well a calving parameterisation fits observational data vastly improves the confidence with which calving can be implemented in modelling applications, in particular if modelling is focussed on a specific region.

The calving parameterisation presented in this study is intended to describe the time-averaged calving response of the tidewater glaciers in the assessed region over long periods, as opposed to capturing individual and specific calving events. Further work is required to validate this parameterisation within a numerical modelling framework and to assess whether such a relationship between calving rate and sub-aerial cliff height exists in other regions.

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