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Formation control of networked mobile robots with guaranteed obstacle and collision avoidance — ERRATUM

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In the original version of this paper the email of the corresponding author, Reza Mahboobi Esfanjani, was given incorrectly. The correct email is mahboobi@sut.ac.ir.

The publisher apologises for this error.

Reference

1. Mohammad Hosseinzadeh Yamchi and Reza Mahboobi Esfanjani. Formation control of networked mobile robots with guaranteed obstacle and collision avoidance. *Robotica*, available on CJO2016. doi:10.1017/S0263574716000102.